FINAL YEAR PROJECT II ORAL PRESENTATION

ional vibration in Difficient Despire

PETRONA

Present by:Michael Arob

PROJECT OBJECTIVES

o mode di ili

at generic equation of drillstring can predice

lo raduce the effective ___meete

considering the parameters e.g. RPM,

29th April ,2008

ailure

0

string,

UNIVERSITI TEKNOLOGI PETRONAS



PROJECT BACKGROUND There are three elements towards understanding and mitigating torsional (Stick-supercond) to understanding dechanisms and causes of <u>Stick-slip</u> (torsional vibration) The methods by which we determine the type of root cause

<u>Actions to be taken to minimize or c</u>

on the basis of those outputs







29th April ,2008

LITERATURE REVIEW

UNIVERSIT

. IADC/SPDDrilling Conference, Dallas, March 3- 6, 1998. this

conference was about the problems which are encountered

by Drillstring particular vibration modes in drillstring

Drilling string develop vibration when run at critical rotary speeds, and these vibration are difficult to control due to the

string long length and large mass. Operating at critical speed

imports severe shock and vibration damage to the. Schlumberger

annual conference of drilling performances, 9th March 2007



METHODOLOGY

Gather data of vibration effect in drill operation

Using angular velocity at drillstring upper part of drillstring to identify Drillstring critical point

> Using MATLAB to model Drillstring generic equation

> > Figure 1.6

Interpret the prediction result UNIVERSITI TEKNOLOGI

PETRONAS

End

METHODOLGY

Using the generic drillstring equation using field. The below block

diagram was build to predict the drillstring responses with

variable input, WOB, RPM and t

 $\mathbf{J}_{\mathbf{a}} \times \mathbf{c} = \mathbf{c} (\mathbf{x}_{\mathbf{a}} + \mathbf{x}_{\mathbf{a}}) + \mathbf{x} (\mathbf{x}_{\mathbf{a}} \times \mathbf{x}_{\mathbf{a}}) = -\mathbf{1}_{\mathbf{a}} \mathbf{c} \mathbf{x}_{\mathbf{a}}$

variable output,ROP and

29th April ,2008_

UNIVERSITI TEKNOLOGI







RPM (rad/s)



DISCUSSION & RESULTS

affected ie in the

Figure 1.10 Characteristic soft formation WOB vs Torque

WOB vs Torque



29th April ,2008

nard tom

9 10



CONCLUSION Amodel decribing the torsional behavior of generic cil drillst has been whether d. This model is a combination of some present model provised in the Lie-ture direction direction direction direction.

due subblem of au

<u>shqwlfhatlinserfilnglRPM</u>

 $\frac{1}{1}$



REFERENCES

[1] T.M Warren, J.H. Oster, L.A. Sinor, and D.C.K. Chen, "Shock Sub

performance

IADC/SPE Dril

October 3-/

29th April ,2008

[3] Schlumberger, Drilling & Measurements

DC/SPE 3932<u>3 presented at the 198</u>

ne, het twestga

UNIVERSITI TEKNOLOGI PETRONAS

10

