



UNIVERSITI
TEKNOLOGI
PETRONAS

FINAL EXAMINATION JANUARY 2025 SEMESTER

COURSE : EEB4033/EFB4023 - DIGITAL SIGNAL PROCESSING
DATE : 15 APRIL 2025 (TUESDAY)
TIME : 2.30 PM - 5.30 PM (3 HOURS)

INSTRUCTIONS TO CANDIDATES

1. Answer **ALL** questions in the Answer Booklet.
2. Begin **EACH** answer on a new page in the Answer Booklet.
3. Indicate clearly answers that are cancelled, if any.
4. Where applicable, show clearly steps taken in arriving at the solutions and indicate **ALL** assumptions, if any.
5. **DO NOT** open this Question Booklet until instructed.

Note :

- i. There are **NINE (9)** pages in this Question Booklet including the cover page and appendices.
- ii. **DOUBLE-SIDED** Question Booklet.

1. a. The MATLAB code in **FIGURE Q1a(i)** illustrates the frequency-shifting property of the Discrete-Time Fourier Transform (DTFT). Additionally, the magnitude spectrum of a discrete-time signal, $x_1[n]$ is presented in **FIGURE Q1a(ii)**. Here, $h = \text{freqz}(b,a,w)$ returns the frequency response vector h evaluated at the normalized frequencies supplied in w . Here, b is the numerator and a is the denominator of the transfer function,

$$H(z) = \frac{B(z)}{A(z)} = \frac{b_1 + b_2 z^{-1} \dots + b_n z^{-(n-1)} + b_{n+1} z^{-n}}{a_1 + a_2 z^{-1} \dots + a_m z^{-(m-1)} + a_{m+1} z^{-m}}$$

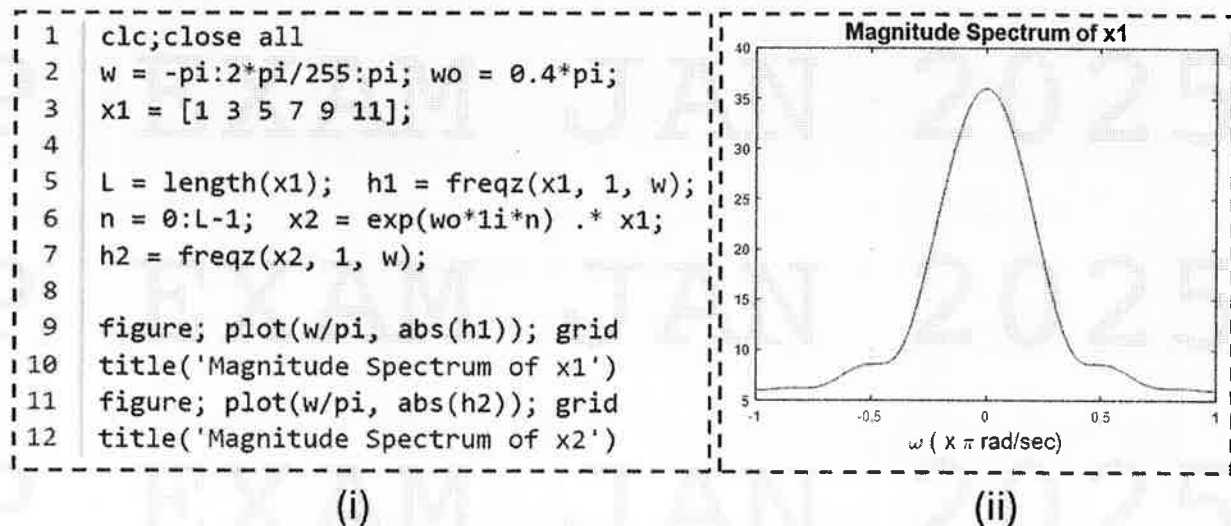


FIGURE Q1a

- i. Determine the DTFT of $x_1[n]$ and $x_2[n]$.

[6 marks]

- ii. Sketch the magnitude spectrum of $x_2[n]$ and explain the frequency-shifting property of the DTFT.

[6 marks]

- b. Consider a causal and stable linear time-invariant (LTI) system that produces an output $y[n]$ in response to an input $x[n]$. If the input and output signals are given as follows,

$$y[n] = n \left(\frac{2}{3} \right)^n u[n] \quad \text{and} \quad x[n] = \left(\frac{4}{5} \right)^n u[n],$$

determine the frequency response and the difference equation governing its operation.

[8 marks]

- c. A low-pass signal with a bandwidth of 1.5 kHz, as illustrated in **FIGURE Q1c**, is sampled at a rate of 2000 samples per second. Sketch the spectrum of the sampled signal in the normalized frequency domain using the Discrete-Time Fourier Transform (DTFT) (i.e., in radians). Additionally, analyze the challenges associated with reconstructing the original signal.

[6 marks]

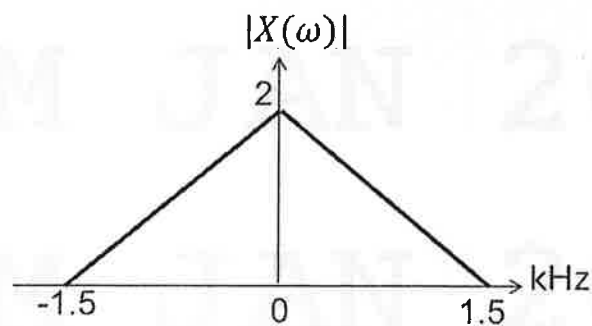


FIGURE Q1c

2. A discrete LTI system with zero initial conditions is described by the following difference equation.

$$y[n] - y[n-1] + \frac{3}{16}y[n-2] = x[n] - \frac{1}{2}x[n-1]$$

- a. Determine the impulse response of the system if the ROC is $\frac{1}{4} < |z| < \frac{3}{4}$ and based on the impulse response, discuss the causality and stability of the system.

[10 marks]

- b. Determine the output response if the input signal is

$$x[n] = \left(\frac{1}{2}\right)^n u[n-4].$$

[6 marks]

3. a. Signal $x[n]$ is given by

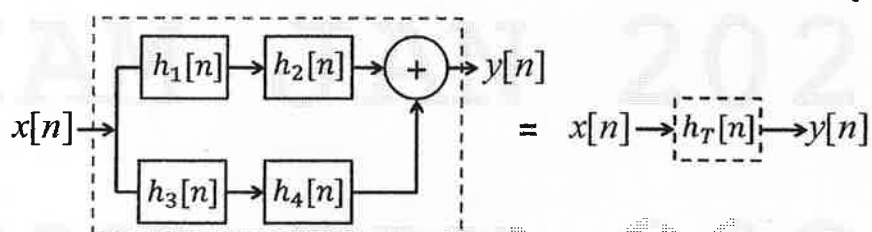
$$x[n] = \{2, 1, 3, \underline{-2}, 1, -1, 0.5, 6\}$$

where the underline indicates the origin of the sequence. Determine $k[n] = x[-2n - 2]$ and $m[n] = k[n](\delta[n + 1] + 2\delta[n - 2])$.

[10 marks]

- b. An interconnection of four LTI systems is shown in **FIGURE Q3**. Find the overall impulse response of the system, $h_T[n]$.

[10 marks]



$$h_1[n] = \left(\frac{1}{5}\right)^n u[n - 5], \quad h_2[n] = 0.3\delta[n - 7],$$

$$h_3[n] = u[n - 4], \quad h_4[n] = 3\delta[n + 1] - \delta[n - 1].$$

FIGURE Q3

4. In a digital audio application, the signal $x[n]$ must be upsampled to ensure compatibility with the varying sampling rates of different audio storage media. The plot in **FIGURE Q4(a)** represents the magnitude spectrum of a discrete-time signal $x[n]$, while **FIGURE Q4(b)** shows the magnitude spectrum of $x[n]$ after undergoing upsampling by a factor of L .

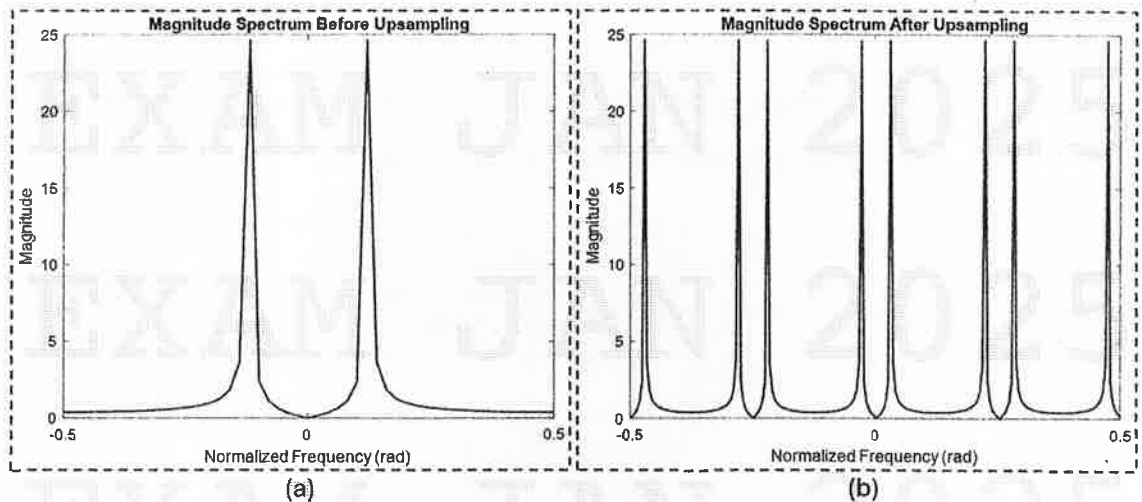


FIGURE Q4

- What is the upsampling factor, L and justify your answer.
[2 marks]
- Based on **FIGURE Q4(b)**, discuss the problem of upsampling a discrete-time signal.
[2 marks]
- Based on **part (b)**, propose a system to mitigate these problems, providing the block diagram of the proposed system. Additionally, specify the parameters of the filter used in the system.
[4 marks]
- If $x[n]$ is to be downsampled by a factor of 3, sketch the magnitude spectrum of the downsampled signal. Clearly label relevant frequency points in your sketch.
[6 marks]

5. A causal digital band-pass biquad filter designed for an audio processing application has the zero-pole plot, magnitude response and direct-form II implementation as shown in **FIGURE Q5 (a), (b) and (c)**, respectively.

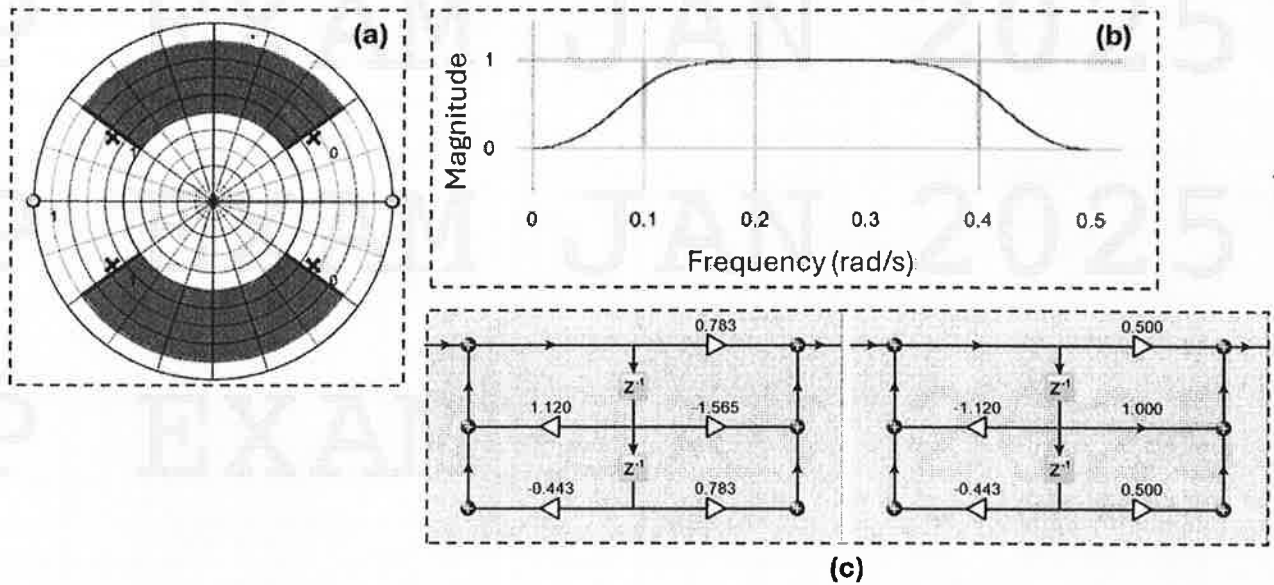


FIGURE Q5

- With the aid of a diagram and based on the zero-pole plot of the filter, determine the filter's magnitude response at $\omega = \pi/10$ rad/s.
[6 marks]
- Based on the position of the poles, discuss the stability of the filter, and explain how to guarantee the stability of the designed filter.
[6 marks]
- Based on the direct-form II implementation, derive the transfer function of the filter.
[6 marks]
- In another audio processing application, you are required to design a band-stop filter without changing the structure of the filter. Provide the zero-pole plot of your proposed design and justify your answer.
[6 marks]

– END OF PAPER –

TABLE AI.1 Common DTFT Pairs

| Sequence | DTFT |
|--|--|
| $\delta[n]$ | 1 |
| $\delta[n - n_0]$ | $e^{-jn_0\omega}$ |
| 1 | $\sum_{k=-\infty}^{\infty} 2\pi\delta(\omega + 2\pi k)$ |
| $a^n u[n]$, $ a < 1$ | $\frac{1}{1 - ae^{-j\omega}}$ |
| $-a^n u[-n - 1]$, $ a > 1$ | $\frac{1}{1 - ae^{-j\omega}}$ |
| $u[n]$ | $\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi\delta(\omega + 2\pi k)$ |
| $(n + 1)a^n u[n]$, $ a < 1$ | $\frac{1}{(1 - ae^{-j\omega})^2}$ |
| $\frac{r^n \sin \omega_p (n + 1)}{\sin \omega_p} u[n]$, $ r < 1$ | $\frac{1}{1 - 2r \cos \omega_p e^{-j\omega} + r^2 e^{-j2\omega}}$ |
| $\frac{\sin \omega_c}{\pi n}$ | $X(e^{j\omega}) = \begin{cases} 1, & \omega < \omega_c \\ 0, & \omega_c < \omega \leq \pi \end{cases}$ |
| $x[n] = \begin{cases} 1, & 0 \leq n \leq M \\ 0, & \text{otherwise} \end{cases}$ | $\frac{\sin[\omega(M + 1)/2]}{\sin(\omega/2)} e^{-j\omega M/2}$ |
| $e^{jn\omega_0}$ | $\sum_{k=-\infty}^{\infty} 2\pi\delta(\omega - \omega_0 + 2\pi k)$ |
| $\cos(\omega_0 n + \varphi)$ | $\sum_{k=-\infty}^{\infty} [\pi e^{j\varphi} \delta(\omega - \omega_0 + 2\pi k) + \pi e^{-j\varphi} \delta(\omega + \omega_0 + 2\pi k)]$ |

TABLE AI.2 Properties of DTFT

| Property | Sequence | DTFT |
|----------------|-----------------------|---|
| Linearity | $ax[n] + by[n]$ | $aX(e^{j\omega}) + bY(e^{j\omega})$ |
| Time-shift | $x[n - n_0]$ | $e^{-jn_0\omega} X(e^{j\omega})$ |
| Time-reversal | $x[-n]$ | $X(e^{-j\omega})$ |
| Modulation | $e^{jn\omega_0} x[n]$ | $X(e^{j(\omega - \omega_0)})$ |
| Convolution | $x[n] * y[n]$ | $X(e^{j\omega}) Y(e^{j\omega})$ |
| Conjugation | $x^*[n]$ | $X^*(e^{-j\omega})$ |
| Derivative | $nx[n]$ | $j \frac{dX(e^{j\omega})}{d\omega}$ |
| Multiplication | $x[n]y[n]$ | $\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta}) Y(e^{j(\omega - \omega_0)}) d\theta$ |

APPENDIX II

TABLE All.1 Common z-Transform Pairs

| Sequence | z-Transform | ROC |
|--|---|-------------|
| $\delta[n]$ | 1 | All z |
| $a^n u[n]$ | $\frac{1}{1 - az^{-1}}$ | $ z > a $ |
| $-a^n u[-n - 1]$ | $\frac{1}{1 - az^{-1}}$ | $ z < a $ |
| $u[n]$ | $\frac{1}{1 - z^{-1}}$ | $ z > 1$ |
| $-u[-n - 1]$ | $\frac{1}{1 - z^{-1}}$ | $ z < 1$ |
| $na^n u[n]$ | $\frac{az^{-1}}{(1 - az^{-1})^2}$ | $ z > a $ |
| $-na^n u[-n - 1]$ | $\frac{az^{-1}}{(1 - az^{-1})^2}$ | $ z < a $ |
| $(\cos \omega_0 n) u[n]$ | $\frac{1 - (\cos \omega_0) z^{-1}}{1 - (2 \cos \omega_0) z^{-1} + z^{-2}}$ | $ z > 1$ |
| $(\sin \omega_0 n) u[n]$ | $\frac{(\sin \omega_0) z^{-1}}{1 - (2 \cos \omega_0) z^{-1} + z^{-2}}$ | $ z > 1$ |
| $(r^n \cos \omega_0 n) u[n]$ | $\frac{1 - (r \cos \omega_0) z^{-1}}{1 - (2r \cos \omega_0) z^{-1} + r^2 z^{-2}}$ | $ z > r$ |
| $(r^n \sin \omega_0 n) u[n]$ | $\frac{(r \sin \omega_0) z^{-1}}{1 - (2r \cos \omega_0) z^{-1} + r^2 z^{-2}}$ | $ z > r$ |
| $x(n) = \begin{cases} a^n, & 0 \leq n \leq N - 1 \\ 0, & \text{otherwise} \end{cases}$ | $\frac{1 - a^N z^{-N}}{1 - z^{-1}}$ | $ z > 0$ |

TABLE All.2 Properties of z-Transform

| Property | Sequence | z-transform | ROC |
|----------------|-----------------|-----------------------|-------------------------|
| Linearity | $ax[n] + by[n]$ | $aX(z) + bY(z)$ | Contains $R_x \cap R_y$ |
| Time-shift | $x[n - n_0]$ | $z^{-n_0} X(z)$ | R_x |
| Time-reversal | $x[-n]$ | $X(z^{-1})$ | $1/R_x$ |
| Exponentiation | $\alpha^n x[n]$ | $X(\alpha^{-1} z)$ | $ \alpha R_x$ |
| Convolution | $x[n] * y[n]$ | $X(z)Y(z)$ | Contains $R_x \cap R_y$ |
| Conjugation | $x^*[n]$ | $X^*(z^*)$ | R_x |
| Derivative | $nx[n]$ | $-z \frac{dX(z)}{dz}$ | R_x |

$$\text{Convolution, } x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k]h[n - k]$$

