# **CERTIFICATION OF APPROVAL**

## MICROCONTROLLER-BASED ELECTRONIC LPG DETECTOR

by

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A project dissertation submitted to the Electrical & Electronics Engineering Programme Universiti Teknologi PETRONAS in partial fulfilment of the requirement for the BACHELOR OF ENGINEERING (Hons) (ELECTRICAL & ELECTRONICS ENGINEERING)

Approved by,

(Dr John Ojur Dennis)

## UNIVERSITI TEKNOLOGI PETRONAS

#### TRONOH, PERAK

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## **CERTIFICATION OF ORIGINALITY**

This is to certify that I am responsible for the work submitted in this project, that the original work is my own except as specified in the references and acknowledgements, and that the original work contained herein have not been undertaken or done by unspecified sources or persons.

NURUL SHAZRAH MOHD SARIFFUDDIN Jun

## ABSTRACT

The report is written to present the work done on the Final year project entitled 'Microcontroller-based Liquefied Petroleum Gas (LP-Gas) Detector'. This project aim is to design a device such that can detect the concentration of gas in a chamber or a small compartment such as a kitchen using the gas resistance drop technique.

This project focuses on designing and implementing a gas detector unit for LPgas detection. The input of the gas detector comes from the output of the MQ-6 gas sensor. If the concentration is high, the output voltage of the sensor rises. The microcontroller which is embedded in the detector circuit acts as the brain for the detector. If the concentration of the gas is at critical or dangerous limit, it produces warning outputs via the warning LED and buzzer. Automatic exhaust fan will also be activated to vent-out the excess gas if the concentration should rise higher.

The microcontroller is programmed to work as such by using the special language called 'assembly language'. This language interprets whatever the data input to it to binary numbers so that it can perform the command programmed by the programmer.

In order to successfully implement this project, researches on the topic selected and feasibility studies were carried out. Problem of the project is identified before the conceptual design. With the concept clarified, the model construction is done followed by experimentation and programming the source code. After a numerous testing and troubleshooting, a prototype gas detector unit is finally designed.

## **ACKNOWLEDGEMENTS**

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# CHAPTER 1 INTRODUCTION

#### 1.1 Background of Study

In most homes, combustion gases are produced by appliances such as gas-fired furnace, boiler, water heater or other fuel-burning devices. Normally, these combustion products — which can include both visible smoke and various invisible gases — should be vented to the outdoors. Unfortunately, they may instead escape into our home, where they could raise a variety of health and other concerns. Since flammable and toxic elements present in combustion gases are hardly detectable with human senses, this project shall implement a domestic gas detector which shall detect Liquefied Petroleum Gases (LP Gases) such as propane and butane and warn the owner when a certain gas concentration is exceeded. Existing gas detectors are mostly DC powered and this may consumed a lot of batteries, and thus increasing the operating costs.

## **1.2 Problem Statement**

#### 1.2.1 Problem Identification

This project focuses on designing and implementing a microcontroller-based electronic gas detector which detects concentration of LP Gas and warns the user via audible alarm if the Lower Explosive Limit (LEL) is reached. The gas detector will also automatically actuate a fan to vent-out the gases to reduce the concentration to normal state. The operating environment will include residential domains or normal household conditions. It shall be used for domestic purposes only, may not be exposed to adverse environment for a long term, and should not have excessive vibrations or contact with water. It will be powered by AC supply or otherwise known as mains supply. The type of microcontroller (the brain of the detector) that will be used is PIC 16F877 because of its simplicity. The program to control the detector is written in assembly language.

#### 1.2.2 Significant of the Project

The Liquefied Petroleum Gas (LP Gas) is an energy source that is commonly used in homes for cooking and heating. It is primarily composed of propane and butane. Although it only happens rarely, a LP gas leak can sometimes occur inside the home. A LP gas leak can be dangerous because it increases the risk of fire or explosion. Since propane and butane naturally does not have any odor, the gas company adds a warning "rotten-egg" smell (the stanching smell which is from mercaptan or a similar sulfurbased compound) that can be easily detected by most people. However, people who have a diminished sense of smell may not be able to rely upon this safety mechanism. A gas detector can be an important tool to help protect our homes. The microcontroller installed is for automatic response so that in case when the LEL of LP Gas is reached, it will give out immediate alarm and start actuating the fan which will vent out the gas until the atmosphere returns to normal concentration. By constructing the prototype, in the end we would have a low-cost mains-supplied detector which can be used in homes.

Exposure to low levels of LP gas is not harmful to health. However, if a gas leak is severe, the amount of oxygen available for breathing could be dramatically reduced, which can lead to asphyxia. Symptoms of asphyxia include

- dizziness
- fatigue
- nausea
- headache
- irregular breathing

Exposure to extremely high levels of LP gas can cause loss of consciousness or even death. The other hazard is the flammability of the gas when it reaches a certain concentration level in air known as the Lower Explosive Limit (LEL).

## 1.3 Objectives and Scope of Study

## 1.3.1 Objectives

The objectives of this project are:

- To design and simulate a microcontroller gas detector using appropriate tools and methodology.
- To construct a prototype of the microcontroller-based gas detector.
- To come up with a design which is cost effective, simple to use and easy to set up.

#### 1.3.2 Scope of Study

The scope of this project takes into consideration the study of LP Gas characteristics, its permissible limits, the sensor and the microcontroller function, programming the assembly language for the PIC16F877 microcontroller, the design and the simulation of the circuits according to requirements set by supervisor.

On the hardware side, the simulated design is wired nicely on a veraboard and presented in the form of a complete gas detector unit, in other words, producing a gas detector unit which has low-cost, long life and good sensitivity to the target gas detected. At the end of this project, a prototype gas detector will be developed that can be used in homes or perhaps small labs which involve the use of LP Gas. This project has exposed the author to microcontroller programming and digital electronics design and resulted in a hands-on experience in order to complete the task in a given time frame.

# CHAPTER 2 LITERATURE REVIEW AND THEORY

#### 2.1 Liquefied Petroleum Gas (LP Gas)

The consequences of a LP gas leak at home can be disastrous. Although the gas is not regarded as poisonous, it is explosive and can lead to devastating explosions if it builds up to sufficient levels [1]. The concentration is measured using what's called the Lower Explosive Limit (LEL).

LP Gas is a mixture of light hydrocarbons that are gaseous at normal temperatures and pressures but readily liquefy at moderate pressures or reduced temperatures. The two most common LP gases are propane and butane [2].

LP Gas is usually stored as a liquid under pressure. When released into the atmosphere at any temperature above its boiling point (-42°C for Propane and 0°C for Butane) it will change from a liquid to vapor. Liquid LPG on bare skin causes frostbite. LP Gas is heavier than air. In both its liquid and vapor sates, it is colorless and odorless. A stenching agent is added to enable any leaks to be detected by smell [3].

#### 2.2 Lower Explosive Limit

The Lower Explosive Limit (LEL) is the lowest amount of gas that will cause an explosion. The alarm threshold is equal to a concentration of 0.35% (3,500 ppm) of Propane-LPG, which corresponds to about 16% of LEL. The regulations require that the alarm threshold is below 25% of LEL [4]. From the Henan Henwai website on the MQ-6 sensor [5], the LEL for LP gas is at 3%. The whole table can be viewed as in APPENDIX 1.

## 2.3 MQ-6 Liquefied Petroleum Gas (LP Gas) Sensor

The gas detector shall be implemented using a semiconductor sensor, the MQ-6 which, are suitable for detecting of LP Gas. It has high sensitivity to LP Gas, iso-butane, propane ,fast response, small sensitivity to smoke, simple drive circuit, stable and has long life [5].

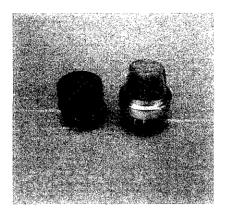


Figure 2.1: MQ-6 Sensor

## 2.3.1 Basic Sensor Circuit

Basically Figure 2.2 shows how the basic sensor circuit looks like. The comparator is added to measure and compare the load voltage ( $V_{RL}$  and the reference voltage ( $V_{REF}$ ).

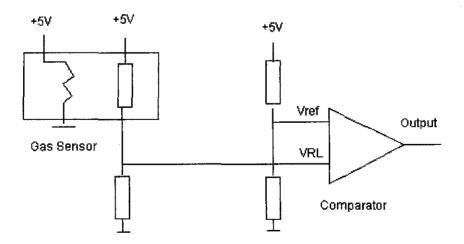


Figure 2.2: Basic Sensor Circuit

#### 2.3.2 Sensitivity of MQ-6 sensor

The feature of the MQ-6 sensor is that it has high sensitivity to LPG, iso-butane and propane and small sensitivity to alcohol and smoke. Figure 2.3 shows the typical sensitivity characteristics of the MQ-6 for several gases at temperature of 20 degrees, oxygen concentration at 21% and RL equals to 20 k $\Omega$ . Ro in the figure refers to the sensor resistance at 1000 ppm of LPG in clean air and Rs refers to the sensor resistance at various concentration of gases

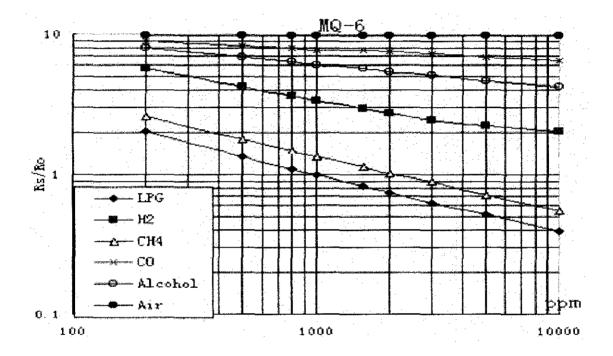


Figure 2.3: Sensitivity Curve for MQ-6 Sensor

The relationship between sensor resistance and the concentration of deoxidizing gas can be expressed by the following equation over a certain range of gas concentration:

$$R = nC - m(\log(Rs) = -m\log C + n)$$

..... Equation 2.1

where R is the electrical resistance of the sensor, C is the gas concentration and m and n are constants. m represents the sensitivity according to the change of gas concentration, n is relevant to sensitivity to the detected gas, concomitancing the difference with different sensors, gas variety, and detecting terms.

According to the Equation 2.1, the relationship of sensor resistance to gas concentration is linear on a logarithmic scale within a practical range of gas concentration (from several ppm to several thousand ppm). Figure 2.3 shows a typical example of the relationship between sensor resistance and gas concentration. The sensor will show sensitivity to a variety of deoxidizing gases, with relative sensitivity to certain gases optimized by the formulation of sensing materials and operating temperature. Since actual sensor resistance values vary from sensor to sensor, typical sensitivity characteristics are expressed as a ratio of sensor resistance in various concentrations of gases (Rs) over resistance in a certain concentration of a target gas (Ro). Since sensor resistance varies as a logarithmic function of gas concentration, therefore sensitivity characteristics to a certain gas differs with sensor type.

When measuring a certain gas, possible interference of co-existing gases must always be taken into consideration. For example, when measuring an atmosphere containing both Propanol and Ethanol, the Propanol measurement can be affected by the Ethanol.

Resistance value of the same sensor is different to various kinds and various concentration gases. Resistance value of various sensors has difference to the same gas concentration too. Thus, when using this component, sensitivity adjustment and calibration is very necessary to every sensor. In addition, when accurately measuring, the proper alarm point for the gas detector should be determined after considering the temperature and humidity influence.

## 2.3.3 Temperature and Humidity Dependency

The sensing principle of semi-conductor sensor is based on chemical adsorption and desorption of gases on the sensor's surface, meaning that the ambient temperature and humidity will affect sensitivity characteristics easily. According to the above, a compensation circuit for temperature dependency must be considered when using the MQ-6 sensor in the gas detector for better reliability and accuracy. Figure 2.4 shows a typical example of these dependencies. Ro in the figure refers to the sensor resistance at 1000ppm of LPG in air at 33%RH and 20 degree. Rs on the other hand refers to the sensor resistance at 1000ppm of LPG in air at different temperatures and humidities.

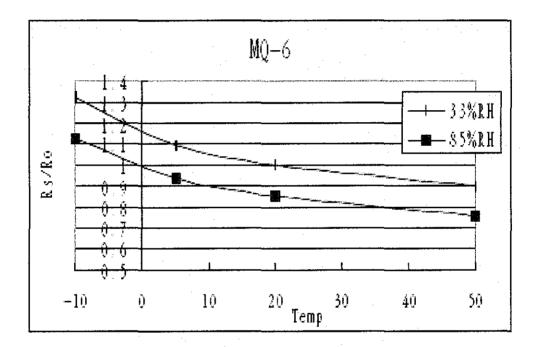


Figure 2.4: Temperature and Humidity Dependency for MQ-6 sensor

Figure 2.5 shows the compensation circuit with thermistors (Rt) for temperature. The circuit in this figure is used as reference for simulation in the Electronics Workbench (EWB) to obtain the voltage and current for the circuit in order to analyze the response of the circuit to different resistance of the sensor circuit.

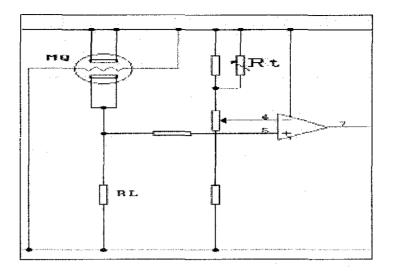


Figure 2.5: Compensation Circuit

## 2.3.4 Sensor Response

Figure 2.6 demonstrates typical behavior when the sensor is exposed to and then removed from a deoxidizing gas. Sensor resistance will drop very quickly when exposed to gas, and when removed from gas its resistance will recover to its original value after a short time. The speed of response and reversibility will vary according to the MQ-6 sensor and the LP-Gas that it sense.

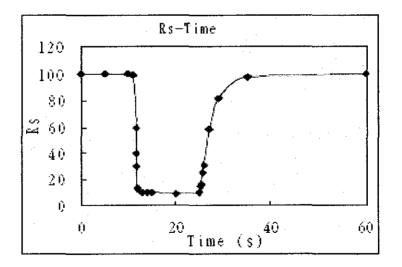


Figure 2.6: The sensor resistance response to gas concentration versus time

One way to analyze the sensor behavior is by using PASCO 750 together with Data Studio. By using the PASCO, the data gathered for the first hour of heating will show that the voltage varies largely during start up of the heating process. At about five minutes later, the graph will decay to stabilize back and only fluctuate a little along the way. The voltage value during the preheating process (less than 34 hours) is around 0.6 to 0.7 V.

After 24 hours of the preheating process, the graph will be seen to stabilize between 0.6 to 0.8V. This indicates that the sensor is ready to operate as it had been heated completely. The graph will show an almost constant reading for as long as there is no external factor that needed it to change its resistance such as humidity or high temperature. Once the sensor is exposed to LPG gas, the graph shoots up to a certain voltage higher than the 0.6~0.8V reading. Although the voltage rise can go as high as 3.0V, the sensor is quick to stabilize back once the concentration of the gas is no longer there. It normally takes approximately 30 seconds before the sensor stabilizes back to its normal value of 0.6 to 0.8V [14].

The purpose of carrying out this experiment is to observe the response of the gas sensor towards the target gas. Other than that, it can also be used to verify the theoretical value of the sensor resistance in the data sheet.

#### 2.3.5 Long-term Stability

To determine the stability of the sensor, the sensor is first energized in normal air. Measurement for confirming sensor characteristics is conducted under ambient air conditions rather than in a temperature/ humidity controlled environment. The cyclic change in sensitivity corresponds to the seasonal changes of temperature/humidity. During these measurements, the gas sensors are powered in a clean atmosphere and then exposed to a gas at certain intervals. It should be noted that sensors will not function normally when continuously exposed to a certain concentration of gas.

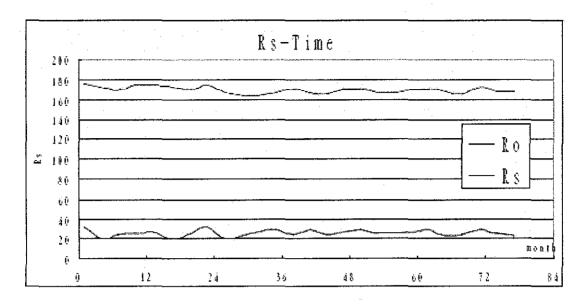


Figure 2.7: The cyclic change in sensitivity vs seasonal changes of temperature/humidity

#### 2.4 The PIC16F877 Microcontroller

The 16F877 is the microcontroller that is used in the design because it makes the detector much simpler. The chip can be programmed to perform operations based on the chip inputs and outputs. To get started to use these chips, two pieces of hardware and two pieces of software is needed [7].

## Hardware

- 1. The Hardware Programmer
- 2. The circuit to test the inputs and outputs of the chip in once it has been programmed

#### Software

- 1. To write and compile assembly (.asm) code to a hexadecimal (.hex) file
- 2. To burn the hex file onto the chip

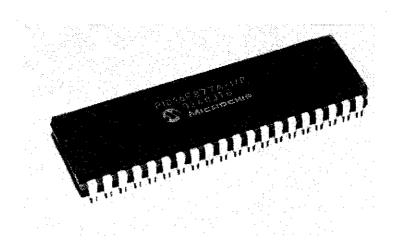


Figure 2.8: PIC 16F877

PIC16F877 features 256 bytes of EEPROM data memory, self programming, an ICD, 8 channels of 10-bit Analog-to-Digital (A/D) converter,2 additional timers, 2 capture/compare/PWM functions, the synchronous serial port can be configured as either 3-wire Serial Peripheral Interface (SPI<sup>TM</sup>) or the 2-wire Inter-Integrated Circuit (I<sup>2</sup>C<sup>TM</sup>) bus and a Universal Asynchronous Receiver Transmitter (USART). All of these features make it ideal for more advanced level A/D applications in automotive, industrial, appliances and consumer applications. [8]

Besides the usual In/out ports, the microcontroller also includes PWM (Pulse Width Modulation), a couple of Analog to Digital converters (A/D), and some type of serial communication. The Ports can be configured with the code to be inputs or outputs. We can then read a high or low logic level (inputs) or produce a high or low logic level (outputs). The PWM helps to adjust the duty cycle (how long the output is high or low) of a square wave and adjust the frequency of the square wave by giving the PIC the information in the code. The A/D converters can be used to "read" an analog voltage like the output voltage of the gas sensor. The voltage will then be represented by the PIC as a binary number [9].

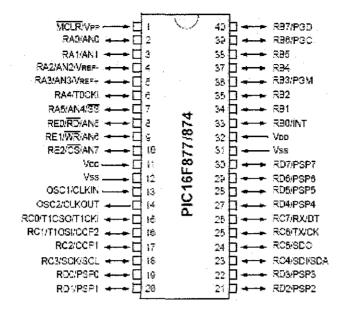


Figure 2.9: The PIC 16F877 Microcontroller pins layout

MPLAB is the free software from Microchip. It compiles the assembly language, helps organize the programs, and interfaces with what ever programmer that is used. It can also be used for debugging of the code.

MPLAB IDE runs as a 32-bit application on MS Windows<sup>®</sup>, is easy to use and includes a host of free software components for fast application development and super-charged debugging. MPLAB IDE also serves as a single, unified graphical user interface for additional Microchip and third party software and hardware development tools. Moving between tools is a snap, and upgrading from the free simulator to MPLAB ICD 2 or the MPLAB ICE emulator is done in a flash because MPLAB IDE has the same basic user interface for all tools [8].

## **CHAPTER 3**

## **METHODOLOGY**

## **3.1 Procedure Identification**

There are six tasks required to be completed for the successful conclusion of the project. These tasks are listed in Table 3.1 and the details are given in the following sections.

Task 1	: Literature review and planning
Task 2	: Gas sensor circuit design, study examples from templates and solution available in the market
Task 3	: Programming the language and loading it into the 16F877
Task 4	: Testing the circuit, testing the program
Task 5	: Producing final hardware
Task 6	: Final report and presentation

Table 3.1: Lists of Tasks for the Project

**Task 1:** The scope of the literature review includes an analysis about Lower Explosive Limit (LEL) of the LP Gas, The MQ-6 gas sensor, gas sensor operation, the microcontroller and the programming language. Sources from books and internet are very useful during this phase. A lot of information is gained through this process and it helps a lot in the progress of the design.

Task 2: Design specification and conceptual design are developed to narrow down the scope and to make easy the design process. By establishing these criteria, the design phase is made easy because all the requirements and constraints are known. Some

examples of templates from the existing designs are studied to come out with the conceptual design of the microcontroller gas detector. This task is done by numerous researches from the relevant websites and books from the library.

**Task 3:** The microcontroller programming language will be run first on the PC to check for errors before loading it into the PIC. The steps involved in programming the PIC are:

Step 1: Writing the assembly language programStep 2: Using the compilerStep 3: Programming the PIC Chip

Thus, PIC program for the gas detector can be loaded up on the computer and the program can be written on it. When writing is finished, it is ready to be assembled. This converts what have been written into a series of numbers which the computer understands and will be able to use to finally 'blow' the PIC. This new program consisting solely of numbers is called the hex code or hex file- a hex file will have .hex after its name. Basically, the 'complicated' PIC language is all a raw program consists of numbers. So, the assembler, a piece of software which comes with the PICSTART or MPLab package-called MPASM (DOS version) or WinASM (Windows version) – translates the words into numbers.

If however it fails to recognize one of the 'words' then it will register an error- things which are definitely wrong. It may register a warning to indicate something which is probably wrong. On the other hand, it may give is a message telling that something which is not wrong, but shows it has had to think a little bit more than usual when 'translating' that particular line.

Once the program has been assembled into a series of numbers, they get fused into ROM (Read Only Memory) of the PIC when we blow the PIC 16F877 and they stay there until we erase it from the PIC.

These are the procedures on how to use MPLAB:

- 1. Click on project and select new project.
- 2. Type in a name for the project and press OK. The edit project box comes up.
- 3. Hit the change button. Make sure to select the part number of the PIC the will be used.
- 4. Check the "MPLAB ICD Debugger" option. In the project files box click on the name of the project that has been created.
- 5. Select "add node". When the "add node" box comes up, type in the same name as when prompted for the project name.
- 6. Click OK. Now click on File and select New, to open a window to type the program code in.

After the codes are written and compiled, if there are no errors, the microcontroller chip can be burned. The burning process can be done using the MPLab. However, for this project, the Warp 13 is used since the application is much easier to apply and less time consuming.

**Task 4:** The testing for the detector is divided to two parts. The first test is on the sensor circuit. Then, the microcontroller code is debugged and tested using the circuit constructed before.

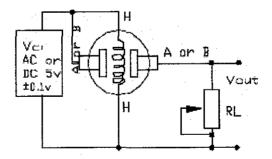


Figure 3.1: The MQ-6 Sensor Circuit

The gas sensor circuit can be tested by connecting the circuit as in the figure above. When the sensor absorbs the LP Gas, the voltage will rise up to just below 5 V. When the gas dissipates, the voltage goes down.

For the demo, all the circuits used are enclosed in a box which represents the gas detector unit. The LP Gas is released near the gas sensor. The gas detector will be on by providing power to the units from the mains supply. The detector is preheat for 2 minutes. When the LP gas concentration reaches LEL, the response of the detector is observed. When the sensor has sensed the gas adequately, the buzzer will sound and the red LED lights up. If the level rises to higher concentration, the fan will be actuated to vent-out the gas.

**Task 5:** The initial hardware was constructed by using the breadboard. After that, the circuit is transferred onto the veraboard for much stable performance and neater look. The final hardware will have the gas detector circuit in a box where it can be placed anywhere inside our homes.

Task 6: The final report and presentation will be carried out as scheduled.

#### 3.2 Tools Required

This project requires integration of software and hardware in order to produce a desired model or design. Table 3.2 shows some of the components used to build the gas detector. This means, along with the PIC 16F877 a collection of LEDs, 330 and 4.7K Resistors, 0.1 uF caps for decoupling, some switches and miscellaneous parts for different applications are also needed.

	Hardware requirements:	Software requirements
1.	VeraBoard	Electronics Work Bench (EWB)
2.	Microcontroller (PIC16F877)	MPLab
3.	Crystal Oscillator	WARP-13 – Microchip PIC Programmer
4.	MQ-6 sensor	
5.	Fan	
6.	Light Emitting Diode (LED)	
7.	Buzzer	
8.	resistors, capacitors, relay, transistors	· · · · · · · · · · · · · · · · · · ·
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Table 3.2: Component Listings

#### **CHAPTER 4**

## **RESULTS & DISCUSSION**

#### 4.1 Characteristics of MQ-6 Gas Sensor

The heart of the electronic gas detector is MQ-6 sensor which senses the LP Gas. The concentration of the gas will be determined via a unique relationship between the concentration of the gas and the internal sensor resistance

The gas detector circuit is designed to measure an the alarm threshold which is equal to a concentration 0.48% (4,800 ppm) of LP gas in the air, which corresponds to about 16% of LEL (lower explosive limit). The regulations require that the alarm threshold is below 25% of LEL. LEL for LP Gas for the MQ-6 sensor = 3.0 % (30,000ppm) as indicated in Table 4.1. This means that, once the sensor detects the 0.48% of LEL, the first alarm will trigger.

Gas Name	LEL(%)	Gas Proportion (air=1)	Toxicity
LP-Gas	3	>1	asphyxiation

Table 4.1: The MQ-6 and LP-Gas relation

This sensor is suitable for detecting of LP gas since it avoids the noise of alcohol, cooking fumes and cigarette smoke. The gas sensor is implemented in a circuit as shown in Figure 4.1 and discussed in Section 4.2.

#### 4.2 Gas Sensor Circuit Simulation

The circuit design for the MQ-6 sensor is as in Figure 4.1. The circuit comprises of some resistors, a comparator, transistor and LED-which indicates the buzzer. In this circuit, the MQ-6 sensor is represented as variable resistor. The circuit in here is used only for simulation. In the actual circuit design, only a 20 k $\Omega$  resistor is put in series with the MQ-6 sensor.

For the simulation, various  $R_L$  value for the circuit in Figure 4.1 is simulated. The voltage drop for each of these resistance values after the simulations are noted. The result of the simulation is as given in Table 4.2. For this range of  $R_L$ , the typical LP-Gas detection ranges from 300 to 100000ppm. Although the table indicates the values of  $V_{ref}$ ,  $V_{RL}$  and  $I_L$  for different resistor values, we are only interested in the value of  $V_{RL}$ .

Table 4.2: Results for simulation at  $V_C = 5V$  and  $I_T = 413.9$  mA

RL	5kΩ	20kΩ	40kΩ	400kΩ
V <sub>ref</sub>	2.619 V	2.619 V	2.619 V	2.626 V
V <sub>RL</sub>	4.282 V	4.779 V	4.981 V	4.983 V
IL	0.7mA	0.239mA	0.12mA	0.012mA

\*Vc is the voltage supplied to the sensor circuit which is 5V.

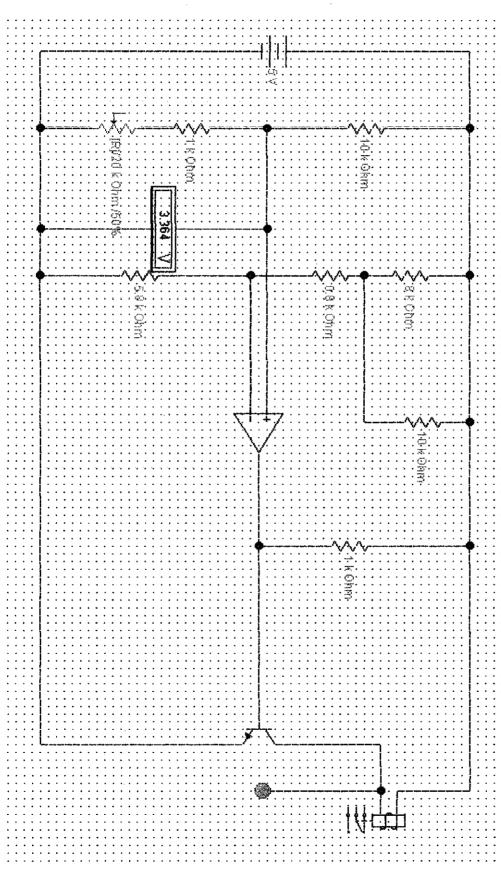
The relationship between the sensor resistance, Rs and the load resistance,  $R_L$  is given by the following expression;

$$Rs = \frac{RL(Vc - V_{RL})}{V_{RL}}$$

.....Equation 4.1

Taking the value of  $R_L$  to be 5 k $\Omega$ , the  $V_{RL}$  is 4.282 V and the value of Rs is found to be 838.39 $\Omega$ . If the value of  $R_L$  is taken to be 40 k $\Omega$ , the resulted Rs would be 152.6 $\Omega$ . At  $R_L = 400 \text{ k}\Omega$ , the Rs is 1364.6 $\Omega$ . Using  $R_L = 20 \text{ k}\Omega$  as recommended in the MQ-6 datasheet, the value of the sensing resistance is found to be 973.15 $\Omega$ .

Figure 4.1: Simulation Circuit for MQ-6 Gas Sensor



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From the results, it can be said that as the resistance of the load gets higher, the resistance of the sensor also increases. Figure 4.2 shows the corresponding values of sensor resistance to the load resistance.

#### 4.3 Gas Sensor Operation

The operation is the MQ-6 is basically by a decrease in electrical resistance when gaseous butane/propane (LP-Gas) is absorbed on the sensor surface. In air the sensor has a given resistance which is measured indirectly as the voltage at the load  $R_L$ . In the presence of deoxidizing gas the resistance of the detector goes down and this voltage rise is detected. In fresh air the current passing through the sensor and  $R_L$  is steady. When the gas fumes come in contact with the sensor, its electrical resistance decreases and the current flows through the load ( $R_L$ ). The voltage developed across the wiper of  $R_L$ , which is connected to the gate of MQ-6, triggers the MQ-6 into conduction.

Figure 4.2 shows the basic circuit for MQ-6. The variation in resistance of the sensor is measured indirectly as a change in voltage appearing across the load resistor  $R_L$ . However, when a combustible gas such as propane comes in contact with the sensor surface, the sensor resistance decreases in accordance with the gas concentration present.

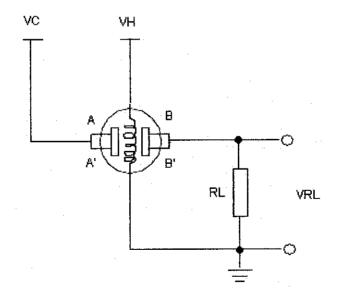


Figure 4.2: Basic Test Circuit

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The voltage change across  $R_L$  is the same when  $V_C$  and  $V_H$  are supplied from AC or DC sources. When the output signal ( $V_{RL}$ ) is measured,  $R_S$  (sensor resistance) is converted by Equation 4.1.

#### **4.4 Gas Sensor Experiments**

As mentioned before, the MQ-6 gas sensor is a resistive device, when it detects LP gas its resistance decreases. The voltage rise signifies the resistance drop in the sensor. One way to observe this is by using the PASCO and Data Studio software. However, due to time constraint, another way of obtaining the experimental values is by observing the changes in the voltage by using multimeter.

Before conducting the experiment, the connections of the circuit and sensor is checked. As can be seen in Figure 4.3, the heater pins, labeled as H on the MQ-6 gas sensor are already connected to an internal heater coil. However Pins A need to be connected externally since the legs are not internally linked. Same goes for Pins B.

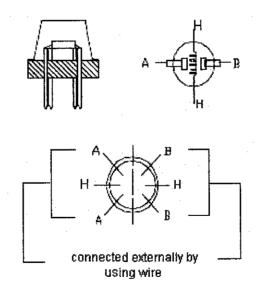


Figure 4.3: The MQ-6 Sensor pins connection

For the gas sensor, an initial 10-minutes warm-up period is required when it first turn on before conducting the experiment. The length of the warm up period will decrease with repeated use.

The results during preheating when exposed to LP Gas are as shown in Table 4.3. In Table 4.3 it can be seen that the load voltage is almost constant during the preheating time. The values indicate humidity or other foreign material that might also been sensed by the sensor is absorb by its surface.

Time ( min)	VL
1	0.017
2	0.016
3	0.015
4	0.015
5	0.015
6	0.015
7	0.015
8	0.015
9	0.015
10	0.014

Table 4.3: Voltage drop of sensor during preheating time(for 10 minutes)

Table 4.4 shows the different values of  $V_L$  when the sensor is exposed to LP-Gas. Several attempts were made to ensure that the sensor is operating accordingly. From the table, it can be seen that the sensor rapidly sense the changes in the concentration of LP Gas in air with minimum time taken to reach the maximum  $V_L$  is found to be 1.02 seconds. This shows that the sensor is very sensitive to the target gas.

Attempt	V <sub>L</sub> before exposure	Max V <sub>L</sub> (during exposure)	Time taken to reach Max V <sub>L</sub> (sec)
1	0.033	3.485	10.52
2	0.035	1.210	17.35
3	0.035	3.334	6.58
4	0.051	3.475	1.31
5	0.034	3.841	3.83
6	0.025	3.381	9.02
7	0.029	3.938	1.14
8	0.029	4.007	1.02

Table 4.4: Voltage drop of sensor during exposure to LP gas

For Attempts 5 till 8 the time taken for the gas sensor to stabilizes back are also recorded.

Attempt	Time taken to stabilize (sec)	V <sub>L</sub> when sensor is stabilized
• 5	47.48	0.033
6	47.16	0.032
7	44.59	0.032
8	46.58	0.032

Table 4.5: Voltage drop of sensor during stabilization

From these results, Equation 4.1 is again used to find the sensing resistance of the sensor in the real environment. Taking the maximum reading of  $V_L$  (4.007V) from the experiment, Rs is found to be 4956.33 $\Omega$ .At minimum reading of  $V_L$  (1.21V), the Rs is found to be 62,644.63 $\Omega$ .

All these values are obtained when the gas is exposed at a distance of about 0.5 cm from the sensor surface. At the distance of 15 cm, the maximum  $V_L$  observed is 4.48 V and it took about average of 16 seconds for the sensor to reach its max  $V_L$ . A few other attempts are taken to get the average value of  $V_L$  at this distance. The results are tabulated in Table 4.6.

Attempt	V <sub>L</sub> during exposure
1	0.678
2	0.741
3	0.576
4	0.649
5	0.753

Table 4.6: Voltage of sensor during exposure at 15 cm

From this table, the average  $V_L$  is 0.6794 V. Using Equation 4.1, the R<sub>S</sub> is equals to 127,189 $\Omega$ , indicating that the concentration of LP gas is not too high if compared to the when exposed at distance of 0.5 cm.

Therefore, the closer the distance between the lighter (gas) and the sensor results in higher concentration of gas that is being exposed to the sensor. Higher  $V_L$  means larger concentration .Therefore, the time taken for the load voltage,  $V_L$  to reach the maximum during every exposure is less when the distance is near.

During the experiment, the sensor is hot since the heating still takes place while it is working. When some humidity is applied, the  $V_L$  tends to decreased below the stabilized value. The sensor circuit is constructed with all components in series (sensor and 20 k $\Omega$  resistor).

#### 4.5 The Microcontroller

## 4.5.1 PIC16F877 Microcontroller

The program for the gas detector is blown in the PIC 16F877. A crystal clock is needed for the microcontroller to function once the chip has been programmed. For the microcontroller gas detector, there will be three outputs. First is the Red or Warning LED which when the gas concentration reaches alarm threshold, the LED lights up faintly and, after some time, lights up brightly. The second output is the buzzer which gives audible alarm when the gas concentration reaches beyond the LEL. The last output is the fan which moves to vent-out the gas when the gas concentration reaches far beyond the LEL. It is activated together with the LED and buzzer.

There would be one input which is the sensor circuit, creating a total 4 input/output pins and plus other pins that are used for the crystal clock, Vcc and ground. In this case the PIC 16F877 is suitable for this project.

The gas detector would operate most efficiently running under autonomous mode. Since the program necessary to produce the desired results needed for the gas detector is fairly straightforward the software was designed using PIC16F877 assembly. The gas sensor input will output an analog signal to the PIC that would have to be converted to a digital representation for the PIC to understand.

#### 4.5.2 The Microcontroller Language

Microcontrollers are usually programmed using the assembly language. The language consists of various mnemonics which describe the instructions. An assembler language is unique to a microcontroller and the assembly language of a certain microcontroller can not be used for any other type of microcontroller. Although the assembly language is very fast, it has some major disadvantages.

Perhaps the most important disadvantage is that the assembly language can become very complex and difficult to maintain. It is usually a very time consuming task to develop large projects using the assembly language. However, since this project only requires the basic analog-to-digital output, the assembly language used is not too difficult to understand.

As mentioned before, microcontrollers can be programmed and compiled using the MPLab. This compiler generates native machine code which can directly be loaded into the memory of the target microcontroller. Figure 4.4 shows the environment of the MPLab.

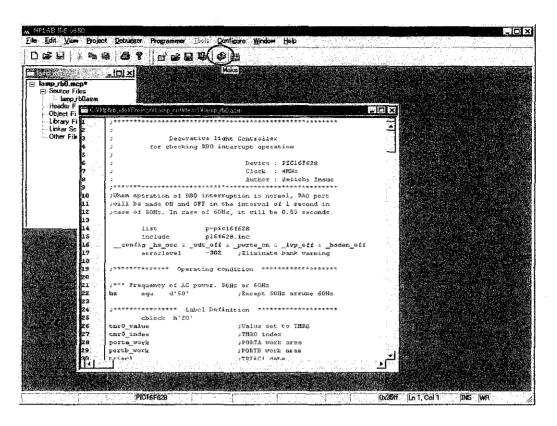


Figure 4.4 : MPLab Environment

#### 4.5.3 Voltage Range and Resolution

The resolution of the converter chip can be obtained by taking the voltage range from REF- to REF+ and divide by 8-bit resolution (or 256). From the tabulated result (Table 4.4) it can be seen that the voltage that is to be read varies from 1 to more than 4 V. Assuming that the voltage varies by 3v, say from 1 to 5 V, the REF- is set to 1 V and REF+ to 5 V.

Therefore, the voltage resolution = 5/256 = 0.0195 V. Thus, reading the number 100 from serial A/D converter (built-in inside the PIC 16F877) is equal to a voltage of 2.95 V [(100 x 0.0195 = 1.95V; 1.17 V + REF - (1 V) = 2.95 V. However, the A/D converter value can only be visualized if the LCD display is interfaced to the microcontroller circuit.

The sensor output voltage  $(V_L)$  will vary between 0 to less than 5 V. Because of the fast response of the sensor, it is hard to determine at which voltage the alarms will be triggered.

However, from the testing done, it can be assumed that the alarm starts to work when the voltage rises to almost 1 V. Therefore, VREF = 0.9V.

Condition	Alarm type
VSENSE > VREF	Gas alarm level 1
VSENSE >> VREF	Gas alarm level 2
VSENSE close to 0	Sensor malfunction

Table 4.7: Alarm conditions

#### **4.5.4 Microcontroller Experiments**

The testing of the software consisted of mainly using LEDs' for the outputs and using a power source for the inputs. This was a practical simulation of how the software should run, except an analog input was not used. The main strategy behind this was to test the PIC's ability to read in a voltage input and compare that input to a constant threshold. After the PIC compares the input it will decide to either turn on the LED or switch off the LED. In other words, if a voltage of 5V signal was input into the PIC input, the PIC will test that input and either switch on or off a light.

For the program, two experiments are conducted. Each experiment is conducted using two microcontrollers, PIC16F84A and PIC16F877. The program for microcontroller PIC 16F84A can be viewed in APPENDIX 2. The program works as follows. Port A of the microcontroller is set as the input, and Port B as the output. The input to the microcontroller is the voltage from the comparator of the gas sensor circuit. The voltage levels are as indicated in the Figure 4.5.

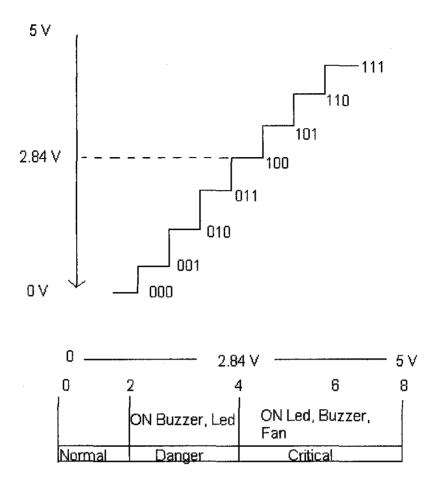


Figure 4.5: Voltage Levels of Gas Sensor

When the voltage is between 0 to 1.4 V the voltage range is considered normal where at this point, the fan, buzzer and the warning LED will not turn on. The voltage between these values indicates that the concentration of the gas is still within safe limits. If the voltage should rise between more than 1.4 V to 2.8 V, the voltage is considered high, which indicates the drop in the resistance values of the gas sensor. This shows that the concentration of the gas is dangerous, and the residents need to be alarmed of the increment in the gas concentration. Therefore, the buzzer will sound, and the warning led will turn on to alert the people around. When the gas reaches the range between 2.8 V to 5.0 V the fan will be actuated along with the buzzer and warning Led. The actuation of the fan will help to reduce the gas concentration to prevent any destruction. At this point the concentration is considered critical. If somehow the voltage input to the

microcontroller is beyond 5.0 V the program will detect the error and will loop again to determine the appropriate output.

The program had been run and compiled successfully and has been burn onto the PIC16F84A. However, during testing with all the detector circuits interfaced to the microcontroller, the output did not produce the response. Thus, another program is constructed and this time using the PIC 16F877 microcontroller.

The code for this program can be viewed in APPENDIX 3. The working is similar as the previous program only that the analog input is readily converted to digital in the microcontroller. After running the test using this program for the detector circuit, it produce the wanted outputs and in appropriate sequence too. Thus, the program is considered successful. The program flowchart can is as in Figure 4.7.

#### 4.6 Detector Circuit Implementation

Figure 4.6 shows the whole detector circuit that has been constructed. The LEDS (labeled as 1 till 8) are put to indicate the rise of voltage coming from the sensor circuit. A miniature voltage regulator circuit is put to regulate the voltage from AC supply from 9V to 5V. The regulated voltage will be used to power up the sensor and microcontroller circuit. The output of the sensor circuit will be the input for the microcontroller at Pin 3. The outputs of the microcontroller come from Pins 15, 16, 17, 18, 23, 24, 25 and 26.

As the voltage goes higher (higher gas concentration), the outputs will be triggered into conduction in a sequence as indicated in the flowchart in Figure 4.7. The buzzer used is cheap and inexpensive. It was found that no external circuitry was needed as it can be hooked up directly to the PIC output. The fan motor could not be hooked directly to an output pin on the PIC as noticed after trying to do so. The fan needs to be powered up by

external DC supply of 12 V in order to actuate it. The output of the microcontroller would only energize the 6V relay to signal that the fan needs to be activated.

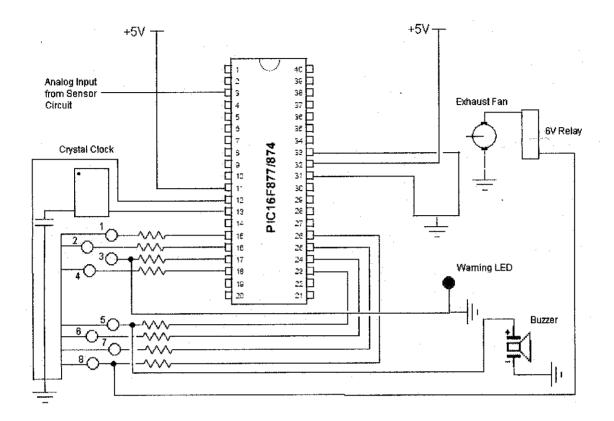


Figure 4.6: The Microcontroller- based LP-Gas Detector Schematic

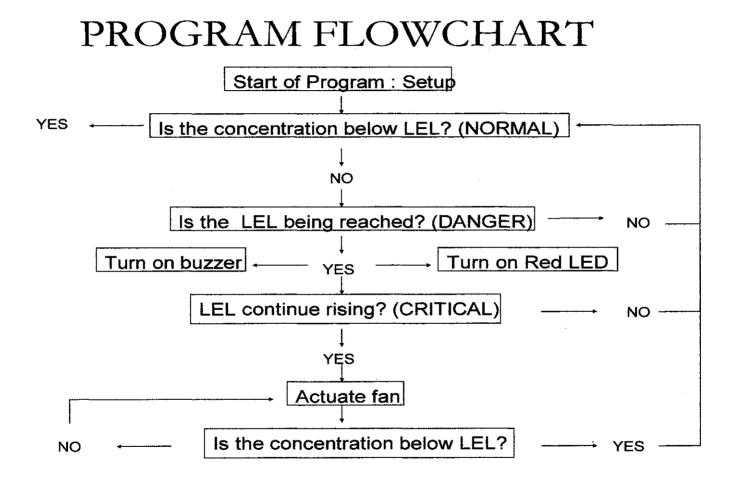


Figure 4.7: Microcontroller Program Flowchart

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### **4.7 Cost Estimation**

The cost below is the price for a physical unit of a gas detector

Components	Quantity (Unit)	Cost (RM)
MQ-6 Gas Sensor	1	50.00
PIC 16F877	1	30.00
Buzzer	1	2.50
Fan	1	10.00
LED	10	6.00
Capacitors	4	4.00
Relay	1	6.00
Veraboard	3	3.60
AC Supply Adapter	1	25.00
Total Estimation		137.10

#### Table 4.8: Components Price Listings

The total estimation is based on assumptions of the cost of each component. The actual cost could be less than RM100. The cost for the software, MPLab is not included since it can be downloaded for free from the internet. The burner can also be built and normally the cost will not exceed RM20.

From this cost estimation, it can be concluded that the microcontroller-based gas detector is low in price and can be obtained for much cheaper price if it were to be sold in large numbers.

### **CHAPTER 5**

## **CONCLUSION AND RECOMMENDATIONS**

### **5.1 Conclusion**

The project aim was to construct a gas detector unit which monitors the level of LP Gas in air of a confined space or a chamber. Consequently, this intend is successfully realized. From the development of the project, it can be concluded that the use of MQ-6 sensor together with the microcontroller produces a reliable gas detector unit. The presence of the LP gas is indicated by the decrease of the sensor resistance. From the simulations done, the results obtained verified that the circuit responds to the presence of LP-Gas. Even without the comparator (which was initially used in the simulation), the detector unit still work successfully because of the miraculous microcontroller, which controls the outputs of the detector.

From the experiments carried out, it can be summarized that the gas detector was able to detect the presence of gas assuming the gas is absorb directly on the sensor surface. The gas detector was able to detect high LPG concentration and produce fast response.

Together with low cost and good quality gas sensor, the detector unit is also possible to be developed in really short time. The reproducibility is great and the detector can be assembled and debugged also by electronic beginner.

The gas detector itself is very good guard which increases the safety of your home. It helps to prevent dangerous situations when the gas cooker or gas boiler have uncontrolled leakage

#### **5.2 Future Recommendations**

For improving this design, a few recommendations are proposed. For future construction, the circuit can be transferred to the Printed Circuit Board (PCB) for much neat and stable performance. For better monitoring of the voltage levels, Liquid Crystal Display (LCD) display can be interfaced to the microcontroller. Other type of gas sensor can also be incorporated to replace the MQ-6. The type of sensor which is commonly used is the TGS sensor (LPM2610). The datasheet is as in APPENDIX 9. However, the design will be better and less power consuming if new sensor that need not be heated are found. This will save time and ensure that the sensor works perfectly once supplied with specific voltage. The gas detector in the end can also be combined with any central home security system and can be also connected to some wireless transmitter.

## REFERENCES

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# APPENDICES

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40		plosion hit(%)	Gas proportion	Sparking	toxicity	Permission		
Gas name	Low er limit	Upper lim	(air=1)	point		concentration		
Methane	5	15	0.55	537.8	asphyxiation			
Ethane	3	12.5	1.406	515	asphyxiation			
Propane	2.3	9.15	1.56	467.8	asphyxiation	1000ppm		
Butane	1.8	8.44	2		asphyxiation			
Ethene	2.7	28.5			narcosis			
Propylene	2.4	11	·		narcosis			
Acetylene	1.5	82	0.906	305				
Hydrogen	4.1	74.2	0.069	585	asphyxiation			
со	12.5	75.6	0.967	608	toxicosis	50ppm		
Natural gases	5	15	<]		asphyxiation			
LPG	3		>1		asphyxiation			
City gas	4	30	0.4		toxicosis	100ppm		
Gasoline	1.2	7.5	3.3	280	Asphyxiation& asphyxiation			
Coal oil	0.7	5	4~5					
Alcohol	3.3	19	1.58	392		1000ppm		
Ethanol	3.5	6.7	0.78	422		1mg/m		
Methyl Alcohol	6.7	36	0.79	385		0.05mg/m		
Acetone	8.1	13	0.79			1000ppm		

Table 10: The familiar combustible, liquid gas explosion limits

# PIC 16F84A Program

#include <P16F84A.inc>

;-----Reserving register-----cblock 0x0C

endc

UIIUU . . ?

;	Equating	, Variable
Fan	equ	3
Buzzer	equ	4
Led	equ	5
;		

	org goto	0x00 setup							
setup	bsf movlw movwf movlw movwf bcf bsf goto	STATUS, 0xFF TRISA 0x07 TRISB STATUS, PORTB, 7 main	RP0	; select bank 1 ; set PortA as an input ; set PortB Pin 3-7 as an output ; move to control register of port b ; select bank 0 ; Pull PortB, P7 HIGH					
main	clrwdt nop call goto	Chk_Inpu main	t ; Check in	; so that it put from Pe	ntent of watch dog timer will never overflow ortA in and keep checking input from PortA				
Chk_Inp	ut	nop							
TryNorn	nal	clrwdt movf addiw btfsc goto bcf bcf bcf return	PORTA, v d'255' - d'2 STATUS, TryDange PORTB, I PORTB, I PORTB, I	2' C r; goto Try Fan Buzzer	; read from Port B ; if the value is 2 and less ; check whether overflow occur Danger if overflow does not occur ; if overflow does not occur ; Fan is switched OFF ; Buzzer is switched OFF ; Led is switched OFF				
TryDang	jer	clrwdt movf addlw btfsc goto bcf bsf bsf return	PORTA, y d'255' - d' STATUS, TryCritica PORTB, I PORTB, I PORTB, I	4' C al; goto Try Fan Buzzer	; read from Port B ; if the value is 4 and less ; check whether overflow occur Critical if overflow does not occur ; if overflow does not occur ; Fan is switched OFF ; Buzzer is switched ON ; Led is switched ON				
TryCriti	cal	clrwdt movf	PORTA,	w	; read from Port B				

sublw	ď255' - ď	8' .	; if the value is 8 and	less
		btfsc goto	STATUS, C TryError	; check whether overflow occur ; goto TryError to indicate the value is not valid ; if overflow occur
		bsf bsf bsf return	PORTB, Fan PORTB, Buzzer PORTB, Led	; Fan is switched ON ; Buzzer is switched ON ; Led is switched ON
TryError		bcf nop goto	PORTB, 7 _TryError; reset itse	; ; ON Error Led ; Looping until microcontroller elf

end

# PIC 16F877 Program

#include <p16f877.inc>

		cblock NumL NumH endc	0x20	;start of ge	eneral purp	ose registers
;start of program						
		ORG GOTO ORG		0x0000 Initialise 0x0004		
Initialise clrf		PORTA clrf BANKSE moviw movwf BANKSE		PORTB PORTC ADCON1 0x06 ADCON1 PORTA		;disable A2D
SetPorts bof	call bsf bcf moviw	STATUS, H'00'	RP0 Init_ADC STATUS, STATUS,	RP0	;select bar	ık () ;initialise analogue input ;bank 1
	movwf movlw	TRISC H'FF'			;set as out	put
	movwf bcf	TRISB	STATUS,	RP0	;set as inp	ut
Main	btfsc call btfss call	PORTB,0 PORTB,0	Temp			
	goto		Main			
Init_ADC0	moviw movwf BANKSE moviw movwf BANKSE Return	L	ADCONI	; Set ADC		;set for AN0 ; Set ADCON0
lnit_ADC1	movlw movwf BANKSE movlw	L	b'0100100 ADCON0 ADCON1 b'0000000		ort a, pin 1 ON1	;set for AN1 ; Set ADCON0 ;enable a/d

movwf	ADCON1 BANKSEL Return	ADCON0
Read_ADC movwf	bsf btfsc ADCON goto \$-1 movf PORTC return	ADCON0, GO_DONE ; initiate conversion 0, GO_DONE ; wait for ADC to finish ADRESH, W
Read_ADC2	bsf btfsc ADCON( goto \$-1 movf movwf return	ADCON0,GO_DONE;initiate conversion 0, GO_DONE ;wait for ADC to finish ADRESH,W PORTC
Temp	call Init_ADC0 call Read_ADC return	
Speed	Call Init_ADC1 Call Read_ADC2 return end	

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.

Activities	W1	W2	W3	W4	W5	W6	<b>W</b> 7	W8	W9	W10	W11	W12	W13	W14	SW	EW
TASK 1					•		<u> </u>							-		••••••
Selection of Project Topic																
Propose topic																
Topic assigned to student		•														
Preliminary Research Work						•										
Introduction			67836 <del>8</del> ,2													
Objective and scope																
Project planning				14 A.												
List of references/literature																
Submission of Preliminary Report				•												
						<u> </u>				<u> </u>						
TASK 2																
Literature research			Seconda.													
Research on gas sensor and microcontroller																
Conceptual design (circuit schematic)																
Simulation & modification																
						<u> </u>										
Submission of Progress Report									•							
<u></u>		<u> </u>						i			<u> </u>					i
TASK 3		-					•								,	
Modification & components purchasing								- 1952-61			and the second se					
Bread-boarding and testing										12 14 18 19			and a second			
Prepare Interim report																
Submission of Interim Report (Draft)			<b>_</b>		Į								•		ļ	
						ļ		<u> </u>				ļ	ļ			
Oral Presentation															- Subdrawa	
											L					
Submission of Interim Report				L		ļ									······	•

## Gantt chart (Semester 2) of the Microcontroller-based LP-Gas Detector Project

No.	Detail/ Week	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
<u> </u>	Project Work Continue			i Çire d			I											
	-Practical/Laboratory Work (Testing the circuit, PASCO)			ļ					<u></u>									
2	Submission of Progress Report 1				0									÷				
				· · · ·						· ·			·					
	Project Work Continue																	
	(PIC Programming, Troubleshooting the circuit)																	
4	Submission of Progress Report 2				 			-	۲			· · · · ·						
5	Project work continue		<u> </u>															
	(Building the environment for the gas detector, PIC programming adjustments, interfacing the PIC with the sensor circuit)																	
6	Submission of Dissertation Final Draft													00				
	Submission of Dissertation Find Dialt		<u> </u>		<u> </u>	_		·						-				
7	Oral Presentation	ļ	ļ		Į						·					•		
8	Submission of Project Dissertation		<u> .</u>												·····			•

•

Milestone

Process

# Photos Taken during Experiments

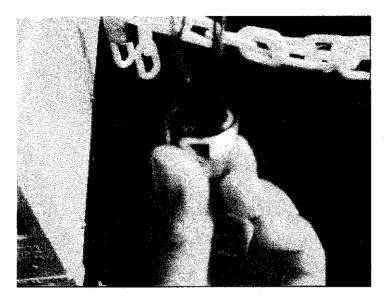


Figure I: The MQ-6 Sensor pins connection

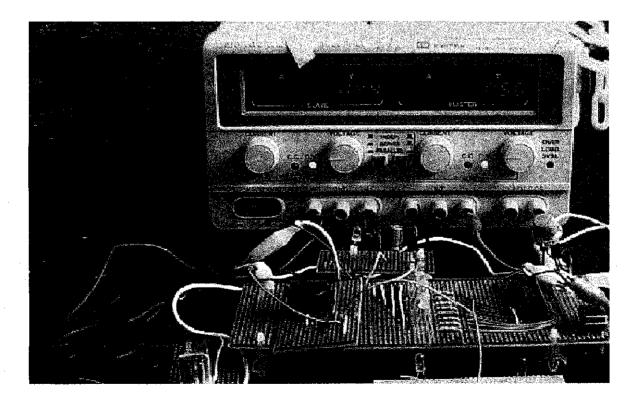
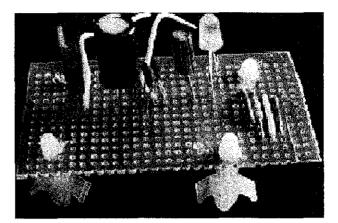


Figure II: Microcontroller-based LPG Detector Circuit



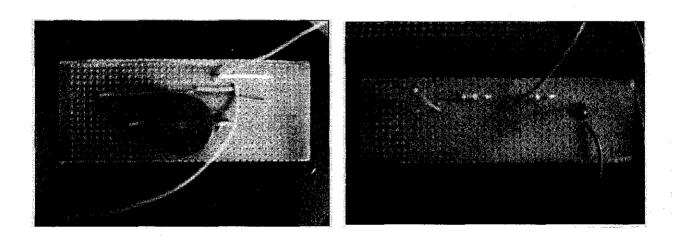


Figure IV: Buzzer Circuit

Figure VI: LED Circuit

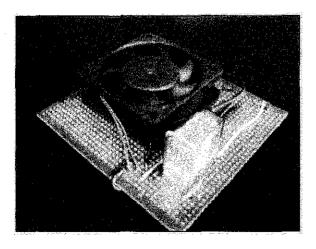


Figure III: Voltage-regulator Circuit

Figure V: Exhaust Fan Circuit

### Kitchen Environment with Gas Detector

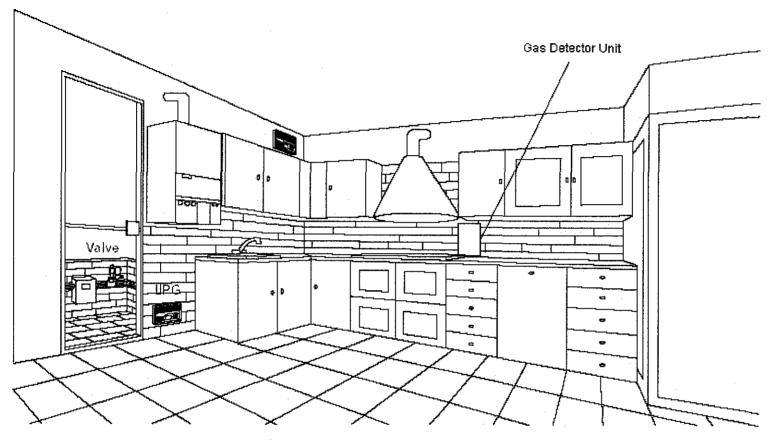


Figure VI: Kitchen Environment

Note that the gas detector is put near the cooking fumes to ensure the safety of the household. This detector is powered by the mains supply. It can be left switched on for hours to make sure that the level of LP Gas does not exceeds its limit.



# **PIC16F87X**

# 28/40-Pin 8-Bit CMOS FLASH Microcontrollers

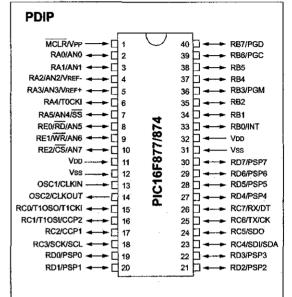
#### **Devices Included in this Data Sheet:**

- PIC16F873
- PIC16F876
- PIC16F874
- PIC16F877

#### **Microcontroller Core Features:**

- · High performance RISC CPU
- · Only 35 single word instructions to learn
- All single cycle instructions except for program branches which are two cycle
- Operating speed: DC 20 MHz clock input DC - 200 ns instruction cycle
- Up to 8K x 14 words of FLASH Program Memory, Up to 368 x 8 bytes of Data Memory (RAM) Up to 256 x 8 bytes of EEPROM Data Memory
- Pinout compatible to the PIC16C73B/74B/76/77
- · Interrupt capability (up to 14 sources)
- Eight level deep hardware stack
- · Direct, indirect and relative addressing modes
- Power-on Reset (POR)
- Power-up Timer (PWRT) and Oscillator Start-up Timer (OST)
- Watchdog Timer (WDT) with its own on-chip RC oscillator for reliable operation
- · Programmable code protection
- Power saving SLEEP mode
- Selectable oscillator options
- Low power, high speed CMOS FLASH/EEPROM technology
- Fully static design
- In-Circuit Serial Programming<sup>™</sup> (ICSP) via two pins
- · Single 5V In-Circuit Serial Programming capability
- In-Circuit Debugging via two pins
- · Processor read/write access to program memory
- Wide operating voltage range: 2.0V to 5.5V
- · High Sink/Source Current: 25 mA
- Commercial, Industrial and Extended temperature ranges
- Low-power consumption:
  - < 0.6 mA typical @ 3V, 4 MHz</li>
  - 20 μA typical @ 3V, 32 kHz
  - < 1 µA typical standby current

#### **Pin Diagram**



#### **Peripheral Features:**

- · Timer0: 8-bit timer/counter with 8-bit prescaler
- Timer1: 16-bit timer/counter with prescaler, can be incremented during SLEEP via external crystal/clock
- Timer2: 8-bit timer/counter with 8-bit period register, prescaler and postscaler
- Two Capture, Compare, PWM modules
  - Capture is 16-bit, max. resolution is 12.5 ns
  - Compare is 16-bit, max. resolution is 200 ns
  - PWM max. resolution is 10-bit
- · 10-bit multi-channel Analog-to-Digital converter
- Synchronous Serial Port (SSP) with SPI<sup>™</sup> (Master mode) and I<sup>2</sup>C<sup>™</sup> (Master/Slave)
- Universal Synchronous Asynchronous Receiver Transmitter (USART/SCI) with 9-bit address detection
- Parallel Slave Port (PSP) 8-bits wide, with external RD, WR and CS controls (40/44-pin only)
- Brown-out detection circuitry for Brown-out Reset (BOR)

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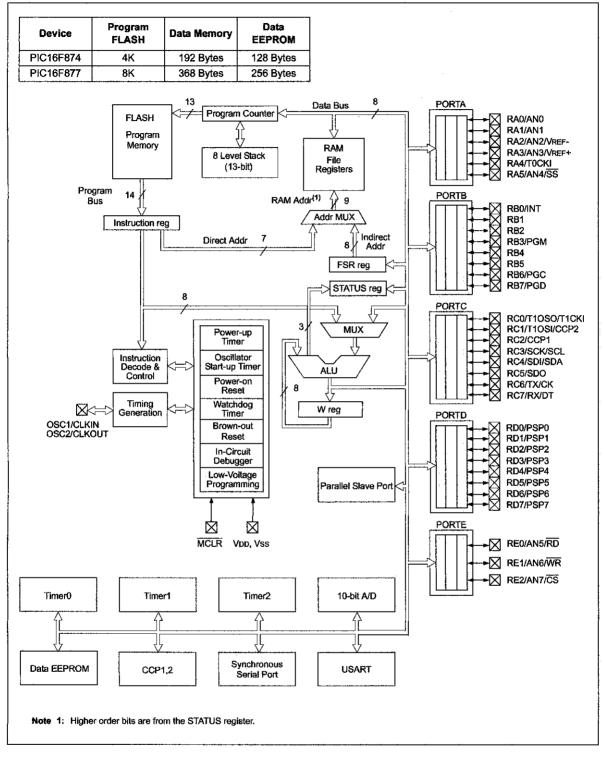
Key Features PICmicro™ Mid-Range Reference Manual (DS33023)	PIC16F873	PIC16F874	PIC16F876	PIC16F877
Operating Frequency	DC - 20 MHz			
RESETS (and Delays)	POR, BOR (PWRT, OST)	POR, BOR (PWRT, OST)	POR, BOR (PWRT, OST)	POR, BOR (PWRT, OST)
FLASH Program Memory (14-bit words)	4K	4K	8K	8K
Data Memory (bytes)	192	192	368	368
EEPROM Data Memory	128	128	256	256
Interrupts	13	14	13	14
I/O Ports	Ports A,B,C	Ports A,B,C,D,E	Ports A,B,C	Ports A,B,C,D,E
Timers	3	3	3	3
Capture/Compare/PWM Modules	2	2	2	2
Serial Communications	MSSP, USART	MSSP, USART	MSSP, USART	MSSP, USART
Parallel Communications		PSP		PSP
10-bit Analog-to-Digital Module	5 input channels	8 input channels	5 input channels	8 input channels
Instruction Set	35 instructions	35 instructions	35 instructions	35 instructions

1

# PIC16F87X



#### : PIC16F874 AND PIC16F877 BLOCK DIAGRAM

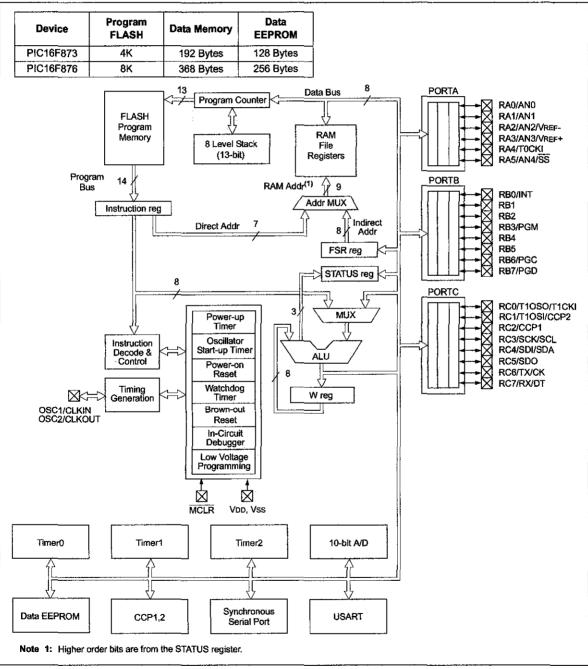


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### 1.0 DEVICE OVERVIEW

This document contains device specific information. Additional information may be found in the PICmicro<sup>™</sup> Mid-Range Reference Manual (DS33023), which may be obtained from your local Microchip Sales Representative or downloaded from the Microchip website. The Reference Manual should be considered a complementary document to this data sheet, and is highly recommended reading for a better understanding of the device architecture and operation of the peripheral modules. There are four devices (PIC16F873, PIC16F874, PIC16F876 and PIC16F877) covered by this data sheet. The PIC16F876/873 devices come in 28-pin packages and the PIC16F877/874 devices come in 40-pin packages. The Parallel Slave Port is not implemented on the 28-pin devices.

The following device block diagrams are sorted by pin number; 28-pin for Figure 1-1 and 40-pin for Figure 1-2. The 28-pin and 40-pin pinouts are listed in Table 1-1 and Table 1-2, respectively.



#### FIGURE 1-1: PIC16F873 AND PIC16F876 BLOCK DIAGRAM

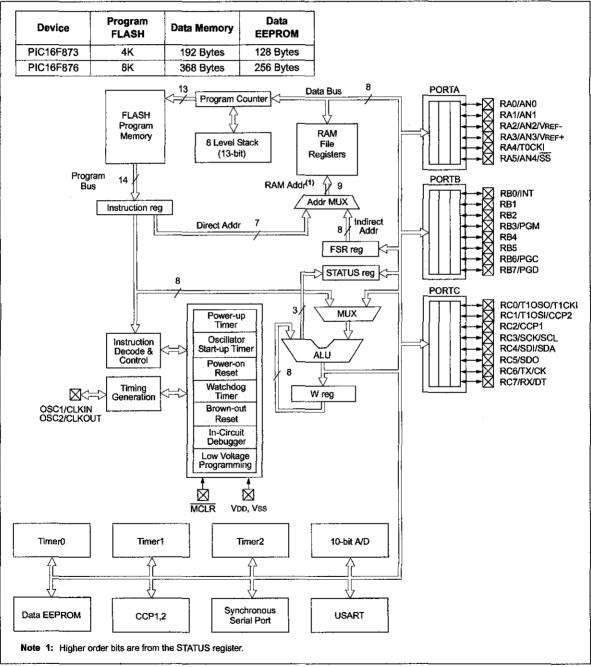
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### 1.0 DEVICE OVERVIEW

This document contains device specific information. Additional information may be found in the PICmicro<sup>™</sup> Mid-Range Reference Manual (DS33023), which may be obtained from your local Microchip Sales Representative or downloaded from the Microchip website. The Reference Manual should be considered a complementary document to this data sheet, and is highly recommended reading for a better understanding of the device architecture and operation of the peripheral modules. There are four devices (PIC16F873, PIC16F874, PIC16F876 and PIC16F877) covered by this data sheet. The PIC16F876/873 devices come in 28-pin packages and the PIC16F877/874 devices come in 40-pin packages. The Parallel Slave Port is not implemented on the 28-pin devices.

The following device block diagrams are sorted by pin number; 28-pin for Figure 1-1 and 40-pin for Figure 1-2. The 28-pin and 40-pin pinouts are listed in Table 1-1 and Table 1-2, respectively.



#### FIGURE 1-1: PIC16F873 AND PIC16F876 BLOCK DIAGRAM

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#### **TABLE 1-2:** PIC16F874 AND PIC16F877 PINOUT DESCRIPTION

Pin Name	DIP Pin#	PLCC Pin#	QFP Pin#	l/O/P Type	Buffer Type	Description
OSC1/CLKIN	13	14	30		ST/CMOS <sup>(4)</sup>	Oscillator crystal input/external clock source input.
OSC2/CLKOUT	14	15	31	0	_	Osciliator crystal output. Connects to crystal or resonator in crystal oscillator mode. In RC mode, OSC2 pin outputs CLKOUT which has 1/4 the frequency of OSC1, and denotes the instruction cycle rate.
MCLR/VPP	1	2	18	l/P	ST	Master Clear (Reset) input or programming voltage input. This pin is an active low RESET to the device.
						PORTA is a bi-directional I/O port.
RA0/AN0	2	3	19	I/O	TTL	RA0 can also be analog input0.
RA1/AN1	3	4	20	1/0	TTL	RA1 can also be analog input1.
RA2/AN2/VREF-	4	5	21	1/0	TTL	RA2 can also be analog input2 or negative analog reference voltage.
RA3/AN3/VREF+	5	6	22	1/0	TTL	RA3 can also be analog input3 or positive analog reference voltage.
RA4/T0CKI	6	7	23	1/0	ST	RA4 can also be the clock input to the Timer0 timer/ counter. Output is open drain type.
RA5/SS/AN4	7	8	24	1/0	TTL	RA5 can also be analog input4 or the slave select for the synchronous serial port.
						PORTB is a bi-directional I/O port. PORTB can be soft- ware programmed for internal weak pull-up on all inputs.
RB0/INT	33	36	8	1/0	TTL/ST <sup>(1)</sup>	RB0 can also be the external interrupt pin.
RB1	34	37	9	1/0	TTL	
RB2	35	38	10	I/O	TTL	
RB3/PGM	36	39	11	I/O	TTL	RB3 can also be the low voltage programming input.
RB4	37	41	14	I/O	TTL	Interrupt-on-change pin.
RB5	38	42	15	1/0	ΠL	Interrupt-on-change pin.
RB6/PGC	39	43	16	1/0	TTL/ST <sup>(2)</sup>	Interrupt-on-change pin or In-Circuit Debugger pin. Serial programming clock.
RB7/PGD	40	44	17	I/O	TTL/ST <sup>(2)</sup>	Interrupt-on-change pin or In-Circuit Debugger pin. Serial programming data.
Legend: 1 = input	0 = 0 — = N	utput lot used	4	I/O = inp TTL = T	ut/output TL input	P = power ST = Schmitt Trigger input

Note 1: This buffer is a Schmitt Trigger input when configured as an external interrupt.

2: This buffer is a Schmitt Trigger input when used in Serial Programming mode.

3: This buffer is a Schmitt Trigger input when configured as general purpose I/O and a TTL input when used in the Parallel Slave Port mode (for interfacing to a microprocessor bus).

4: This buffer is a Schmitt Trigger input when configured in RC oscillator mode and a CMOS input otherwise.

Pin Name	DIP Pin#	PLCC Pin#	QFP Pin#	I/O/P Type	Buffer Type	Description
						PORTC is a bi-directional I/O port.
RC0/T1OSO/T1CKI	15	16	32	I/O	ST	RC0 can also be the Timer1 oscillator output or a Timer1 clock input.
RC1/T1OSI/CCP2	16	18	35	1/0	ST	RC1 can also be the Timer1 oscillator input or Capture2 input/Compare2 output/PWM2 output.
RC2/CCP1	17	19	36	1/0	ST	RC2 can also be the Capture1 input/Compare1 output/PWM1 output.
RC3/SCK/SCL	18	20	37	1/0	ST	RC3 can also be the synchronous serial clock input/ output for both SPI and I <sup>2</sup> C modes.
RC4/SDI/SDA	23	25	42	1/0	SТ	RC4 can also be the SPI Data In (SPI mode) or data I/O ( $I^2C$ mode).
RC5/SDO	24	26	43	1/0	ST	RC5 can also be the SPI Data Out (SPI mode).
RC6/TX/CK	25	27	44	1/0	ST	RC6 can also be the USART Asynchronous Transmit or Synchronous Clock.
RC7/RX/DT	26	29	1	1/0	ST	RC7 can also be the USART Asynchronous Receive or Synchronous Data.
,						PORTD is a bi-directional I/O port or parallel slave port when interfacing to a microprocessor bus.
RD0/PSP0	19	21	38	1/0	ST/TTL <sup>(3)</sup>	
RD1/PSP1	20	22	39	1/0	ST/TTL <sup>(3)</sup>	
RD2/PSP2	21	23	40	1/0	ST/TTL <sup>(3)</sup>	
RD3/PSP3	22	24	41	1/0	ST/TTL <sup>(3)</sup>	
RD4/PSP4	27	30	2	I/O	ST/TTL <sup>(3)</sup>	
RD5/PSP5	28	31	3	1/0	ST/TTL <sup>(3)</sup>	
RD6/PSP6	29	32	4	1/O	ST/TTL <sup>(3)</sup>	
RD7/PSP7	30	33	5	1/0	ST/TTL <sup>(3)</sup>	
						PORTE is a bi-directional I/O port.
RE0/RD/AN5	8	9	25	1/0	ST/TTL <sup>(3)</sup>	RE0 can also be read control for the parallel slave port, or analog input5.
RE1/WR/AN6	9	10	26	1/0	ST/TTL <sup>(3)</sup>	RE1 can also be write control for the parallel slave port, or analog input6.
RE2/CS/AN7	10	11	27	1/0	ST/TTL <sup>(3)</sup>	RE2 can also be select control for the parallel slave port, or analog input7.
Vss	12,31	13,34	6,29	P	—	Ground reference for logic and I/O pins.
VDD	11,32	12,35	7,28	Р	—	Positive supply for logic and I/O pins.
NC	—	1, <b>17,28</b> , 40	12,13, 33,34			These pins are not internally connected. These pins should be left unconnected.
Legend: I = input	0 = 0 = 1	utput lot used		I/O = inp TTL = T	ut/output TL input	P = power ST = Schmitt Trigger input

Note 1: This buffer is a Schmitt Trigger input when configured as an external interrupt.

2: This buffer is a Schmitt Trigger input when used in Serial Programming mode.

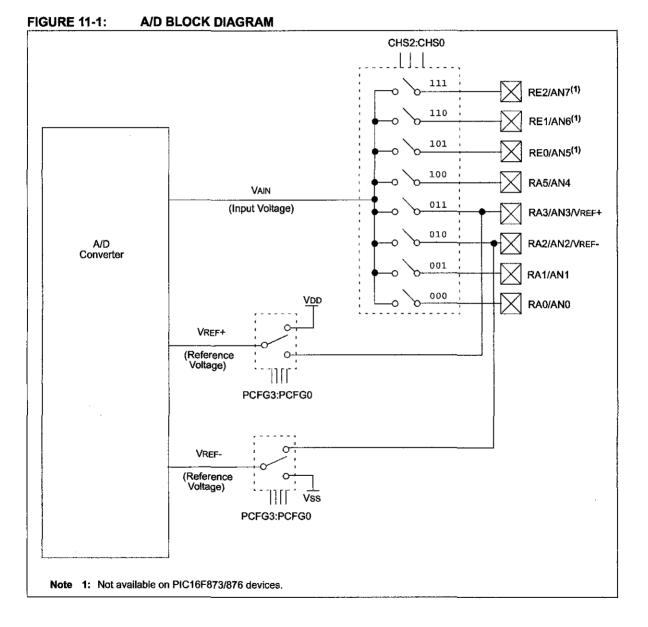
3: This buffer is a Schmitt Trigger input when configured as general purpose I/O and a TTL input when used in the Parallel Slave Port mode (for interfacing to a microprocessor bus).

4: This buffer is a Schmitt Trigger input when configured in RC oscillator mode and a CMOS input otherwise.

These steps should be followed for doing an A/D Conversion:

- 1. Configure the A/D module:
  - Configure analog pins/voltage reference and digital I/O (ADCON1)
  - Select A/D input channel (ADCON0)
  - Select A/D conversion clock (ADCON0)
  - Turn on A/D module (ADCON0)
- 2. Configure A/D interrupt (if desired):
  - · Clear ADIF bit
  - Set ADIE bit
  - Set PEIE bit
  - Set GIE bit

- 3. Wait the required acquisition time.
- 4. Start conversion:
  - Set GO/DONE bit (ADCON0)
- 5. Wait for A/D conversion to complete, by either:
  - Polling for the GO/DONE bit to be cleared (with interrupts enabled); OR
  - Waiting for the A/D interrupt
- Read A/D result register pair (ADRESH:ADRESL), clear bit ADIF if required.
- 7. For the next conversion, go to step 1 or step 2, as required. The A/D conversion time per bit is defined as TAD. A minimum wait of 2TAD is required before the next acquisition starts.



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# PIC16F87X



U-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
ADFM	-			PCFG3	PCFG2	PCFG1	PCFG0
bit 7							bit 0

bit 7 **ADFM:** A/D Result Format Select bit

1 =Right justified. 6 Most Significant bits of ADRESH are read as '0'.

0 = Left justified. 6 Least Significant bits of ADRESL are read as '0'.

#### bit 6-4 Unimplemented: Read as '0'

bit 3-0 PCFG3:PCFG0: A/D Port Configuration Control bits:

PCFG3: PCFG0	AN7 <sup>(1)</sup> RE2	AN6 <sup>(1)</sup> RE1	AN5 <sup>(1)</sup> RE0	AN4 RA5	AN3 RA3	AN2 RA2	AN1 RA1	AN0 RA0	VREF+	VREF-	CHAN/ Refs <sup>(2)</sup>
0000	A	A	Α	Α	A	A	Α	A	VDD	Vss	8/0
0001	A	A	Α	A	VREF+	A	Α	A	RA3	Vss	7/1
0010	D	D	D	Α	A	A	Α	A	daV	Vss	5/0
0011	D	D.	D	Α	VREF+	A	A	A	RA3	Vss	4/1
0100	D	D	D	D	A	D	A	A	VDD	Vss	3/0
0101	D	D	D	Ď	VREF+	D	Α	A	RA3	Vss	2/1
011x	D	D	D	D	D	D	D	D	VDD	Vss	0/0
1000	A	A	Α	Α	VREF+	VREF-	A	A	RA3	RA2	6/2
1001	D	D	Α	A	A	A	Α	A	VDD	Vss	6/0
1010	D	D	Α	Α	VREF+	A	A	A	RA3	Vss	5/1
1011	D	D	A ·	Α	VREF+	VREF-	Α	A	RA3	RA2	4/2
1100	D	D	D	Α	VREF+	VREF-	A	A	RA3	RA2	3/2
1101	D	D	D	D	VREF+	VREF-	A	A	RA3	RA2	. 2/2
1110	D	D	D	D	D	D	D	A	VDD	Vss	1/0
1111	D	D	D	D	VREF+	VREF-	D	A	RA3	RA2	1/2

A = Analog input D = Digital I/O

Note 1: These channels are not available on PIC16F873/876 devices.

2: This column indicates the number of analog channels available as A/D inputs and the number of analog channels used as voltage reference inputs.

Legend:			· · · · ·
R = Readable bit	W = Writable bit	U = Unimplemented	bit, read as '0'
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

The ADRESH:ADRESL registers contain the 10-bit result of the A/D conversion. When the A/D conversion is complete, the result is loaded into this A/D result register pair, the GO/DONE bit (ADCON0<2>) is cleared and the A/D interrupt flag bit ADIF is set. The block diagram of the A/D module is shown in Figure 11-1.

After the A/D module has been configured as desired, the selected channel must be acquired before the conversion is started. The analog input channels must have their corresponding TRIS bits selected as inputs. To determine sample time, see Section 11.1. After this acquisition time has elapsed, the A/D conversion can be started.

### 11.0 ANALOG-TO-DIGITAL CONVERTER (A/D) MODULE

The Analog-to-Digital (A/D) Converter module has five inputs for the 28-pin devices and eight for the other devices.

The analog input charges a sample and hold capacitor. The output of the sample and hold capacitor is the input into the converter. The converter then generates a digital result of this analog level via successive approximation. The A/D conversion of the analog input signal results in a corresponding 10-bit digital number. The A/D module has high and low voltage reference input that is software selectable to some combination of VDD, Vss, RA2, or RA3.

The A/D converter has a unique feature of being able to operate while the device is in SLEEP mode. To operate in SLEEP, the A/D clock must be derived from the A/D's internal RC oscillator. The A/D module has four registers. These registers are:

- A/D Result High Register (ADRESH)
- A/D Result Low Register (ADRESL)
- A/D Control Register0 (ADCON0)
- A/D Control Register1 (ADCON1)

The ADCON0 register, shown in Register 11-1, controls the operation of the A/D module. The ADCON1 register, shown in Register 11-2, configures the functions of the port pins. The port pins can be configured as analog inputs (RA3 can also be the voltage reference), or as digital I/O.

Additional information on using the A/D module can be found in the PICmicro™ Mid-Range MCU Family Reference Manual (DS33023).

	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
	ADCS1	ADCS0	CHS2	CHS1	CHS0	GO/DONE		ADON
	bit 7	• <b>•</b>		<u> </u>				bit 0
bit 7-6	00 = Fosc/2 01 = Fosc/8 10 = Fosc/3	1				lator)		
bit 5-3	000 = chan 001 = chan 010 = chan 011 = chan 100 = chan 101 = chan 110 = chan	2: Analog Cha nel 0, (RA0/Al nel 1, (RA1/Al nel 2, (RA2/Al nel 3, (RA3/Al nel 4, (RA5/Al nel 5, (RE0/Al nel 6, (RE1/Al nel 6, (RE2/Al	NO) N1) N2) N3) N4) N5) <sup>(1)</sup> N6) <sup>(1)</sup>	bits				
bit 2	If ADON = 1 1 = A/D con 0 = A/D con	A/D Conversi version in proversion in proversion not in version not in	gress (setti progress (t	ng this bit sta		,	ware when th	e A/D
bit 1		nted: Read a	•					
bit 0	ADON: A/D On bit 1 = A/D converter module is operating 0 = A/D converter module is shut-off and consumes no operating current							
	Note 1: T	hese channel	s are not av	ailable on Pl	C16F873/87	6 devices.		
	Legend:	· · · · · · · · · · · · · · · · · · ·	· · · · · ·					
	R = Readab	le bit	W = W	ritable bit	U = Unimj	plemented bit	, read as '0'	
	- n = Value a	at POR	'1' = Bi	t is set	'0' = Bit is	cleared	x = Bit is unk	nown

REGISTER 11-1: ADCON0 REGISTER (ADDRESS: 1Fh)

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#### 11.4 A/D Conversions

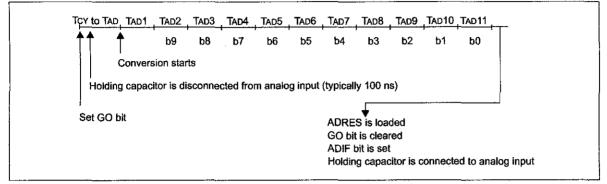
Clearing the GO/DONE bit during a conversion will abort the current conversion. The A/D result register pair will NOT be updated with the partially completed A/D conversion sample. That is, the ADRESH:ADRESL registers will continue to contain the value of the last completed conversion (or the last value written to the ADRESH:ADRESL registers). After the A/D conversion is aborted, a 2TAD wait is required before the next

FIGURE 11-3: A/D CONVERSION TAD CYCLES

acquisition is started. After this 2TAD wait, acquisition on the selected channel is automatically started. The GO/DONE bit can then be set to start the conversion.

In Figure 11-3, after the GO bit is set, the first time segment has a minimum of TCY and a maximum of TAD.

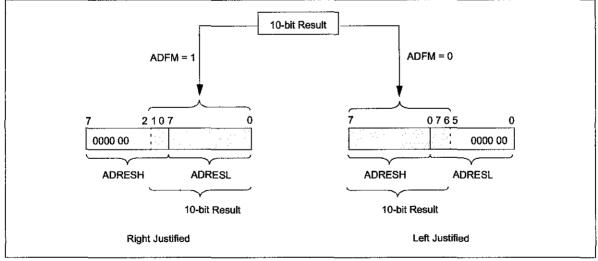
Note: The GO/DONE bit should NOT be set in the same instruction that turns on the A/D.



#### 11.4.1 A/D RESULT REGISTERS

The ADRESH:ADRESL register pair is the location where the 10-bit A/D result is loaded at the completion of the A/D conversion. This register pair is 16-bits wide. The A/D module gives the flexibility to left or right justify the 10-bit result in the 16-bit result register. The A/D Format Select bit (ADFM) controls this justification. Figure 11-4 shows the operation of the A/D result justification. The extra bits are loaded with '0's'. When an A/D result will not overwrite these locations (A/D disable), these registers may be used as two general purpose 8-bit registers.





#### FEATURES

- \* High sensitivity to LPG, iso-butane, propane
- \* Small sensitivity to alcohol, smoke.
- \* Fast response . \* Stable and long life \* Simple drive circuit

#### APPLICATION

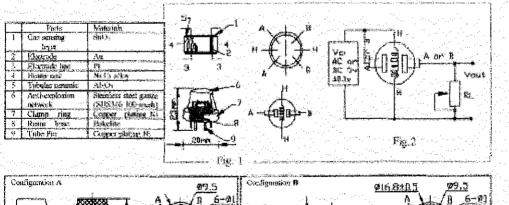
They are used in gas leakage detecting equipments in family and industry, are suitable for detecting of

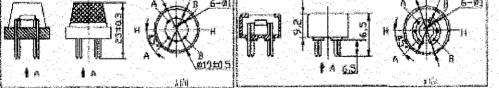
LPCLisa-butane propane, LNG, avoid the noise of alcohol and cooking fumes and cigarette smoke.

#### SPECIFICATIONS

Symbol	Paramuler many	Technical condition	Remarks
Ye	Cursuit visitage	5V40 [	AC OR DC
પ <sub>ંદા</sub>	Heating wohape	SV:001	ACOR DC
_₽ <sub>1.</sub>	Load resistance	20K O	
K <sub>ét</sub>	Henter resistance		Roran Tem
P <sub>R</sub>	Reading consemption	loss than 758mw	
B. En	visosament condition		
Symbol	Paratistics name.	Technical condition	Remarks
Tao	Cong Pen	-16°C-56°C	
anag garana ana ana ang Tagi	Storage Tem	-2070-7070	
Ke	Related humidity	iess than 95% Rb	
Ö,	Окуран солсениятся	21%(standard condition)Oxygen	BUTUTEARE VALUE IS
The party of the start and start shall The		coecceleration can affect sensitivity	over 2%
C Sens	itivity characteristic		
Symbol	Paraneter same	Technical parameter	Rannark 2
Rs	Sensing Registered	10K Q - 608 Q	Delembre exercitization
		(1990ppm LPG)	scopet
ta da ser a se	[1] A. A. M.		209-10000emi

D. Strucyure and configuration, basic measuring circuit

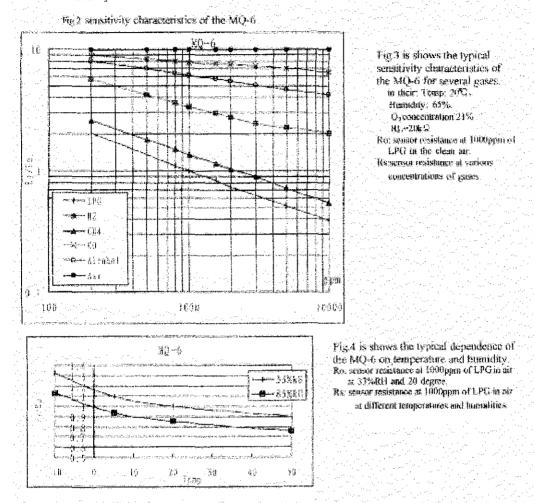




Structure and configuration of MQ-6 gas sensor is shown as Fig. 1 (Configuration A or B), sensor composed by

miere AL2O2 ceramic tube. The Diexide (SoO2) sensitive layer, measuring electrode and heater are fixed into a crust mode by plastic and stainless steel net. The heater provides necessary work conditions for work of sensitive components. The enveloped MQ-6 have 6 pin ,4 of them are used to fetch signals, and other 2 are used for providing heating current.

Electric parameter measurement circuit is shown as Fig.2 E. Sensitivity characteristic curve



#### SENSITVITY ADJUSTMENT

Resistance value of MQ-6 is difference to various kinds and various concentration gases. So, When using this components, sensitivity adjostment is very necessary, we recommend that you calibrate the detector for UKRppin of LPG concentration in air and use value of Load resistance ( R, ) about  $20K\Omega$  ( $10K\Omega$  to  $47K\Omega$ ). When accurately measuring, the proper alarm point for the gas detector should be determined after ecusidering the temperature and humidity influence.

# IGARO

# LPM-2610 - pre-calibrated module for LP Gas

### Features:

- \* Factory calibrated
- \* Temperature compensation circuit
- \* Low power consumption sensor TGS2610
- \* Compact size

The LPM-2610 is a pre-calibrated module for LP gas alarms which is precisely calibrated in Figaro's humidity and temperature controlled facility.

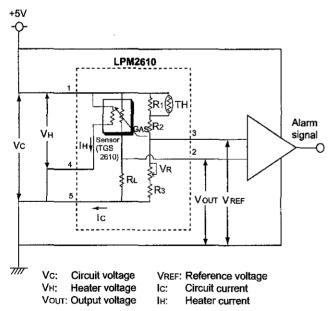
The most important process in manufacturing reliable residential gas alarms is adjusting the alarm point. Calibration is a complicated and time consuming process which also requires a substantial investment in calibration equipment. By eliminating the costly calibration process, this module enables users to easily and simply manufacture residential LP gas alarms. Figaro has taken the complexity out of designing a gas detector circuit by providing users with a temperature compensation circuit which combines a built-in thermistor and individually adjusted load resistor together with Figaro's low power LP gas sensor.

A connector allows easy replacement of the module for the purpose of periodic sensor renewal. This input/output connector enables easy installation of the module into the gas detectors' mother board. This same mother board can be used for both methane and LPG gas detectors by simply changing the module.

This module is designed to meet the performance requirements of BS7348, UNI CEI-70028, EN50194, and UL1484.

Please refer to "Technical Information for TGS2610" for sensor sensitivity characteristics. Refer to "Application Notes for TGS2610" for further information regarding circuit design.

#### **Circuit Diagram**



#### **Basic Pin Connection**

A regulated voltage of 5V DC should be applied to Pin #1. A voltage comparator should be connected to Pins #2 and 3. A circuit for detecting breakage of the heater may be connected to Pin #4 (in which case, Pins #4 and 5 should be connected separately to the GND).

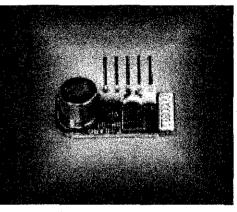
When the gas sensor module is exposed to a concentration of target gas which exceeds the desired alarming point, the value of Vout will reach or exceed the value of VREF, causing the module to reach the alarm condition.

NOTE: As described in Sec. 2-6 of *"Technical Information for TGS2610"*, when energizing the sensor after an unpowered period, the sensor's resistance (Rs) drops sharply for the first few seconds after energizing, regardless of the presence of gases, before recovering to a stable level. This 'initial action' may cause activation of an alarm during the first few moments of energizing since VRL would exceed Vref. To prevent unnecessary alarms during sensor warmup, a circuit modification such as that shown in Sec. 1-7 of *"Application Notes for TGS2610"* should be used.

IMPORTANT NOTE: OPERATING CONDITIONS IN WHICH FIGARO SENSORS ARE USED WILL VARY WITH EACH CUSTOMER'S SPECIFIC APPLICATIONS, FIGARO STRONGLY RECOMMENDS CONSULTING OUR TECHNICAL STAFF BEFORE DEPLOYING FIGARO SENSORS IN YOUR APPLICATION AND, IN PARTICULAR, WHEN CUSTOMER'S TARGET GASES ARE NOT LISTED HEREIN. FIGARO CANNOT ASSUME ANY RESPONSIBILITY FOR ANY USE OF ITS SENSORS IN A PRODUCT OR APPLICATION FOR WHICH SENSOR HAS NOT BEEN SPECIFICALLY TESTED BY FIGARO.

# Applications:

\* Residential LP gas alarm



#### Parts List:

Part	Spec.	Maker	Model #	Qty
Carbon resistor	12kΩ 1/8W	Рапазопіс	ERJ8GEYJ123A	1
Carbon resistor	430Ω 1/8W	Panasonic	ERJ8GEYJ431A	1
Carbon resistor	4.3kΩ 1/8W	Panasonic	ERJ8GEYJ432A	1
Carbon resistor	Var. 1/8W	Panasonic	ERJ8GEYJxxxA	1
Potentiometer	10kΩ 1/5W	Panasonic	EVML1GA00B14	1
Thermistor	10kΩ at 25°C B const.=3400	Mitsubishi Materials	SC20-31103KT	1
Gas Sensor	-	Figaro	TGS2610	1
Connector	-	Nichiatsu	MB5P-90S	1
	Carbon resistor Carbon resistor Carbon resistor Carbon resistor Potentiometer Thermistor Gas Sensor	Carbon resistor    12kΩ    1/8W      Carbon resistor    430Ω    1/8W      Carbon resistor    4.3kΩ    1/8W      Carbon resistor    Var.    1/8W      Carbon resistor    Var.    1/8W      Carbon resistor    Var.    1/8W      Potentiometer    10kΩ    1/5W      Thermistor    10kΩ at 25°C    B const.=3400      Gas Sensor    -	Carbon resistor12k $\Omega$ 1/8WPanasonicCarbon resistor430 $\Omega$ 1/8WPanasonicCarbon resistor4.3k $\Omega$ 1/8WPanasonicCarbon resistorVar. 1/8WPanasonicCarbon resistor10k $\Omega$ 1/5WPanasonicPotentiometer10k $\Omega$ 1/5WPanasonicThermistor10k $\Omega$ at 25°C B const.=3400Mitsubishi MaterialsGas Sensor-Figaro	Carbon resistor12k $\Omega$ 1/8WPanasonicERJ8GEYJ123ACarbon resistor430 $\Omega$ 1/8WPanasonicERJ8GEYJ431ACarbon resistor4.3k $\Omega$ 1/8WPanasonicERJ8GEYJ432ACarbon resistorVar. 1/8WPanasonicERJ8GEYJ432ACarbon resistorVar. 1/8WPanasonicERJ8GEYJ432APotentiometer10k $\Omega$ 1/5WPanasonicEVML1GA00B14Thermistor10k $\Omega$ at 25°C B const=3400Mitsubishi MaterialsSC20-31103KTGas Sensor-FigaroTGS2610

### **Specifications:**

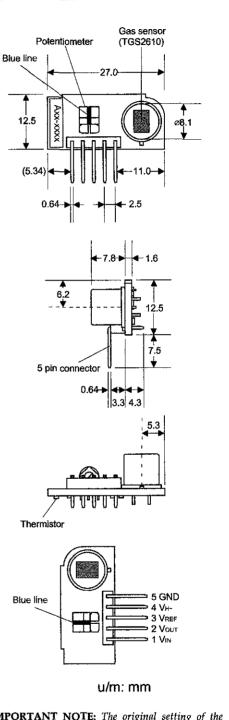
Mc	Module number				
	Test gas conditions	na an an Carlo State ann Chine an Anna	1800±50ppm isobutane in air at 20±2°С, 65±5%RH Vн = 5.0±0.05V DC Vc = 5.0±0.05V DC		
Standard test conditions	Circuit conditions				
	Preheating period pri	or to test	2 days		
Electrical characteristics	Reference voltage	VREF(STD)	Vout(STD) ±0.5V DC		
under standard test conditions	Output voltage	Vout(STD)	2.5±0.5V DC		

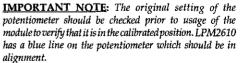
### **Electrical Characteristics:**

	Heater voltage	Ve	5.0±0.2V DC
	Circuit voltage	Vc	5.0±0.2V DC
Recommended	Minimum impedance between Pl	n#2 and GND	2.5140
operating conditions	Minimum impedance between Pi	2.5ΜΩ	
	Operating conditions	0~40°C, 30~95%RH	
	Temperature differential bet and outside detector casing	≤10°C max. (see NOTE)	
e na su gathanan	Heater current (current between Pins.#1 and 4)		56±5mA
Electrical characteristics under operating conditions	Circuit current (current between Pins #1 and 5)	le	10mA (max.)
	Reference voltage	VREF	1.0~4.0V DC
	Output voltage	Vout	0.05~(Vc-0.05)V DC

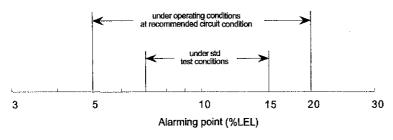
**NOTE:** Due to heat generated by circuit components, if the internal temperature of the detector exceeds the environmental temperture outside the detector casing by 10°C or more, the calibrated alarm concentration would drift due to drifting of Vref. If users are unable to design detectors so as to keep this temperature differential below 10°C, please consult with Figaro.

### **Structure and Dimensions:**





#### **Expected performance:**



Expected performance of LP gas detectors using LPM-2610 and 10% LEL alarming point

**NOTE:** When using LPM2610, typical alarm tolerances for 10%LEL of LP gas such as those shown in the figure above can be expected. However, in actual usage, alarm thresholds may vary since the threshold is also affected by such factors as the tolerances of test conditions and heat generation inside the gas detection enclosure. As a result, Figaro neither expressly nor impliedly warrants the performance shown in this figure. If a large difference between the expected and actual performance of detectors is noticed, please consult with Figaro.

#### **Absolute Maximum Ratings:**

	Circuit voltage Vc	-0.3~+5.5V DC
Absolute	Heater voltage VH	-0.3~+5.5V DC (max. of 2 minutes at 5.5V)
maximum ratings	Operating temperature	-15~+55°C (max. 95%RH)
(see NOTE)	Storage temperature	-20~+60°C (avoid condensation)
	Soldering temperature	260°C (max. in 10 sec.)

**NOTE:** Detectors should be designed according to "Recommended Operating Conditions" as shown above. However, detector circuits should also be designed not to exceed "Absolute Maximum Ratings" under any circumstances. To exceed these ratings may cause damage or deterioration of the sensor.

For applications involving usage of LPM2610 for applications other than residential LP gas alarms, please consult with Figaro.



REV: 03/02