PEDESTRIANS CHARATERISTICS AT TRAFFIC LIGHT SIGNAL INTERSECTION IN IPOH

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by

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CERTIFICATION OF APPROVAL

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A project dissertation submitted to the Civil Engineering Program Universiti Teknologi PETRONAS In partial fulfillment for the requirement of the BACHELOR OF CIVIL ENGINEERING (Hons)

Approved by,

(Assoc. Prof. Dr. Madzlan b Napiah)

UNIVERSITI TEKNOLOGI PETRONAS TRONOH, PERAK JUNE 2006

CERTIFICATION OF ORIGINALITY

This is to certify that I am responsible for the work submitted in this project, that the original work is my own except as specified in the references and acknowledgements, and that the original work contained herein have not been undertaken or done by unspecified sources or persons.

_____ (NOOR AILEEN BT MOHD ADNAN)

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ABSTRACT

Pedestrian crossing is one of the greatest challenges for the traffic and safety engineering communities. Lack of facilities for pedestrian caused fatal accidents involving pedestrians especially at intersections where there is high volume of vehicles. Many major roads in Malaysia are ignoring the facilities for pedestrian to cross the road. Therefore, many pedestrians risk their live to cross the roads even though they knew the danger and risk they have to take. Concerning pedestrian fatality at intersection, nowadays a lot of facilities for pedestrians have been provided in order to increase the safety of pedestrian at signalized intersection. These include the pedestrian crossing lane, traffic system for pedestrians and provided safe place for pedestrian to cross the road. By adding facilities at traffic light signal, the delays for vehicle will be higher and this can caused heavy congestion. On the other hand, if the delays time for pedestrian is high, the possibility of non-compliance pedestrian will increase.

This project studied the characteristic of the pedestrians in term of delays and compliancy at two selected signalized intersections. Traffic survey was conducted to study the performance of the traffic signal with the existence of pedestrian facilities at the two intersections selected. Two types of traffic signal for pedestrians were used namely pushbutton system which located at Jalan Sultan Yusuf and fixed-time system which located at Jalan Dato Onn Jaafar – Jalan Sultan Idris Shah. The performance of the road as well as performance of pedestrian crossing was analyzed using SIDRA software. Finally, recommendations on how to improve the intersection were proposed.

The average walking speed for pedestrian is 1.6 m/s for free-flow walking. The average walking speed is 1.28 m/s and 1.56 m/s for both traffic systems. It can be concluded that the average walking speed at the intersections is quite normal. Non-compliance pedestrians at the intersection are quite low at both sites. For Jalan Sultan Yusuf, the LOS for pedestrian is B while for vehicle is D. For Jalan Dato Onn Jaafar – Jalan Sultan Yusuf the LOS for pedestrian and vehicle is B and D, respectively.

CHAPTER 1 INTRODUCTION

1.1 Background of Project

In designing the traffic light at the intersections, pedestrian's aspect, especially in Malaysia, is given less emphasizes. Most of the intersection, do not consider the safety of the pedestrians. Therefore, the accidents involving pedestrians are very high in Malaysia. Hazardous intersection types for pedestrian crossings include high-volume, high-speed and multilane intersections with complex signal phasing or without any traffic control at all. Pedestrians are at risk even at simple stop sign or yield sign intersections because of the common disregard of traffic control devices by motorists. Pedestrians have not been accorded equal status with vehicles at intersections. Roadways have been designed and constructed primarily to accommodate vehicular traffic rather than pedestrians.

Pedestrians' factor is one of the most important factors in traffic management in transportation accommodation system, especially in the big city, shopping areas and urban areas. Traffic management takes two considerations for pedestrian which are the safety of the pedestrians and the smoothness of the traffic.

Traffic signal control at a junction reduces the conflict between traffic streams. The aim of good traffic signal design is to optimize traffic throughout at the junction whilst addressing the objective of improved highway safety. This includes giving full consideration to the needs and demand for pedestrian flow at the junction. Traffic signals are the most common form of control for important junctions within an urban highway network. The widespread use of traffic signal control can be attributed to a number of factors, including:

(i) Signals make the most effective use of road space where development is intense

- (ii) Signals provide inherent flexibility in coping with variable and changing traffic patterns
- (iii) Signals can be coordinated on an area-wide basis, so as to minimize overall delays through a highway network (known as Urban Traffic Control UTC)
- (iv) Signal junctions are usually safer for pedestrians than other forms of junction control, as positive pedestrian crossing periods can be provided within the signal stage sequence.

Pedestrian crossing lane at the signalized intersection is the most commonly used especially in city center. In general, there are three signs shown for pedestrian crossing signal which are:

- (i) <u>Green light signal with pedestrians walking symbol</u>
 This sign shows that the pedestrians can cross the road safely as the traffic signal for vehicles are red. This green light signal shows the time for pedestrian to move from the curb of road and cross the road. In certain country, the traffic lights are designed to produce a sound for blind people.
- (ii) <u>Green light flashing with pedestrian walking symbol</u>

This also called clearance time for pedestrians. The time designed should make sure pedestrians can cross the road safely.

(iii) <u>Red light with pedestrian waiting symbol</u>
 The symbol represents time the pedestrians are not allowed to cross the road.
 This time is called delay time for pedestrians. This means green light signal for vehicles.

1.2 Problem Statement

Roadways have been designed and constructed primarily to accommodate vehicular traffic rather than pedestrians. Traffic improvements that include widening streets, adding lanes, and using traffic engineering solutions that increase vehicular efficiency can decrease pedestrian safety.

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A high percentage of pedestrians, especially in large urban areas, regularly violate pedestrian traffic control and place themselves at risk of collisions with motor vehicles.¹

About one-third of fatal collisions with pedestrians are the result of pedestrians disobeying intersection traffic control or making dangerous judgments in attempting to cross a street.² Pedestrian traffic control violations generally receive low levels of enforcement.

The design and improvement of roadways often fail to meet the needs of pedestrians of all ages and capabilities for safely crossing intersections, including older persons, young children and those with impaired vision or difficulty in walking. Many intersection reconstruction projects and traffic control installations have increased the distances that one must walk to cross at an intersection. This is quite difficult especially for older people to walk faster at wider lane. Intersection signal timings may be too short to permit safe intersection crossings. Traffic engineers may use a walking speed that is too fast for many pedestrians in determining the necessary time for pedestrians to cross the street. Traffic engineers may assume walking speed for one group not including the children and older people. The speed for younger and healthy people will vary according of group of people.

Crash data consistently show that collisions with pedestrians occur far more often with turning vehicles than with straight-through traffic. Left-turning vehicles are more often involved in pedestrian accidents than right-turning vehicles, partly because drivers are not able to see pedestrians to the left as well.³

Pedestrians involved in crashes are more likely to be killed as vehicle speed increases. The fatality rate for a pedestrian hit by a car at 20 mph is 5 percent. The fatality rate rises to 80 percent when vehicle speed is increased to 40 mph.⁴

Right turn on red (RTOR) contributes to pedestrian crashes because it creates reduced pedestrian opportunities to cross intersections without having to confront turning vehicles.

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Major issues related to pedestrians and signalized intersections include:

- (i) Seemingly arbitrary length of Walk and flashing Don't Walk cycles.
- Pros and cons of lengthening flashing Don't Walk to accommodate slower pedestrians.
- (iii) Safety trade-off of shortened pedestrian phase implemented to enhance vehicular right turns
- (iv) Fairness of laws that allow motorists to enter an intersection on the yellow while prohibiting pedestrians from doing so during flashing Don't Walk.
- (v) Trade-off between motor traffic delays and pedestrian delays at actuated pedestrian crossings.
- (vi) Integrating pedestrian recall and pedestrian actuation in way pedestrians will understand.

In designing and operating intersections that are attentive to the needs of pedestrians, the following considerations should be addressed:

- (i) Minimizing time and distance pedestrians need to cross roadway.
- (ii) Making pedestrian movements more predictable through the use of crosswalks and signalization

1.3 Objective

The main objective of this project is to study the characteristic of pedestrians in term of the speed of pedestrians; pedestrians who obey the traffic signal and the delay time of pedestrians need to wait at the intersection. The level of service for pedestrian as well as foe vehicle will be determined in order to observe the performance of the pedestrian crossing and what the effect of its existence to the level of service for vehicles. If the performance of that intersection is not good, the proposal to improve the level of service and safety at the traffic light signal intersection will be identified.

1.3.1 Scope of Study

The study will involve the following:

(i.) Site survey determination

Site surveys will be selected within Ipoh area. The factors taken into consideration in order to conduct the survey were high volume of pedestrian and high delay time for pedestrians.

(ii.) Data Collection

Pedestrian speed, pedestrian flow rate, pedestrian delays and compliance and noncompliance pedestrians will be determined.

(iii.) Data Analysis

Data collected will be analyzed by using software SIDRA. Results from analysis will determine the LOS for both pedestrians and vehicle movements.

CHAPTER 2 LITERATURE REVIEW

2.1 Introduction

Pedestrian activity can be a major component in urban street capacity analysis, and pedestrian characteristics are an important factor in the design and operation of transportation systems. Concentrated pedestrians movement occurs at public events, in and near transit terminals, high-rise buildings, department stores, theaters, parking garages, and other major traffic generators. The concentration of pedestrian activity at street corners and crosswalks makes them critical traffic links for both sidewalks and street networks. An overloaded corner or crosswalk not only affects pedestrian convenience, but can only delay vehicle turning movements, thereby reducing the capacity of the intersection and connecting street.¹

Speed is an important level-of-service criterion because it can be easily observed and measured. Photographic studies show that pedestrian movement on sidewalks is affected by the presence of other pedestrians, even areas above 40 sq ft/ped. At 60 sq ft/ped, pedestrians have been observed walking in a checkerboard pattern, rather than directly behind or alongside each other. These same observations suggest¹¹ that up to 100 sq ft/ped are required before completely free movement occurs without conflicts, and that at 130 sq ft/ped, individual pedestrians are no longer influenced by others. Bunching or "platooning" does not completely disappear until space is about 500 sq ft/ ped or higher.⁶

Push-button basis

Pelican (pedestrian light controlled) crossings signals remain at green to drivers and red to pedestrians until pedestrian activates a push-button to secure a crossing phase; vehicles must then stop for a red signal, even if there are no pedestrians use the crossing. Figure 1 shows the type push-button system which available in Ipoh.



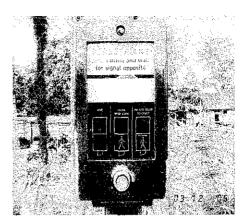


Figure 1: Push-button traffic signalized system

Fixed-time basis

Initially, all pelican signals operated on a fixed-time basis, and then vehicle-actuation was initiated on roads with 85th percentile>56 km/h. The principle of vehicle-actuation means that, following the expiry of a preset minimum green to vehicles, the change to pedestrian priority is initiated when a suitable gap in the vehicular stream is detected or when a vehicle maximum running time expires. A pelican signal has an upper limit on the time that a crossing may be occupied by pedestrians; this reduces the delays to vehicles in locales with high pedestrian flows. Vehicle-actuated pelicans are used at locations with high vehicle approach speeds and/or where there are significant numbers of elderly pedestrians.

2.2 aaSIDRA software

The aaSIDRA or Traffic SIDRA (Signalised & unsignalised Intersection Design and Research Aid) software is for use as an aid for design and evaluation of the following intersection types:

- (i) Signalised intersections (fixed-time / pre-timed and actuated),
- (ii) Roundabouts,
- (iii) Two-way stop sign control,
- (iv) All-way stop sign control, and
- (v) Give-way (yield) sign-control.

aaSIDRA uses detailed analytical traffic models coupled with an iterative approximation method to provide estimates of capacity and performance statistics (delay, queue length, stop rate, etc). Although aaSIDRA is a single intersection analysis package, it can perform traffic signal analysis as an isolated intersection (default) or as a coordinated intersection by specifying platooned arrival data.

aaSIDRA output includes Level of Service (LOS) results based on the concept described in the US Highway Capacity Manual (HCM) and various other publications. The following options are offered for LOS determination:

- (i) Delay (HCM),
- (ii) Degree of saturation,
- (iii) Delay (HCM) and degree of saturation,
- (iv) Delay (RTA NSW),
- (v) ICU method.

2.3 Warrants for Traffic Signals

The Manual on Uniform Traffic Control Devices (MUTCD) specifies eight different warrants that justify the installation of a traffic signal. Traffic signal control should not be implemented if none of the warrants met. As the project is concentrating on the pedestrians, the explanation regarding Pedestrians Warrant is explained in brief.

- (i) Warrant 1: Eight-Hour Vehicular Volume
- (ii) Warrant 2: Four-Hour Vehicular Volume
- (iii) Warrant 3: Peak Hour

(iv) Warrant 4: Pedestrian

- (v) Warrant 5: School Crossing
- (iv) Warrant 6: Coordinated Signal System
- (v) Warrant 7: Crash Experience
- (vi) Warrant 8: Roadway Network

2.3.1 Pedestrian Warrant

The Pedestrian Warrant addresses situations in which the need for signalization is the frequency of vehicle-pedestrian conflicts and the inability of pedestrians to avoid such conflicts due to the volume of traffic present. Signals may be placed under this warrant at mid-block locations, as well as at intersections. If the traffic signal is justified at an intersection by this warrant only, it will usually be at least a semi-actuated signal (a full actuated signal is also a possibility at an isolated intersection) with pedestrian push-button and signal heads for pedestrians crossing the major street.

The Pedestrian Signal Warrant shall not be applied at locations where the distance to the nearest traffic control signal along the major street is less than 300ft, unless the proposed traffic control signal will not restrict the progressive movement of traffic. The criterion for pedestrian volume crossing the major roadway may be reduced as much as 50% if the average crossing speed of pedestrians is less than 4ft/s. If a traffic control signal is justified by both this signal warrant and a traffic engineering study, the traffic control signal shall be equipped with pedestrian signal heads conforming to requirements set forth.⁸

Pedestrian analysis uses some familiar terms, as well as others not used elsewhere in the manual. The pedestrian capacity terminologies used in this report are as followed:

- (i) Pedestrian speed is the average pedestrian walking speed, generally expressed in units of meter per second
- (ii) Pedestrian flow rate is the number of pedestrians passing a point per unit time, expressed as pedestrians per 15 minutes or pedestrians per minute; 'point' is referred to a perpendicular line of sight across the width of a walkway.
- (iii) Unit width flow is the average flow of pedestrians per unit of effective walkway width, expressed as pedestrians per minutes per meter.
- (iv) Platoon refers to number of pedestrians walking together in a group
- (v) Pedestrian density is the average number of pedestrians per unit or area within a walkway or queuing area, expressed as pedestrians per square meter.

- (vi) Pedestrians speed is the average area provided for each pedestrian in a walkway or queuing area, expressed in terms of square meter per pedestrians.
- (vii) Pedestrian delay is the time the pedestrian has to wait at the curb when the traffic signalized crossing is red.
- (viii) Compliance is the pedestrian which is obey the traffic light and cross only when the traffic signal for pedestrian crossing turns green.
- (ix) Non-compliance is pedestrian who does not obey the traffic light for pedestrians.Pedestrians who cross road when the traffic light is red.

2.4 Characteristic of Pedestrian

2.4.1 Pedestrian Walking Speed

Speed is an important design element that will determine sufficient time require for crossing manoeuvre before traffic begins to move. This is an aspect which requires careful local study if the best solution is to be provided, and is likely to be both time-of-day and area dependent. Some researches into road crossing speeds have indicated an average value in the range of 1.2 m/s to 1.35 m/s at busy crossings with a mix of pedestrian age groups. Average walking speeds approximating to the free-flow walking speeds in pedestrians concourses of 1.6 m/s can be expected.

Pedestrian speed is measured by dividing the length of the cross lane with time traveled by the pedestrian. This is an important element to determine the minimum flash time so that the last pedestrian can cross the road safely with minimum delay time for the vehicles.

Quantifying Pedestrian Walk Times

A lot of researches have been conducted regarding pedestrian's speed. Manual Uniform Traffic Control Devices (MUTCD, 1988), proposes the speed for pedestrian is between 0.76 - 1.83 m/s. The average walking speed is 1.3 meter per second (m/s) for men and 1.1 meter per second (m/s) for women. A half-mile walk at this rate would take 10 minutes without stopping.⁸ A pedestrian walking for this distance across typical block

lengths of one-eighth mile must cross four streets. If streets are narrow, traffic volume is light, and all intersections have four-way stops at which every vehicle yields the right-ofway to pedestrians, a person walking would experience a minimum of delay. There would still be some delay to look both ways before crossing to see if the street was clear. Table 1 and Table 2 shows average delays for a variety of signal cycle lengths and pedestrian green phases.

Cycle length	Green phase for	pedestrians	Average delay
(seconds)	(seconds)		(seconds)
60	15	aya ta ar ina kata data di kata na kata data data data data data data dat	17.25
60	10	al fan 'n de bernel werne dat dat in dit her dit her de bernet. 1 1 1 1	21.25
90	15	an na heral e stan na na heral na heral 1	31.67
90	10	ina ang mang mang nang pinang nang mang mang mang mang mang mang	36.00
120	15	19 10 19 10 10 10 10 10 10 10 10 10 10 10 10 10	46.375
120	10	ni ni manani na mana Manani	50.875

Table 1: Average Pedestrian Delays at Traffic Signals

2.4.1 Motor Vehicle Delay

The Institute of Transportation Engineers (ITE) has calculated vehicle delays at signalized intersections and found that "when capacity is below about 75 percent of maximum flow, the green phases and cycle length have the most pronounced effect on average delay. The calculations assume a saturation flow of 1.11 vehicles per second (veh/sec) (4,000 veh/hr) and an approach flow of 0.264 veh/sec (950 veh/hr)." Table 3 shows the average delay increase for vehicle traffic as the green phase is reduced.⁹

Cycle length	Green phase for pedestrians	Average delay (seconds)
(seconds)	(seconds)	كالمحيطة أحجاجه ومحالم ومكلما خالفي وأكاب ووالتي وراكب وكأمر وواكب والزور
60	15	52.12
60	20	19.07
60	.25	14.21
60	30	10.44
60	en en la contra cont 135 	7.29
90	25	36.27
90	35	22.86
90	45	15.33
90	55	9.34
90	65	4.85
120	35	42.47
120	45	31.50
120	55	23.69
120	65	17.03
120	75	11.46

Table 2: Average Motor Vehicle Delays at Traffic Signals

2.4.2 Walking distances

Walking distance is an important design aspect, since the shorter the distance, the higher the probability that it will be made on foot. Pedestrians tend to use the crossing lane at traffic signalized intersection when the flow of vehicle is too heavy. It is dangerous to cross at the busy intersection, though.

2.4.3 Non-Compliance (Pedestrians did not followed the rule before crossing the road)

Pedestrians tend to take the least energy route (the shortest distance and the flattest path) between two points. They tend to cross road with the most convenient locations rather than at designated crossings. According to American Association of State Highway and Transportation Officials (AASHTO) roadway design policy $(2001)^{10}$, pedestrians usually do not walk over 1 mile to work or over 0.5 mile to transit stop. About 80 percent of the distances traveled by pedestrian will be less than 0.5 mile. When the delay time for the

pedestrian is too high, the pedestrians tend to cross the road without using the crossing lane provided. They tend to cross the road when the volume of vehicle is lessened. Figure 2 illustrates a common non-compliance scenario.



Figure 2: Non-compliance pedestrian

2.5 Level of Service

The Level of Service (LOS) expresses the performance of a highway at traffic volumes less than capacity. LOS for class I highway (project site) is based on two measures which is Percent Time Spent Following (PTSF) and the Average Travel Speed (ATS). At an operational level of analysis, LOS is determined based on existing or future traffic conditions and specific roadway characteristics. Level of service (LOS) is a quality measure, generally in terms of such service measures as speed and travel time, freedom to maneuver, traffic interruptions, comfort and convenience. A given LOS (A, B, C, D, E, and F) comprises or describes a range of conditions or values always given from the perspective of the facility user.

2.5.1 Level of Service (for vehicle)

The Level of Service (LOS) expresses the performance of a highway at traffic volumes less than capacity.

	Control delay per vehicle in seconds (6) (including geometric delay)	
Level of Service	Signals and Roundabouts	Stop Signs and Give-Way (Yielo) Signs
A	d≤10	ci≤10
9	10 < d ≤ 20	10 ≤ d ≤ 15
C	2C < d ≤ 35	15 < d ≤ 25
<u>-</u>	35 < d ≤ 55	25 ≪ d ≤ 35
Ε	55 ≤ d ≤ 60	35 ≪ d ≤ 50
Ŧ	80 < d	50 < d

Table 3: Level-of-service definitions for VEHICLES

2.5 Level of Service (for pedestrians)

The definitions for pedestrian LOS are given in Table 4 while Table 5 gives the description of the definitions.

Table 4: Pedestrian level-of-service on walkway

Level of service	Space (sq ft /	Exp	ected flows and sp	nd speeds	
	ped)	Ave. speed (ft/min)	Flow rate (ped/min/ft)	Vol/cap ratio	
A	≥130	≥260	≤2	≤0.08	
B	≥40	≥250	≤7	≤0.28	
C	≥24	≥240	≤10	≤0.40	
D	≥15	≥225	≤15	≤0.60	
E	≥6	≥150	≤25	≤1.00	
F	<6	<150	Var	iable	

Table 5: Description of Level of Service

Level of service	Description		
Α	Pedestrians move in desired paths without altering their movements in response to other pedestrians. Walking speeds are freely selected, and conflicts between pedestrians are likely		
В	Sufficient area is provided to allow pedestrians to freely select walking speeds, to bypass other pedestrians, and to avoid crossing conflicts with others. At this level, pedestrians begin to be aware of other pedestrians, and to respond to their presence in the selection of walking path.		
С	Sufficient space is available to select normal walking speeds, and to bypass other pedestrians in primarily unidirectional streams. Where reverse direction or crossing movement exist, minor conflicts will occur, and speeds and volume will be somewhat lower.		
D	Freedom to select individual walking speed and to bypass other pedestrian is restricted. Where crossing or reverse-flow movements exist, the probability of conflict is high, and its avoidance requires frequent changes in speed and position.		
E	Virtually all pedestrians would have their normal walking speed restricted, requiring frequent adjustment of gait. Insufficient space is provided for passing of slower pedestrians. Cross or reverse-flow movements are possible only with extreme difficulties. Design volume approaches the limit of walkway capacity, with resulting stoppages and interruptions of flow.		
F	All walking speeds are severely restricted, and forward progress is made only by shuffling. There is frequent, unavoidable contact with other pedestrians. Cross and reverse-flow movements are virtually impossible. Space is more characteristic of queued pedestrians than of moving pedestrian's stream.		

2.6 Facilities for Pedestrians

Pedestrians may sometimes need an exclusive signal stage. The following warrant for the exclusive signal stage

- (i) The pedestrian flow across any one arm is 300 pedestrians per hour or more
- (ii) The turning traffic into any arm has an average headway of less than 5 seconds during its green time and is conflicting with a flow of more than 50 pedestrians per hour
- (iii) There are special circumstances such as significant numbers of elderly, infirm or disabled pedestrians.

CHAPTER 3 METHODOLOGY

3.1 Introduction

The pre sampling data collections were determined according to two locations selected; Location 1 is at Jalan Sultan Yusuf which uses push-button system and Location 2 at Jalan Sultan Iskandar Shah which uses fixed-time system. The locations were selected based on high volume of vehicles use the road and pedestrians crossing the road.

3.2 Reconnaissance Survey

Cameras are set up at the site location identified. The duration for the survey is estimated to be 2 to 3 hours. The most suitable time to conduct the survey is during the peak hour as this time many pedestrians will be using the crossing lane.

A few site surveys had been examined in order to choose the suitable location for the survey. Locations selected should fulfill the important factors such as:

- (i) High volume of vehiclesThe site surveys selected are among the busy road within Ipoh area.
- (ii) High delay time for pedestrian
 The pedestrians have to wait for a long time to cross to road where the vehicles volume is high. This is referring to fixed time traffic light control system.
- (iii) High volume of pedestrians
 Usually the pedestrians will be using the crossing lane when the road is
 busy. The site surveys are selected based on high volume of the
 pedestrians using the crossing lane.

After visiting a few locations, two locations have been selected to conduct the surveys based on criteria mentioned above. First location is Jalan Sultan Yusuf which operated under push-button system and second location is at Jalan Sultan Dato Onn Jaafar – Jalan Sultan Idris Shah operated under fixed-time system. The suitable time for conducting survey was observed to be from 8 to 11 am on Jalan Sultan Iskandar Shah and from 12 to 3 pm on Jalan Sultan Yusuf.

3.2.1 Location 1: Jalan Sultan Yusuf

2 cameras were set up for the directions; to observe the volume of the vehicles and to collect data for pedestrian crossing. To estimate data using SIDRA, the volume for pedestrians as well as vehicles must be collected at all direction. But, the pedestrian characteristic only focused at one traffic signal only which is next to BCB building. Figure 3 shows a schematic layout at Location 1 while Figure 4 pictures the said location.

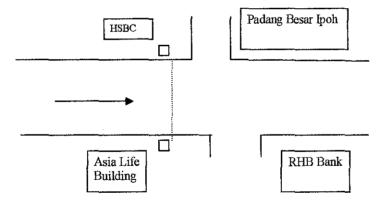


Figure 3: Location 1

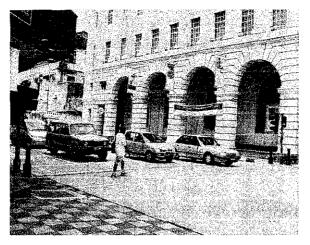


Figure 4: Pedestrian Crossing at Jalan Sultan Yusuf

3.2.2 Location 2: Jalan Dato Onn Jaafar - Jalan Sultan Idris Shah

Data along Jalan Sultan Iskandar Shah can only be collected during morning time and the author did the site survey at 8.00 am till 11.00 am. The time is chosen as during lunch hour the traffic will be taken control by traffic police. This is to avoid heavy congestion along the road as many workers from nearby working areas will be out during lunch hour. During 3-hours of observation, many pedestrians were seen using the crossing lane to get to the other side of road. The location selected is a good place to do the survey as it is located near wet market, shopping area and near office area.

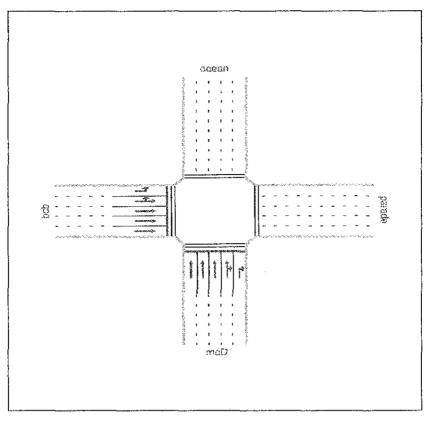


Figure 5: Location 2

The survey can only be conducted during non-peak hour time as at 1pm - 2pm and at 5pm - 6pm the traffic will be taken control by police. This is due to heavy congestion at the main roads within Ipoh city center during this hour. Figure 5 shows schematic layout at Location 2.

The characteristic and physical layout at both location are given in Table 6.

Detail	Location 1	Location 2
Type of traffic signal	Push-button	Fixed time
Road length (m)	14.3	15.7
No. of lane	5	5
Flashing time (sec)	11.0	9.0

Table 6: Geometrical Data on both site surveys

3.3 Video surveys

Video recorders were used to take the pedestrian movement, together with their interaction with vehicles during periods of observation. The delays and behavior patterns are recorded such as reluctance of an elderly person to cross the road. The pedestrians crossing difficulties will be analyzed. Cameras are set up at the selected sites and video recordings taken of the pedestrian movement, together with vehicles where appropriate, during the selected observation periods.

3.4 Manual count

Manual counts are concerned with counting the flow of pedestrians through a junction, across a road, or along section. Because it is important to determine conflicts with motor vehicles, vehicles counts are normally carried out at the same time. The time period in the day over which the counts are undertaken must coincide with the peak times of the activity of study. The day of the week made must be representative of the demand. School holidays, early closing, and special events should be avoided.

3.5 Data Collection

The data collection for both site study were done during the weekdays because during this daytime, many pedestrians are staff working at site study area use the pedestrian lane to cross the roads.

3.5.1 Location 1: Jalan Sultan Yusuf

Pedestrian crossing lane at Jalan Sultan Yusuf located in between of Asia Life building, RHB Bank and HSBC Bank. This location is one of the main roads in Ipoh and many pedestrians use this lane to cross the road especially during weekdays. This crossing lane used push-button basis which the button must be pushed first and the pedestrians have to wait until the green light signal for pedestrians before crossing the road. The pre-sampling data collection was conducted on 13th of October 2005 from 12.00 pm till 3.00 pm. The target to get the maximum volume of pedestrians is during the peak hour, the time when most of pedestrians will be using the road. The location for the push-button system is chosen based on a few criteria including:

- Pedestrian displays and push buttons are required at all signalized intersections unless the pedestrian movement is prohibited.
- (ii) Crosswalks should be located as close as possible to the intersection.
- (iii) Push buttons shall not be placed more than 5 feet from the normal path of the pedestrian, and no more than 15 feet from the center point at the end of the associated crosswalk.
- (iv) Special consideration should be given to people with disabilities when locating the push buttons. When the push button is installed on a vehicle signal standard, a paved path at least 4-feet wide from the shoulder or sidewalk to the standard shall be provided
- (v) If installed behind a guardrail, pedestrian push button posts should not be greater than 1.5 feet from the face of the guardrail.

3.5.2 Location 2: Jalan Dato Onn Jaafar – Jalan Sultan Idris Shah

On 29th September 2005, traffic survey was conducted at Jalan Sultan Iskandar Shah to collect the data needed for the fixed time traffic system. The location is selected based on the following factors:

- (i) Traffic controlled signal is a fixed-time basis
- Undivided five-lane road with uniform width (and similar width between sites).
 Different pedestrian behaviour is expected at signalized crossing on divided roads due to some pedestrians stopping in the median area or due to the use of staged crossing.
- (iii) Sufficient pedestrian flow. A balance judgment was applied between flows too high or too low to ensure the integrity of the data was maintained. Excess flows would overwhelm the surveyor causing data to be missed. On the other hand,

flows that are very low could have the reverse effect of the observers being underworked and becoming distracted.

(iv) Surveys were conducted at pedestrian actuated mid-block signalized crossings.
 Such crossings are usually located where high pedestrian activity is concentrated along short sections of road carrying high traffic volumes.

2 cameras were set up for the directions; to observe the volume of the vehicles and to collect data for pedestrian crossing. The survey was conducted at 1200 pm which was peak hour time. Unfortunately, during 15 minutes of observation, the traffic was taken control by traffic police. Therefore, the survey had to stop

The author did a second observation at Jalan Sultan Iskandar Shah on 6th October. This time, the author used only 1 camera as the crossing lane is concentrated only from one direction. The time taken was at 8-11a.m.

For data collection in the laboratory, the video taken at the site surveys were observed to gather data for pedestrians as well as vehicles. The data were collected as mentioned below:

- (i) Time taken for pedestrian to cross the road during green phase
- (ii) Volume of compliance and non-compliance pedestrians
- (iii) Capacity of vehicle along the roads

A few problems had occurred during the collection of the data such as:

- (i) A lot of pedestrians tend to wait at the corner of the building or far from the curb of the road. As the camera must focus on the pedestrians' traffic signal and at the same time focus at the road, the pedestrian movement could not be captured and the data collection for delay time is difficult to collect.
- (ii) The cameras itself must be located at sheltered location as it was a rainy day.

- (iii) Some of pedestrian preferred not to use the lane of crossing but cross the road in between the vehicles when the vehicles stopped at the red light. This is quite difficult to capture as the cameras were only limited at certain angel only.
- (iv) Only one camera was available at one junction and it was difficult to capture all the characteristic of pedestrians at the junction.
- (v) Two cameras were used to capture for four pedestrian crossings at Jalan Dato Onn Jaafar – Jalan Sultan Idris Shah. The cameras must be set up at the same time to get the same data for vehicles data collection.

3.6 Data processing and Discussion

The data which have been measured at the site locations or at the laboratory were processed by using Microsoft Excel as attached in Appendix A. Graphs show the characteristic of pedestrian while crossing the push-button basis and fixed-time basis.

3.7 Level of Service Recommendation

Based on the result from delay time for pedestrian and vehicle and speed of the pedestrian crossing the road, the LOS recommendation at location 1 and 2 will be discussed. Geometry factors involved are minimum green time for pedestrian, cycle time, setting of fixed time system and length of pedestrian crossing lane.

CHAPTER 4 RESULT AND DISCUSSION

4.1 Introduction

Collection of pedestrian data using the crossing lane at traffic signalized system can be determined after all the data have been analyzed whether at the site locations or at the laboratory. These include the delay time of the vehicle, delay time for pedestrian and speed of the pedestrian while crossing the roads.

4.2 Data Collected from site Surveys

The traffic operation at both crossing lane are different from one another. Therefore, signal phasing at both locations are different. Table 7 shows the pedestrian signal phasing from location 1 and Location 2.

Location	1	2
Туре	Push-Button	Fixed-time
Minimum Green time for pedestrian (sec)	6	50
Minimum green time for vehicle (sec)	25	35
Flash time (sec)	12	8
All red (sec)	2	2

Table 7: Pedestrian Signal Phasing

4.3 Delay time for vehicle

The delay time for pedestrian at location 1 which is at Jalan Sultan Yusuf is low compared to Location 2. This is due to difference of red phase between the two locations. At location 1, the delay time for vehicle is 20 seconds only when a pedestrian had pushed the button and the vehicles have to give way to pedestrians to cross the road. but, for location 2, the red phase is 50 seconds in which the vehicles have to give way to pedestrians to cross as well as vehicles from the another approach way. Table 8 shows delay time at both locations.

Location	1	2
Туре	Push-button	Fixed-time
Time of survey	9 - 10am	1 – 2 pm
Delay Max	20	50

Table 8: Delay Time for both locations

4.4 Delay time for pedestrian

High delay time for pedestrian at any intersection will make the pedestrian became inpatient and cross the road without waiting for pedestrian crossing signal changed to green. This is one of the factors many crashes involved pedestrian at the intersection. To avoid this, the delay time must be reduced to the minimal point.

In this survey, pedestrians' delay time is time that pedestrians have to wait while waiting at the curb until the pedestrian had entered the crossing lane. The data collected did not include for non-compliance pedestrians. This survey is done assuming the delay time was not interrupted by other factors.

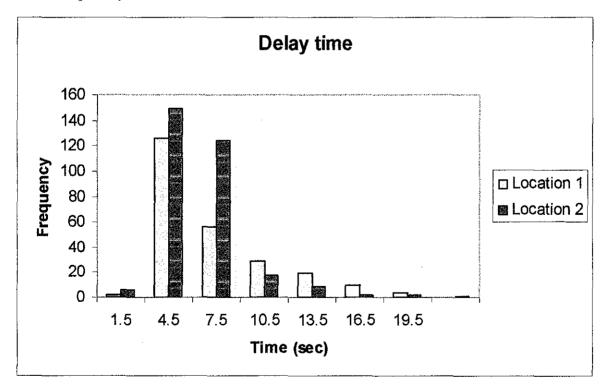


Figure 6: Delay time for location 1 and 2

Figure 6 shows the delay time for both locations. From the graph, it obviously shows that the high percentage of delay time for both locations is below 6.0 seconds. Location 1 which is operated under push-button system shows that high delay time compared to Location 2 which operated under fixed-time system. Waiting time in 5 - 6 seconds is considered normal according to Highway Capacity Manual, TRB 1994.

Pedestrians at Location 1 have to wait longer at the crossing traffic signal as compared to Location 2. Even though the pedestrian had pushed the button, but as the system gave the priority to vehicle, the pedestrians have to wait. This is due to different traffic operation

4.5 Compliance and Non-compliance

There are some of the pedestrian who are not patient and could not wait until the traffic crossing signal turns green. This is one of the common problems faced at the intersection. This is very dangerous and risky for these kinds of pedestrians. Compliance pedestrian is pedestrian which is obeyed and only cross the road when the signal turns green, whilst non-compliance pedestrian is pedestrian who did not obeyed and cross the road when there are no vehicle even though the traffic crossing signal is red. Table 9 gives the percentage of compliance and non compliance at both locations.

Location	1	2
Time of survey	9-10am	1-2pm
Compliance (%)	93.5	96.9
Non-compliance (%)	6.5	2.1
Total Pedestrian	263	320

Table 9: Compliance and Non-compliance

It shows that pedestrian at location 1 tend to cross the road without waiting for the traffic signal. This is because the delay time at this location is higher compared to location 2. The push-button system gives priority to the vehicles. Long cycle time cat this location caused an wider gap between the vehicles which means the pedestrians can cross the road when there is sufficient gap.

4.6 Crossing time

In designing pedestrian crossing traffic signal, the time taken for the pedestrian to safely cross the road must be sufficient. Crossing time is time taken by a pedestrian to cross the road at crossing lane provided under traffic light signal system. In this study, the consideration for crossing time is when the pedestrian step into the crossing lane till he/she left the lane completely. The data is obtained based on video captured during the survey time and a re shown in Table 10. Meanwhile, the profile of pedestrian crossing time at both locations is shown in Figure 7.

Location	1	2
Type system	Push-button	Fixed-time
Time of study	1 – 2 pm	9 – 10 am
Lane width (m)	14.3	15.7
Average crossing time (sec)	9.06	10.49
Minimum crossing time (sec)	3.7	5.0
Maximum crossing time (sec)	16.8	19.7

Table 10: Pedestrian Crossing time

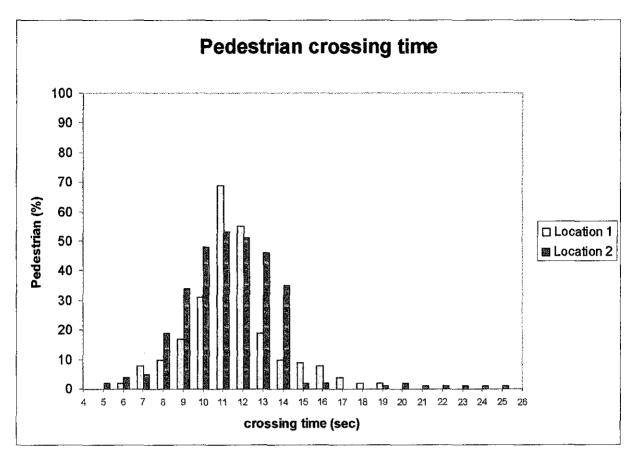


Figure 7: Comparison of crossing time

4.7 Pedestrian speed

Pedestrian speed is one of an important element for designing traffic system for pedestrians. This will ensure all the pedestrians cross the road safely when flashing time occurred. In this survey, the speed of pedestrian is determined by dividing the width of the road with time taken for pedestrian crossing the road. Table 11 shows the summary of pedestrian for both locations.

Table 11: Speed of pedestrian

Location	1	2			
Type of traffic signal	Push-button	Fixed-time			
Minimum speed (m/s)	0.86	0.8			
Maximum speed (m/s)	3.86	3.14			
Average Speed	1.28	1,56			
Total pedestrian	246	310			

Detailed results for speed of pedestrians for location 1 and 2 are attached in Appendix A and Appendix B.

CHAPTER 5 JUNCTION ANALYSIS

5.1 Introduction

Data analysis can also be determined by using aaSIDRA software to determine the level of service (LOS) for vehicles as well as pedestrians. In this part, the aaSIDRA analysis is used to analyze the efficiency of crossing traffic signal at two locations selected. To achieve the objective, the analyses of data at both locations were analyzed. Data obtained such as pedestrian and vehicle volume and also the geometrical characteristic of the traffic during the site survey will be used in this software.

5.2 Location 1

Location 1 is located at Jalan Sultan Yusuf which uses the push-button system for pedestrians. Table 12 below shows the LOS for pedestrian and vehicle. From the result below, LOS is B for the pedestrian crossing signal at Jalan Sultan Yusuf is good for both pedestrians and vehicles. The average delay for pedestrian is slightly higher compared with average delay for vehicle. This is because; the push-button system gives priority to vehicles. Therefore, the delays for pedestrians are expected to be higher.

کا نتایا اشد نشار سو بیس بیس	io (g/C) 1 (2nd	Flow (veh (Cap. veh	of I Satn	Delay	LOS
West: HSBC						
11 T 0.438*		-	4206	0.672*	* 12.4	В
				0.672	12.4	В
Pedestrians 53 (Ped) 0.125*		259	1500	0.173	 18.9	В
		259	1500	0.173	18.9	В
ALL VEHICLES:				0.672		В
INTERSECTION	(persons):					

Table S.15 - CAPACITY AND LEVEL OF SERVICE

Table 12: Data analyzed at Location 1

Based on the Table 12, the LOS for pedestrian crossing within one hour total flow period was LOS B. Meanwhile, for the vehicles flow, the LOS was found to be LOS B. In most of straight route, the LOS for vehicle should be LOS A as there is no other junction interfere with traffic light system and caused delay. But, in this case, even when it is a straight road, the LOS is low. This is due to the heavy traffic flow during the survey as the author chose peak hour time to do the survey. The LOS for pedestrians is quite low as the total volume of pedestrian crossing the road was quite high during the survey. This is because, most of pedestrians have to used the crossing lane to cross the road as the volume of vehicle is increasing especially during the peak hour time. Plus, the location of the road is situated between office areas. Therefore, during lunch hour most of people went out to get lunch.

Detailed results for location 1 are attached in Appendix A.

5.3 Location 2

Location 2 is pedestrian crossing traffic signal which operates under fixed time system which is located at Jalan Dato Onn Jaafar – Jalan Sultan Idris Shah. Table 12 shows the data analyzed at the location.

	Green Time Ratio (g/C) 1st 2nd grn grn	Flow (veh	Cap. (veh	of D	Delay	LOS
South: mcD						
2 T	0.213*					D
3 R	0.213	535	622	0.860*	50.2	D
		1731	2012	0.860	43.8	D
West: bcb				<u>₩₩</u> ₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩		
10 L	0.363	553	664	0.833	40.7	D
11 T	0.363*	2324	2788	0.834	30.7	С
		2877	3452	0.834	32.6	С
Pedestrians					-	
51 (Ped)	0.075*	328	900	0.364	34.2	D
53 (Ped) ().075	151	900	0.168	34.2	D
55 (Ped) (0.075	142	900	0.158	34.2	D
57 (Ped) (0.075	326	5 900	0.362	34.2	2 D
-		947	7 3600	0.364	34	1.2 D
ALL VEHI	CLES:	46	08 54	63 0.8	- 60 30	5.8 D
INTERSEC	TION (persons)): 78	59 54	63 0.8	- 60 3	6.5

Table S.15 - CAPACITY AND LEVEL OF SERVICE

Table 13: Data analyzed at Location 2

It can be observed that the LOS for pedestrian and vehicle at all approaches are mostly LOS D. This is because the high average delays for pedestrian 34.2 sec and 40 - 50 seconds for vehicle from all approaches.

For location 2, the main focus of this survey is to study the pedestrian characteristic at one intersection only. But, as aaSIDRA software requirement is to calculate the LOS for that particular road, the data for all junctions must be collected. From what the author could observe, there is non-stop moving vehicle along this road as it is one of the main roads in Ipoh. It is became heavier traffic during lunch hour and when people started to leave the office to go home. It is not awkward if the LOS for pedestrians is low for most of the time.

Detailed results for location 2 are attached in Appendix B

CHAPTER 6 CONCLUSIONS AND RECOMMENDATIONS

6.1 Conclusions

According to Manual Uniform Traffic Control Devices the proposed average speed for pedestrian is 0.76 - 1.83 m/s. But, based on the result the average speed for location 1 and 2 is 1.28 m/s and 1.56 m/s which means the average speed at the site location is normal. Although the pedestrians were from different group of age, but still the average speed is not too fast or too slow.

Based on Table 1, the average delay for 60 seconds cycle length is 17.25 - 21.25 seconds. However, according to the survey the average delay is 20 seconds for push-button system and 50 seconds for fixed time.

A good level of service for traffic signal for pedestrians is when it can minimize the delay time for pedestrians and also for vehicles, guarantee the safety of pedestrians while crossing the road and provide sufficient area for the pedestrian to cross the road.

From the data collected, it can be concluded that level of service B at Jalan Sultan Yusuf achieved the best performance compared with LOS at Jalan Sultan Idris Shah which is LOS D for all approaches. Jalan Sultan Idris Shah uses fixed-time basis which is difficult to amend as it must consider geometrical condition as well as capacity of pedestrians and vehicles. The volume for vehicles and pedestrians can not be expected to be the same for every day but the locations were selected based on the assumption that locations of the site surveys will be high in both volumes. For location 1, the LOS for vehicle's users achieved good LOS. The volume of vehicle uses the road are less than the design capacity, while for the pedestrian minor conflict might occur as it was LOS B.

For location 2, the LOS for vehicle to go straight is LOS C that means it is not very smooth traffic while for pedestrians the LOS is D which means the high delay for pedestrians to cross the road.

The minimum green time at location 1 is 6 seconds and the flashing time is 12 seconds. Even though the flashing time is longer but this makes many pedestrians uneasy when they are unsure whether or not they will have enough time to finish crossing before the traffic pattern changes. Sometimes, they got panic and run when the flashing green phase appeared. Therefore, installation of traffic signal with countdown phase is practical to ensure the safety of the pedestrians and to increase the confidence of the pedestrians to cross the road even though the green light is flashing.

6.2 Recommendations

The width of the lane should be wide enough to provide sufficient space to accommodate pedestrians from both directions. This is to avoid conflict between pedestrian and to reduce delay while in moving queue. In this survey, the width of the lane is 2 meter for both locations. The small width area caused many pedestrians chose not to walk within the lane. They prefer to walk outside the white line when crossing.

When green phase for pedestrian occurred, all the pedestrian will use the lane to cross. The capacities of the pedestrians are high during this time. Generally, two pedestrians who came from opposite direction needs 0.76 meter which means for two meters crossing lane, only 2 to 3 persons can walk simultaneously on the crossing lane. Based on Highway Capacity Manual, TRB 1994, the rule for designing lane width is 2 meter for minor road and 4 meter for major road. Both pedestrian lanes are located at major road with 5 lanes of roads. Therefore, the lane should be widening to 4 meter⁶.

On very wide intersections that require a long time to finish crossing, the flashing hand phase must be very long in duration, e.g. thirty seconds or more. Pedestrian countdown displays are experimental traffic control devices designed to inform pedestrians how many seconds they have left to finish crossing the street. The purpose of informing pedestrians of the remaining time is to keep pedestrians from panicking when they are on time while encouraging late pedestrians to hurry. At intersections with countdown timers, fewer pedestrians already in the intersection start run at the start of the flashing hand, but the number of pedestrians starting to cross after the flashing hand begins actually increases slightly over normal intersections. The countdown timers may make these late-crossing pedestrians more confident that they can make it across in time if they hurry.

This survey is an interesting topic for further studies. The author did the survey at oneway intersection only. It is recommended to do analysis on two-way traffic signalized system to observe the characteristic of pedestrian and to analyze the performance of that selected road. Jalan Sultan Idris Shah which located in front of the Maybank building is one of the examples which can be used as study area.

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APPENDIX A

LOCATION 1 JALAN SULTAN YUSUF

- Pedestrian Data
- Traffic Data
- Data using SIDRA software

PEDESTRIAN DATA

Location : Jalan Sultan Yusuf

Pedestrian crossing system: Push-button system

Road length: 14.3 m

Green time: 6 seconds

Flashing time: 11 seconds

Time of survey: 1300 - 1400

	Class		Percentage		
Class (sec)	midvalue	Frequency	frequency	Cumulative of frequency	Cumulative percentage of frequency
0	0	0	0	0	0
2.5 - 3.5	3	0	0	0	0
3.5 - 4.5	4	2	0.81	2	0.81
4.5 - 5.5	5	8	3.25	10	4.07
5.5 - 6.5	6	10	4.07	20	8.13
6.5 - 7.5	7	17	6.91	37	15.04
7.5 - 8.5	8	31	12.60	68	27.64
8.5 - 9.5	9	69	28.05	137	55.69
9.5 - 10.5	10	55	22.36	192	78.05
10.5 - 11.5	11	19	7.72	211	85.77
11.5 - 12.5	12	10	4.07	221	89.84
12.5 -13.5	13	9	3.66	230	93.50
13.5 - 14.5	14	8	3.25	238	96.75
14.5 - 15.5	15	4	1.63	242	98.37
15.5 - 16,5	16	2	0.81	244	99.19
16.5 - 17.5	17	2	0.81	246	100.00
<u></u>	<u></u>	246	100.00		

Table 1: Pedestrian crossing time

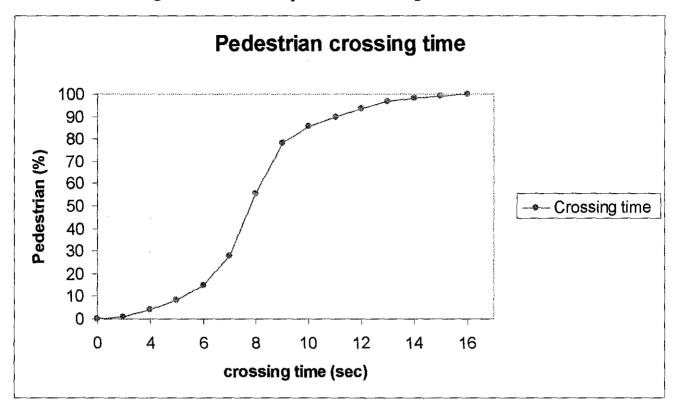
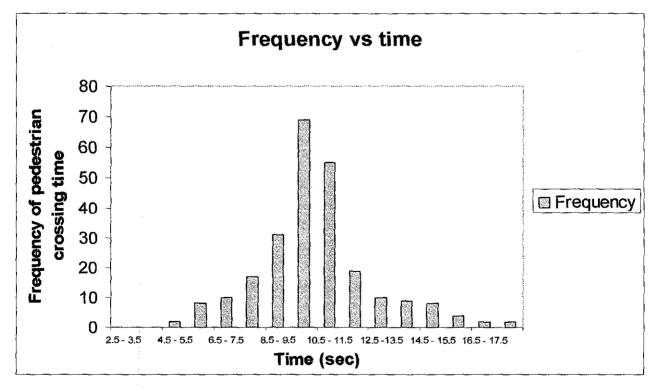


Figure 1: Cumulative pedestrian crossing time





value Freque).5 0).6 1).7 0).8 1).9 6 I.0 10 I.1 21	ncy frequency 0 1 1 2 8	Percentage frequency 0.00 0.41 0.00 0.41	frequency 0 0 0
0.7 0 0.8 1 0.9 6 1.0 10	2	0.00	
0.810.961.010	2		0
).9 6 I.0 10		0.41	
1.0 10	8		1
		2,44	3
1 21	18	4.07	7
4.1	39	8.54	16
1.2 63	102	25.61	41
1.3 37	139	15.04	57
1.4 27	166	10.98	67
1.5 19	185	7.72	75
1.6 24	209	9.76	85
1.7 21	230	8.54	94
1.8 0	230	0.00	94
1.9 0	230	0.00	94
2.0 3	233	1.22	95
2.1 3	236	1.22	96
2.2 2	238	0.81	97
2.3 1	239	0.41	97
2.4 0	239	0.00	97
2.5 2	241	0.81	98
2.6 2	243	0.81	99
2.7 1	244	0.41	99
2.8 1	245	0.41	100
	.8 0 .9 0 .0 3 .1 3 .2 2 .3 1 .4 0 .5 2 .6 2	.8 0 230 .9 0 230 .0 3 233 .1 3 236 .2 2 238 .3 1 239 .4 0 239 .5 2 241 .6 2 243	.8 0 230 0.00 .9 0 230 0.00 .0 3 233 1.22 .1 3 236 1.22 .2 2 238 0.81 .3 1 239 0.41 .4 0 239 0.00 .5 2 241 0.81 .6 2 243 0.81

Table 2: Pedestrian crossing speed

246

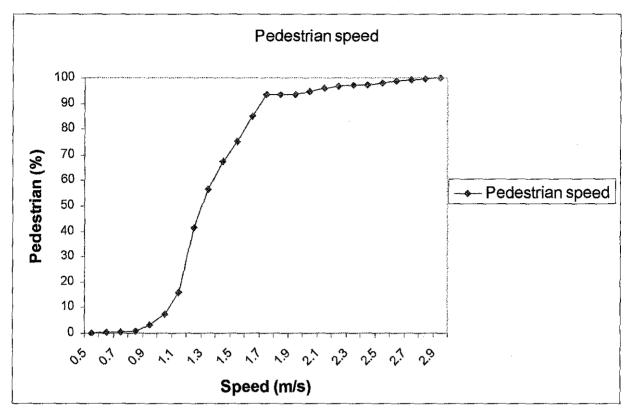
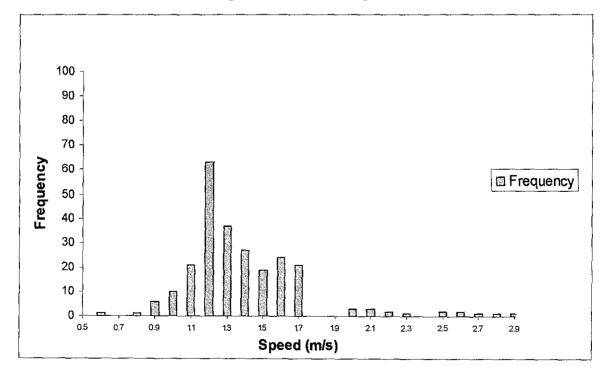


Figure 3: Cumulative pedestrian speed

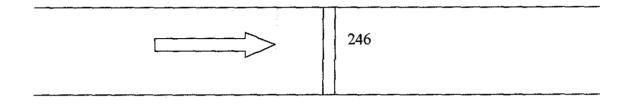
Figure 4: Pedestrian speed



TRAFFIC DATA

Location: Jalan Sultan Yusuf Duration of survey: 1 hour

Time of survey: 1300 - 1400

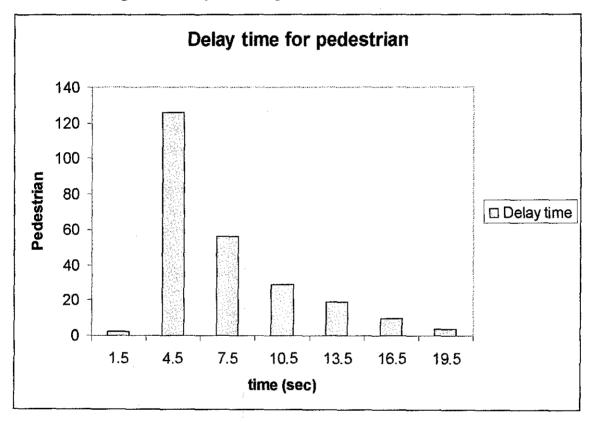


Time	Total traffic
1315	63
1330	76
1345	53
1400	54
Total	246

Class (sec)	Median	Frequency	Frequency precentage	
0.0 - 3.0	1.5	2	9	9.35
3.0 - 6.0	4.5	126	42	2.68
6.0 - 9.0	7.5	56	2:	2.76
9.0 - 12.0	10.5	29	1.	1.78
12.0 - 15.0	13.5	19		7.72
15.0 - 18.0	16.5	10	4	1.06
18.0 - 21.0	19.5	4	-	1.62
		246		100

Table 3: Delay time for pedestrian

Figure 5: Delay time for pedestrian



aaSIDRA INPUT DATA

LOCATION 1

Akcelik & Associates - aaSIDRA 2.0.1.206 utp aileen Registered User No. a1061 Licence Type: Educational, Multi Computer

Time and Date of Analysis 10:57 PM, 7 May 2006

Filename: G:\pelajaran\fyp\fyp2\aaSIDRA Projects\push button\aileen1.LIS

Push-button basis Jalan Sultan Yusuf

INPUT DATA LISTING

MAIN OPTIONS

						Major						Unit	SIDRA
Line	Int.	Int.	Def.	Summ.	Int.	Road/	Int.	Def	Drive	NZ	User	Time	Versn
Туре	Type	Ctrl	File.	Out.	Geom.	Fwy	Coord	Grp	Rule	Rule	Levl	Method	No.
0	1	А	30	F	7	EW	EW	Y	R	N	A	Ϋ	5.40

PROGRAM CONTROL DATA

Line	Cycl	Cycl	Max	Intg	Stp	Peak	Flow	ΗV	Total	Satf	PFF	Satf
Туре	Time	Incr	Cycl	Time	Pen	Per	Scal	Opt	Per	Scal	*100	Estim
1	Р	10	150	6	20	15	100	P	60	100	95	Y

INTERSECTION DATA

		No.		Turn	Perct	Lane	Base	Prac		
Line	Int	Appr		On	Heavy	Width	Satn	Deg	Apprch	
Type	No.	Lanes	Peds	Red	Vehs	(cm)	Flow	Satn	Dist	Speed
A1		3	F	N	0	300	1950	90	500	60

APPROACH DESCRIPTION

	App				No.	No.					Ped.	Cross	Down
Line	Rd	Approach	Road	Name	App	Ext	Med.		Con		Dist	ance	SL
Туре	Loc	(Desc	ription	n)	Lns	Lns	Width	Ped	Тур	TOR	Appr	Exit	Lgth
A2	Е	Padang			0	5	N	F		N	1500	0	N
A2	W	HSBC			5	0	N	N	AN	N	0	0	N
A2	Е	Padang	-	,			N	F		N	1500	0 0	-

APPROACH DATA

	Appr	Perct	Appr	Lane	Base	Prac.					
Line	Road	Heavy	Grade	Width	Satn	Deg.	PHF	Arrvl	Appr	Exit	Appr
Type	Locn	Vehs	(%)	(cm)	Flow	Satn	*100	Туре	Speed	Speed	Dist
A3	W	0	0	300	1950	90	95	3	60	⁻ 60	500

MOVEMENT DESCRIPTION

	Appr					VΈ	нг	СЬЕ	S -					PED	s
Line	Road	Exit		Mov	Mov	Mov									
Type	Locn	Road	Trn	No.	No.	No.									
A4	Ë													53	
A4	W	Е	т	11											

VEHICLE VOLUMES

	Appr								
Line Veh	Road		Volume	of	Traffic	Turning	TO	APPROACH	
Type Class	Locn	S	SE	F	C NE	Ñ	NW	W	SW

A5	TOT	E	
A5	%HV	E	
A5	TOT	W	2684
A5	%HV	W	0

PEDESTRIAN VOLUMES

Line	Vol.	of	Pedes	strians	in	Front	of	Appro	ach	
Туре	S		SE	E	NE	N		NW	Ŵ	SW
A6			2	46						

LANE DATA

	Appr				\mathtt{SL}	Lane	Basic	Lane	SL	No.of	Bus
Line	Road	Lane	Lane	Lane	Length	Width	Satn	Util	Green	Park	Stops
Type	Locn	No.	Dis.	Type	(m)	(cm)	Flow	(웅)	Const	Manvs	/hour
Ā8	W	1	Т	1	N*	300	1950	100	N	N	Ń
A8	W	2	т	1	N*	300	1950	100	N	N	N
8A	W	3	Ť	1	N*	300	1950	100	N	N	N
A8	W	4	Т	1	N*	300	1950	100	N	N	N
A 8	W	5	Т	1	N*	300	1950	100	N	N	N

PHASE DATA

			Opd												
Line	Phase	Mov	Ped												
Туре	Name	No.	Dum												
A14	A	53	Ρ												
A14	в	11							-						
	A 1/m		·												

Under Opd/Ped/Dum: L,T,R=Opposed turns, P=Pedestrian, D=Dummy

PHASE SEQUENCE DATA

	Phase		-							
Line	Seq.	Pha								
Туре	No.	Nam								
A15	1	А	B							

CURRENT PHASE SEQUENCE

	Phase
Line	Seq.
Туре	No.
A16	1

NEGOTIATION RADIUS (GEOMETRIC DATA)

Line	Appr Road	Negotiati	on rad	dius for	traffic	exiting	TO APPROACH	
Type A21	Locn W	S SE	E P	NE	n nw	W	SW	

NEGOTIATION SPEED (GEOMETRIC DATA)

Line	Appr Road	Negotiati	lon sp	eed for	traf	fic exi	ting	TO APPROACH	
Туре А22	Locn W	S SE	Б Б	NE	N	NW	W	SW	

NEGOTIATION DISTANCE (GEOMETRIC DATA)

Appr

Line Road -- Negotiation distance for traffic exiting TO APPROACH --

Туре	Locn	S	SE	E	NE	N	NW	W	SW
A23	W			Р					

MOVEMENT DATA: PHASE AND TIMING PARAMETERS (Mov.Type: P=Pedestrian, D=Dummy, U V W=Undetected, C=Continuous) F I R S T G R E E N

Line	Mov.	Mov.	From	То	Inter-	Start	End	Min.	Max.
Type	Type	No.	Phase	Phase	Green	Loss	Gain	Green	Green
4	P	53	A	в	6	2	-8	16	N
4		11	В	А	6	3	3	6	N

MOVEMENT DATA (2)

		Satn	Flow				Turn Ty Radius	• •
Line	Mov	1st	2nd	Prac.	Grad.			
Type	No.	Grn	Grn	Deg.Satn	(원)		L	R
5	53	12000		90		0		
5	11			90	0	0	0	0

MOVEMENT GROUPING DEFINITION

Line Grp Mov Mov Mov Mov Mov Mov Mov Mov ---- GROUP DESCRIPTION ----Type No. No. No. No. No. No. No. No. No. 11 1 11 11 2 53 HSBC Pedestrians

DATA FOR MOVEMENT GROUPINGS

Line Type	Group No.		Delay Weight	Stop Weight	Queue Weight		
		do	100w1	100w2	100w3		
12 2	1	100	100	100	100	0	0
12 2	2	100	100	100	100	0	0

DATA FOR FUEL/EMISSIONS/COST

Group	Idling	Stead	y Speed	Veh.	Power Coeffs.	Alphanumeric
No.	Rate			Mass	(*10E4)	Description
	(/h)	А	в	(kq)		
			(*10E5)		Betal Beta2	Name Unit
1	All para	meters	program	calcul	ated	
2	All para	meters	program	calcul	ated	

MOVEMENT DATA (1)

		Appro	bach				e Space n/veh)		PHF *100	Arrival & Control
Line Type	Mov No.	Speed (km/h)	Dist. (m)			LA	HV			Type & Coord.
15 15	53 11	4 60	10 500	0 0	0	100 700	0 1300	0 0	95 95	3AN 3AN

GREEN SPLIT PRIORITY

Line	Applic-	Mov.	Pri.								
Туре	able?	No.	Code								
20	N	•	•	•	•	•	•	•	•	•	•

VARIABLE CYCLE TIME DATA

CYCLE TIMES

Туре 21	User/ Prog N	 1st	2nd 150		4th 5t	h 6t1	n 7t1	n 8th	. 9th	10th	11th	12th	13th	14th
VARIAB	LE FLOW	SCALE	DATA	L			F	LO	W	sci	ΥΓΕ	S		
	User/ Prog N	Gro	ups		st 2nd		4th	5th	6th	7th 81	 th 9th	n 10t)	h 11t	 h 12th
End of	Input	Data L	istir	na fra	om fil	~·								
G:\pela	-			-			oush	butt	:on\a	ileen	L.DAT			
G:\pela	-			-			push	butt	:on\a	ileen:	L.DAT			
~	-	yp\fyp		-			push	butt	:on\a	ileen	L.DAT			
RUNTIM	jaran\f	yp\fyp MATION aSIDRA	2\aas	IDRA			oush	butt	:on\a	ileen	1.DAT			

Main Iteration No. 4 Main Iteration No. 5 Calculating Performance Results and Writing Main Output File: G:\pelajaran\fyp\fyp2\aaSIDRA Projects\push button\aileen1.OUT

•

aaSIDRA OUTPUT DATA

LOCATION 1

Akcelik & Associates Pty Ltd - aaSIDRA 2.0.1.206 _____ utp Registered User No. a1061 aileen Licence Type: Educational, Multi Computer Time and Date of Analysis 10:57 PM, 7 May 2006 lename: G:\pelajaran\fyp\fyp2\aaSIDRA Projects\push button\aileen1.OUT .sh-button basis lan Sultan Yusuf tersection ID: N INFORMATION ______ Basic Parameters: Intersection Type: Signalised - Actuated Isolated For fully-actuated signal timings, the following specifications will be ignored: Any maximum cycle time specification Any user-given cycle time (unless phase times also given) User-given cycle and phase times (if variable flow scale run) Any variable cycle time specification Any green split priority specification Driving on the right-hand side of the road Input data specified in Metric units Default Values File No. 30 Peak flow period (for performance): 15 minutes Unit time (for volumes): 60 minutes (Total Flow Period) Delay definition: Control delay Geometric delay included aaSIDRA Standard Delay and Queue models used Level of Service based on: Delay (HCM method) Queue definition: Back of queue, 95th Percentile No. of Main (Timing-Capacity) Iterations = 5 Comparison of last two iterations: Difference in intersection degree of satn = 0.0 % Difference in total vehicle capacity = 0.0 % Largest difference in eff. green times = 0 secs (max. value for stopping = 0 secs) ish-button basis alan Sultan Yusuf itersection ID: **EFAULT PARAMETERS** _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ sfault values for some of the important general parameters: Default Values File: DEF30.SDF) 1. Basic saturation flow: 1950 tcu/h This value applies mainly to signalised intersections. For roundabouts and sign-controlled intersections, it is used for determining capacity of priority and continuous movements. 2. Through car equivalents for signalised intersections LEFT THROUGH RIGHT HV LV HV LV HV LV Normal1.0501.8001.0001.6501.0501.800Restricted1.2502.2501.2502.250

3. Opposed turn parameters (Signalised intersection)

	Left turns Right turr	Cr. G. s: 4 as: 4	it. ap .5 .0	Fol.up Hdway 2.6 2.4	Deps at End 2.2 2.5	% E Opj	xit Flo posing 0 0	W		
4. Cru	ise speed=	60 km/h	, Ap	proach Dia	stance	- 50	0 m			
5. Quet	ue space pe Light vehi				ehicles	s: 13	.0			
	list of ir Guide part					s is d	given i	n the		
lan Sul	ton basis ltan Yusuf tion ID: Actuate	ed Isola	ted S	ignals, Cy	ycle Ti	ime =	48			
·	0 - TRAFFIC									
	ov D.			Throug LV						
HICLES	Dema	ind flow	s in	veh/hour a	as used	i by	the pro	gram		
	11 			2825					0.95	
DESTRIA	ANS 53	Flow	(ped/) 259	hour)				1.00	0.95	
ish-buti	le and Peak ton basis ltan Yusuf tion ID: Actuate			effects : ignals, Cy			<u></u>	alues.		
ble S.	1 - MOVEMEN	IT PHASE	AND	TIMING PA	RAMETEI	₹S				
10v 10.	Tvo First	Green	Sec	ond Green						
		Op Pr		To Op Pr	1st Grn	2nd Grn	1st Grn	2nd Grn	1st Grn	2nd Grn
est: HSI 11 T	BC *B A				6				21	
edestr: 53	(Ped)*A B	**			16		21.0Mi	n 	6	
Input p Output	t Phase Seque phase seque phase sequ	uence N ence: A lence: A	o.: 1 B							
Dum Du Und Ur Unl Ur	edestrian	n 1st g	reen	period	L R	"L "R ? "L	ight" t eft and	rns are urns ar Right"	opposed e oppose opposed ation fl	d

ish-button basis

lan Sultan Yusuf tersection ID: Actuated Isolated Signals, Cycle Time = 48

ble S.2 - MOVEMENT CAPACITY PARAMETERS

⊙v	Dem Flow	Satn	Flow		Ratio	Total Cap.	Prac. Deg.	Prac. Spare	Lane Util	Deg. Satn
	(veh /h)	1st Grn	2nd Grn	1st Grn	2nd Grn	(veh /h)	Satn xp	Cap. (%)	(%)	x
st: HS 11 T	BC 2825	9614		0.294		4206	0.90	34	100	0.672*
edestr 53	ians 259	12000		0.022		1500	0.90		100	0.173

sh-button basis

lan Sultan Yusuf

tersection ID:

Actuated Isolated Signals, Cycle Time = 48

ble S.3 - INTERSECTION PARAMETERS

Crit App. Mov & No. Turn	Green Period	Pha Fr	ases To	Adjusted Lost Time	Adjusted Flow Ratio	Required Grn Time Ratio	Required Movement Time
53 E_Ped 11 W_T		A B	B A Total:	21 6 27	0.294	0.430	21.0Min 26.6 47.6

- Flow ratio not used for cycle time calculations and the adjusted lost time equals the required movement time (=Min or Max as shown in Table S.1)

Cycle Time: Minimum Maximum Practical Chosen		
34 NA 48 48		
Intersection Level of Service	=	7
		B
Worst movement Level of Service	=	B
Average intersection delay (s)		12.8
Largest average movement delay (s)	=	18.9
Largest back of queue, 95% (m)	12	89
Performance Index	-	86.22
Degree of saturation (highest)	=	0.672
Practical Spare Capacity (lowest)	=	34 %
Total vehicle capacity, all lanes (veh/h)		4206
Total vehicle flow (veh/h)	=	2825
Total pedestrian flow (ped/h)		259
Total person flow (pers/h)	-	4497
Total vehicle delay (veh-h/h)		9.72
Total pedestrian delay (ped-h/h)	37	1.36
Total person delay (pers-h/h)	=	15.94
Total effective vehicle stops (veh/h)	=	2070
Total effective pedestrian stops (ped/h)	=	227
Total effective person stops (pers/h)	=	3333
Total vehicle travel (veh-km/h)	=	1713.2
Total cost (\$/h)	=	923.47
Total fuel (L/h)	_	181.0
• • •	_	452.51
Total CO2 (kg/h)	-	452.51

ish-button basis

lan Sultan Yusuf tersection ID: Actuated Isolated Signals, Cycle Time = 48 ble S.4 - PHASE INFORMATION _____ Phase Change Green Displayed Grn+Intgrn No. Time Start Green Secs Prop. ______ 0 6 15 21 0.438 21 27 21 27 0.562 Α в ******* Current Phase Sequence No.: 1 Input phase sequence: A B Output phase sequence: A B .sh-button basis lan Sultan Yusuf tersection ID: Actuated Isolated Signals, Cycle Time = 48 ble S.5 - MOVEMENT PERFORMANCE __________ MovTotalTotalAver.Prop.Eff. Longest QueuePerf.Aver.No.DelayDelayDelayQueuedStop95%BackIndexSpeed(veh-h/h) (pers-h/h) (sec)Rate (vehs) (m)(km/h) st: HSBC 11 T 9.72 14.58 12.4 0.83 0.73 12.7 89 82.95 44.8 _____ 'edestrians 53 1.36 1.36 18.9 0.87 0.88 0.6 1 3.27 1.3 ish-button basis ilan Sultan Yusuf itersection ID: Actuated Isolated Signals, Cycle Time = 48 able S.6 - INTERSECTION PERFORMANCE ______ Total Deg. Total Total Aver. Prop. Eff. Longest Perf. Aver. Tow Sath Delay Delay Delay Queued Stop Queue Index Speed reh/h) x (veh-h/h) (pers-h/h) (sec) Rate (m) (km/h) ≥st: HSBC 2825 0.672 9.72 14.58 12.4 0.835 0.73 89 82.95 44.8 ?edestrians 259 0.173 1.36 1.36 18.9 0.878 0.88 1 3.27 1.3 _ __ __ __ __ __ ----------LL VEHICLES: 2825 0.672 9.72 14.58 12.4 0.835 0.73 89 82.95 44.8

Leue values in this table are 95% back of queue (metres).

15.94 12.8 0.839 0.74

86.22

43.3

SHIN 9 7 - TANE DEDENDMANCE

VTERSECTION (persons):

1497 0.672

	Morr			e Red nes (Dem Flow	Cap	Satn	Delay	Eff.	Qие 95% В		Shrt Lane
ane o	Mov No.	R1	G1	R2	G2	(veh /h)	(veh /h)		(sec)	Stop Rate	(vehs)	(m)	(m)
est:	HSBC												
Т	11	27	21	0	0	565	841	0.672	12.4	0.73	12.7	89	
т	11	27	21	0	0	565	841	0.672	12.4	0.73	12.7	89	
т	11	27	21	0	0	565	841	0.672	12.4	0.73	12.7	89	
T	11	27	21	0	0	565	841	0.672	12.4	0.73	12.7	89	
T	11	27	21	0	0	565	841	0.672	12.4	0.73	12.7	89	

ish-button basis
ilan Sultan Yusuf
itersection ID:

Actuated Isolated Signals, Cycle Time = 48

ble S.8 - LANE FLOW AND CAPACITY INFORMATION

an Io.	Mov No.		n Flow Thru	(veh Rig		Lane Width (m)	Adj. Basic	ation Aver 1st (veh)	Aver 2nd	End Cap (veh /h)	•	Deg. Satn x	Lane Util %
<i>lest:</i> . T ? T ? T ! T ! T ; T	HSBC 11 11 11 11 11	0 0 0 0 0	565 565 565 565 565 565	0 0 0 0 0	565 565 565 565 565 565	3.00 3.00 3.00 3.00 3.00 3.00	1923 1923 1923 1923 1923 1923	1923 1923 1923	0 0 0 0 0	0 0 0 0 0	841 841 841	0.672 0.672 0.672 0.672 0.672 0.672	100 100 100 100 100

Basic Saturation Flow in this table is adjusted for lane width, approach grade, parking manoeuvres and number of buses stopping. Saturation flow scale applies if specified.

lov lo.	Моч Тур	Dem Flow (veh /h)	Total Cap. (veh /h)	Util		1st 2nd	Aver. Delay (sec)	Eff. Stop Rate	95% Back of Queue (veh)	Perf. Index
est: H 11 T	SBC	2825	4206	100	0.672*	21*	12.4	0.73	12.7	82.95
Pedest 53	rians (Ped)	259	1500	100	0.173	 -	18.9	0.88	0.6	3.27

able S.12A - FUEL CONSUMPTION, EMISSIONS AND COST - TOTAL

<pre>Alan Sultan Yusuf Itersection ID: Actuated Isolated Signals, Cycle Time = 48 Able S.12B - FUEL CONSUMPTION, EMISSIONS AND COST - RATE Mov Fuel Cost HC CO NOX CO2</pre>		Total	Cost Total \$/h	Total	Total	Total	Total
edestrians 53 27.67 27.67 LL VEHICLES: 181.0 895.80 0.768 36.56 1.100 452.5 MTERSECTION: 181.0 923.47 0.768 36.56 1.100 452.5 Pump price of fuel (\$/L) = 0.850 Fuel resource cost factor = 0.50 Ratio of running cost to fuel cost = 3.0 Average income (\$/h) = 23.00 Time value factor = 0.60 Average occupancy (persons/veh) = 1.5 Light vehicle mass (1000 kg) = 1.4 Heavy vehicle mass (1000 kg) = 1.0 Light vehicle idle fuel rate (L/h) = 1.350 Heavy vehicle idle fuel rate (L/h) = 2.000 The idle fuel and vehicle mass parameters given above are th values (data given in RIDES may override some of these param ish-button basis ilan Sultan Yusuf itersection ID: Actuated Isolated Signals, Cycle Time = 48 ible S.12B - FUEL CONSUMPTION, EMISSIONS AND COST - RATE Mov Fuel Cost HC CO NOX CO2							
53 27.67 27.67 LL VEHICLES: 181.0 895.80 0.768 36.56 1.100 452.5 NTERSECTION: 181.0 923.47 0.768 36.56 1.100 452.5 RAMETERS USED IN COST CALCULATIONS Pump price of fuel (\$/L) = 0.850 Fuel resource cost factor = 0.50 Ratio of running cost to fuel cost = 3.0 Average income (\$/h) = 23.00 Time value factor = 0.60 Average occupancy (persons/veh) = 1.4 Heavy vehicle mass (1000 kg) = 11.0 Light vehicle mass (1000 kg) = 1.10 Light vehicle idle fuel rate (L/h) = 2.000 The idle fuel and vehicle mass parameters given above are th values (data given in RIDES may override some of these param ish-button basis							
27.67 LL VEHICLES: 181.0 895.80 0.768 36.56 1.100 452.5 TRESECTION: 181.0 923.47 0.768 36.56 1.100 452.5 RAMETERS USED IN COST CALCULATIONS Pump price of fuel (\$/L) = 0.850 Fuel resource cost factor = 0.50 Ratio of running cost to fuel cost = 3.0 Average income (\$/h) = 23.00 Time value factor = 0.60 Average occupancy (persons/veh) = 1.4 Heavy vehicle mass (1000 kg) = 1.4 Heavy vehicle idle fuel rate (L/h) = 1.350 Heavy vehicle idle fuel rate (L/h) = 2.000 The idle fuel and vehicle mass parameters given above are th values (data given in RIDES may override some of these param ish-button basis alan Sultan Yusuf tersection ID: Actuated Isolated Signals, Cycle Time = 48 able S.12B - FUEL CONSUMPTION, EMISSIONS AND COST - RATE Mov Fuel Cost HC CO NOX CO2			27.67				
NTERSECTION: 181.0 923.47 0.768 36.56 1.100 452.5 RAMETERS USED IN COST CALCULATIONS Pump price of fuel (\$/L) = 0.850 Fuel resource cost factor = 0.50 Ratio of running cost to fuel cost = 3.0 Average income (\$/h) = 23.00 Time value factor = 0.60 Average occupancy (persons/veh) = 1.4 Heavy vehicle mass (1000 kg) = 1.4 Heavy vehicle idle fuel rate (L/h) = 1.350 Heavy vehicle idle fuel rate (L/h) = 2.000 The idle fuel and vehicle mass parameters given above are th values (data given in RIDES may override some of these param ish-button basis 1an Sultan Yusuf itersection ID: Actuated Isolated Signals, Cycle Time = 48 able S.12B - FUEL CONSUMPTION, EMISSIONS AND COST - RATE			27.67				
NTERSECTION:181.0923.470.76836.561.100452.5RAMETERS USED IN COST CALCULATIONSPump price of fuel (\$/L)=0.850Fuel resource cost factor=0.50Ratio of running cost to fuel cost=3.0Average income (\$/h)=23.00Time value factor=0.60Average occupancy (persons/veh)=1.5Light vehicle mass (1000 kg)=1.4Heavy vehicle idle fuel rate (L/h)=1.350Heavy vehicle idle fuel rate (L/h)=2.000The idle fuel and vehicle mass parameters given above are th values (data given in RIDES may override some of these paramish-button basis alan Sultan Yusuf itersection ID: Actuated Isolated Signals, Cycle Time =Able S.12B - FUEL CONSUMPTION, EMISSIONS AND COST - RATEMovFuel Cost HCCONOX							452.5
Pump price of fuel (\$/L)=0.850Fuel resource cost factor=0.50Ratio of running cost to fuel cost=3.0Average income (\$/h)=23.00Time value factor=0.60Average occupancy (persons/veh)=1.5Light vehicle mass (1000 kg)=1.4Heavy vehicle mass (1000 kg)=11.0Light vehicle idle fuel rate (L/h)=1.350Heavy vehicle idle fuel rate (L/h)=2.000The idle fuel and vehicle mass parameters given above are th values (data given in RIDES may override some of these paramIsh-button basis alan Sultan Yusuf itersection ID: Actuated Isolated Signals, Cycle Time =48able S.12B - FUEL CONSUMPTION, EMISSIONS AND COST - RATEMovFuel Cost HCCONOXCO2NOXCO2							452.5
<pre>values (data given in RIDES may override some of these param sh-button basis lan Sultan Yusuf stersection ID:</pre>	Fuel resourc Ratio of run Average inco Time value f Average occu Light vehicl Heavy vehicl Light vehicl	e cost f ning cos me (\$/h) actor pancy (p e mass (e mass (e idle f	actor at to fue persons/ve 1000 kg) 1000 kg) Tuel rate	≥h) (L/h)		3.0 23.00 0.60 1.5 1.4 11.0 1.350	
No. Rate Rate Rate Rate Rate Rate							
	alan Sultan Yu Atersection ID Act Able S.12B - F	suf : uated Is UEL CONS	SUMPTION,	EMISSIO	NS AND CO)ST - RAI	
No. Rate Rate	alan Sultan Yu htersection ID Act able S.12B - F Mov No.	suf : uated Is UEL CONS Fuel	COST	EMISSION	NS AND CO	OST - RAT	CO2 Rate
Pedestrians 10.68 10.68	alan Sultan Yu htersection ID Act able S.12B - F Mov No.	suf : uated Is UEL CONS Fuel Rate L/100km 10.6	COST Rate \$/km 0.52	EMISSION HC Rate g/km 0.448	NS AND CO CO Rate g/km 21.34	DST - RAT NOX Rate g/km 0.642	CO2 Rate g/km 264.1
ALL VEHICLES: 10.6 0.52 0.448 21.34 0.642 264.1	alan Sultan Yu Atersection ID Act Able S.12B - F Mov No. No. est: HSBC 11 T Pedestrians	suf : uated Is UEL CONS Fuel Rate L/100km 10.6 10.6	Cost Rate \$/km 0.52 0.52 10.68	EMISSION HC Rate g/km 0.448 0.448	NS AND CO CO Rate g/km 21.34	DST - RAT NOX Rate g/km 0.642	CO2 Rate g/km 264.1
INTERSECTION: 10.6 0.54 0.448 21.34 0.642 264.1	alan Sultan Yu htersection ID Act able S.12B - F Mov No. est: HSBC 11 T Pedestrians 53	suf : uated Is UEL CONS Fuel Rate L/100km 10.6 	COST Rate \$/km 0.52 0.52 10.68 10.68	EMISSION HC Rate g/km 0.448 0.448	NS AND CO CO Rate g/km 21.34 21.34	DST - RAT NOX Rate g/km 0.642 0.642	CO2 Rate g/km 264.1 264.1

ush-button basis alan Sultan Yusuf ntersection ID:

_____ _____ _____ Demand Flow (veh/h) Adj. Eff Grn Deg Aver. Longest Shrt ------ %HV Basic (secs) Sat Delay Queue Lane L T R Tot Satf. 1st 2nd x (sec) (m) (m) ane Demand Flow (veh/h) 0. _____ lest: HSBC 56556501922210.67212.48956556501922210.67212.48956556501922210.67212.48956556501922210.67212.48956556501922210.67212.48956556501922210.67212.489 т Т Т T T _____ ______ 0 2825 0 2825 0 0.672 12.4 89 'edestrians 259 6 0.173 18.9 0.6 Across E approach Total % Cycle Max Aver. Max LL VEHICLES
 Flow
 HV
 Time
 X
 Delay
 Queue

 2825
 0
 48
 0.672
 12.4
 89
 _____ stal flow period = 60 minutes. Peak flow period = 15 minutes. weue values in this table are 95% back of queue (metres).)te: Basic Saturation Flows (in through car units) have been adjusted for grade, lane widths, parking manoeuvres and bus stops. ish-button basis ilan Sultan Yusuf itersection ID: Actuated Isolated Signals, Cycle Time = 48 ble S.15 - CAPACITY AND LEVEL OF SERVICE Mov Green Time Total Total Deg. Aver. LOS Typ Ratio (g/C) Flow Cap. of Delay ------ (veh (veh Satn 1st 2nd /h) /h) (v/c) (sec) grn grn lov 10. st: HSBC 2825 4206 0.672* 12.4 B 11 T 0.438* -----_____ ----2825 4206 0.672 12.4 B _____ Pedestrians 53 (Ped) 0.125* 259 1500 0.173 18.9 B _____ 1500 0.173 18.9 259 В ALL VEHICLES: 2825 4206 0.672 12.4 В INTERSECTION (persons): 4497 4206 0.672 12.8 _____ ____ Level of Service calculations are based on average control delay including geometric delay (HCM criteria), independent of the current delay definition used. For the criteria, refer to the "Level of Service" topic in the aaSIDRA Output Guide or the Output section of the on-line help. Intersection capacity is calculated considering vehicle movements only. * Maximum v/c ratio, or critical green periods

ble S.14 - SUMMARY OF INPUT AND OUTPUT DATA

ish-button basis

ble D.O - GEOMETRIC DELAY DATA _____ Negn Negn Negn Appr. Downstream rom To Radius Speed Dist. Dist. Distance pproach Approach (m) (km/h) (m) (m) (m) _____* _______ ----_____ est: HSBC East S 60.0 10.0 500 106 Downstream distance is distance travelled from the stopline until exit cruise speed is reached (includes negotiation distance). Acceleration distance is weighted for light and heavy vehicles. The same distance applies for both stopped and unstopped vehicles. sh-button basis lan Sultan Yusuf tersection ID: Actuated Isolated Signals, Cycle Time = 48 ble D.1 - LANE DELAYS ----- Delay (seconds/veh) ------Deg. Stop-line Delay Acc. Queuing Stopd ane Mov Satn 1st 2nd Total Dec. Total MvUp (Idle) Geom Control o. No. x dl d2 dSL dn dq dqm di dig dic ______ 'est: HSBC

 T
 11
 0.672
 12.4
 0.0
 12.4
 7.2
 5.2
 0.0
 5.2
 0.0
 12.4

 T
 11
 0.672
 12.4
 0.0
 12.4
 7.2
 5.2
 0.0
 5.2
 0.0
 12.4

 T
 11
 0.672
 12.4
 0.0
 12.4
 7.2
 5.2
 0.0
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 T
 11
 0.672
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 12.4
 7.2
 5.2
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 5.2
 0.0
 12.4

 T
 11
 0.672
 12.4
 0.0
 12.4
 7.2
 5.2
 0.0
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 T
 11
 0.672
 12.4
 0.0
 12.4
 7.2
 5.2
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 T
 11
 0.672
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 7.2
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 0.0
 12.4

 T
 11
 0.672
 12.4
 0.0
 12.4
 7.2
 5.2
 0.0
 5.2
 0.0
 12.4

</tabr/> ______ dn is average stop-start delay for all vehicles queued and unqueued

Ish-button basis Ilan Sultan Yusuf Itersection ID:

Actuated Isolated Signals, Cycle Time = 48

ble D.2 - LANE STOPS

lane lo.	Deg. Satn X	Ef hel	fectiv he2	-	Rate Overall h		Queue Move-up Rate hqm
lest:	HSBC						
. Т	0.672	0.73	0.00	0.00	0.73	0.835	0.00
: T	0.672	0.73	0.00	0.00	0.73	0.835	0.00
) T	0.672	0.73	0.00	0.00	0.73	0.835	0.00
l T	0.672	0.73	0.00	0.00	0.73	0.835	0.00
jΤ	0.672	0.73	0.00	0.00	0.73	0.835	0.00

hqm is average queue move-up rate for all vehicles queued and unqueued

ish-button basis

ble D.3 - LANE QUEUES

	Deg. Satn	Ovrfl. Oueue -	Avera	age (ve	eh)		Perce	ntile	(veh)		Queue Stor.
ane o.	X	No	Nb1	Nb2	Nb	70%	85%	90%	95%	98%	Ratio
'est: T T T T	HSBC 0.672 0.672 0.672 0.672	0.0 0.0 0.0 0.0	6.6 6.6 6.6	0.0 0.0 0.0 0.0	6.6 6.6 6.6 6.6	7.9 7.9 7.9 7.9	10.2 10.2 10.2 10.2	11.2 11.2 11.2 11.2 11.2	12.7 12.7 12.7 12.7	15.3 15.3 15.3 15.3	0.18 0.18 0.18 0.18
' T	0.672	0.0	6.6	0.0	6.6	7.9	10.2	11.2	12.7	15.3	0.18

Values printed in this table are back of queue (vehicles).

wble D.4 - MOVEMENT SPEEDS (km/h)

Mov No.	App. Sp Cruise	eeds Negn		Speeds Cruise	~	Move-up 2nd Grn		tion Spd Overall
Nest:	HSBC 60.0	60.0	60.0	60.0			50.1	44.8

"Running Speed" is the average speed excluding stopped periods.

ish-button basis ilan Sultan Yusuf itersection ID:

Actuated Isolated Signals, Cycle Time = 48

able D.5 - PROGRESSION FACTORS & ACTUATED SIGNAL PARAMETERS

Mov No.	Control	Coord.	Arrival Type	Delay Prog. Factor	Queue Prog. Factor	Gap Settin es	.gs eh	1st	Grn	. Sett 2nd Gmin	Grn
√est: 11	HSBC VA	No	3	1.000	1.000	2.5	3.1	6	50		
edes 53	trians VA	No	3	1.000	1.000						

--- End of aaSIDRA Output ---

Intersection Summary

Push-button basis

	lik sociates
aa Traffic	SIDRA

Performance Measure	Vehicles	Pedestrians	Pers
Demand Flow	2825 veh/h	259 ped/h	4497 p
Degree of Saturation	0.672	0.173	
Capacity (Total)	4206 veh/h		
95% Back of Queue (m)	89 m	1 m	
95% Back of Queue (veh)	12.7 veh	0.6 ped	
Control Delay (Total)	9.72 veh-h/h	1.36 ped-h/h	15.94
Control Delay (Average)	12.4 s/veh	18.9 s/ped	12.8 s/
Level of Service	LOS B	LOS B	
Level of Service (Worst Movement)	LOS B	LOS B	
Total Effective Stops	2070 veh/h	227 ped/h	3333 p
Effective Stop Rate	0.73 per veh	0.88 per ped	0.74 pe
Travel Distance (Total)	1713.2 veh-km/h	2.6 ped-km/h	2572.4
Travel Distance (Average)	606 m	10 m	572 m
Travel Time (Total)	38.3 veh-h/h	2.0 ped-h/h	59.4 pe
Travel Time (Average)	48.8 secs	27.9 secs	47.6 se
Travel Speed	44.8 km/h	1.3 km/h	43.3 kr
Operating Cost (Total)	896 \$/h	28 \$/h	923 \$/
Fuel Consumption (Total)	181.0 L/h		
Carbon Dioxide (Total)	452.5 kg/h		
Hydrocarbons (Total)	0.768 kg/h		
Carbon Monoxide (Total)	36.56 kg/h		
NOX (Total)	1.100 kg/h		

والمحاوية والمحربة والمراجع والمراكبة المحافية المحافية المحافية المحافية والمحافية والمراجع

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6/11/2006

Movement Summary



Push-button basis

Pedestrian crossing - Actuated isolated Cycle Time = 48 seconds

Vehicle Movements

And the other with a second the second to the second s

Mov No	Turn	Dem Flow (veh/h)	Cap (veh/h)	Deg of Satn (v/c)	Aver Delay (sec)	Level of Service	95% Back of Queue (m)	Eff. Stop Rate	Aver Speed (km/h)	Oper Cost (\$/h)
HSBC	e fræði ser fræði sægræg	ena prazena zna grua (nazina inaci	e Shekine (në Shekine propose sh	nen a shaken in shaken shaken s	n provensko stre kalen en Dereke konstanten so	nen en fan e	a seasona ann an Shaolana (1997).	na menina di mengena di meningka meningka seringka seringka seringka seringka seringka seringka seringka sering	nen senen e senen senen senen s	n og har fra efter fra offens fra
11	т	2825	4206	0.672	12.4	LOS B	89	0.73	44.8	896
Approach		2825	4206	0.672	12.4	LOS B	89	0.73	44.8	896
All Vehicles	produktion produktion provinge	2825	4206	0.672	12.4	LOS B	89	0.73	44.8	896

Pedestrian Movements

Mov No	Dem Flow (veh/h)	Aver Delay (sec)	Level of Service	95% Back of Queue (m)	Eff. Stop Rate	Oper Cost (\$/h)	
به امواد موجد موجد هواد عوجه موهد مواد هوی.	אין איניי ועל יביי וניי איני איני איני איני איני איני אי	والمراجعين المراجع المرجع الموجع المواجر المواجر المواجر المواجر المواجر المواجر	والموافر الموافر الموفر الموافر حوالي هويتها فارهر الأوار مو	ela este este con este este este este	an a	وفارعوه وفارعهم وترارعون وفارعون والمراجع والمراجع	n er er er e
53	259	18.9	LOS B	1	0.88	28	
II Peds	259	18.9	LOS B	1	0.88	28	

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APPENDIX B

LOCATION 2 JALAN SULTAN IDRIS SHAH

- Pedestrian Data
- Traffic Data
- Data using SIDRA software

PEDESTRIAN DATA

Location: Jalan Dato Onn Jaafar – Jalan Sultan Idris Shah

Pedestrian crossing system: Fixed time

Road Length: 15.7 m

Green time: 50 seconds

Flashing time: 50 seconds

Time of survey: 0900 – 1000

	Class		Percentage	Cumulative of	Cumulative percentage of
Class (sec)	midvalue	Frequency	frequency	frequency	frequency
3.5 - <u>4.</u> 5	4	0	0	0	0.0
4.5 - 5.5	5	2	0.6	2	0.6
5.5 - 6.5	6	4	1.3	6	1.9
6.5 - 7.5	7	5	1.6	11	3.5
7.5 - 8.5	8	19	6.1	30	9.6
8.5 - 9.5	9	34	11.0	64	20.6
9.5 - 10.5	10	48	15.5	112	36.1
10.5 - 11.5	11	53	17.1	165	53.2
11.5 -12.5	12	51	16.5	216	69.7
12.5 -13.5	13	52	16.8	268	86.5
13.5 - 14.5	14	35	11.3	303	97.8
14.5 - 15.5	15	2	0.6	305	98.4
15.5 - 16.5	16	2	0.6	307	99.0
16.5 - 17.5	17	0	0.0	307	99.0
17.5 - 18.5	18	0	0.0	307	99.0
18.5 - 19.5	19	1	0.3	308	99.3
19.5 - 20.5	20	2	0.6	310	100.0
<u>,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,</u>	· · · · · · · · · · · · · · · · · · ·	310	100.0		

 Table 1: Pedestrian crossing time

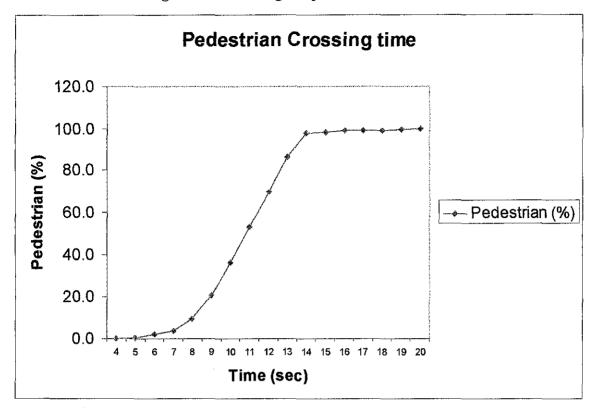
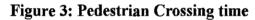
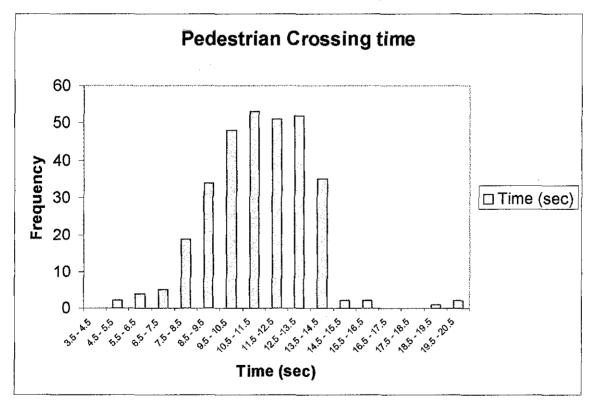


Figure 2: Percentage of pedestrian over time

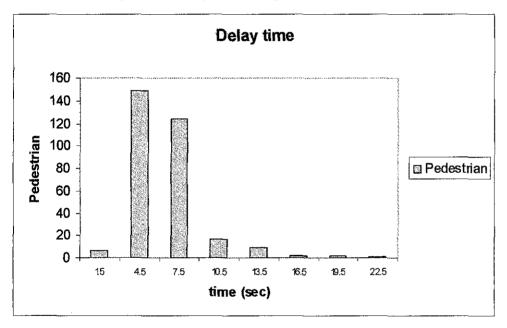




Class (sec)	Median	Frequency	Frequency precentage
0.0 - 3.0	1.5	6	1.29
3.0 - 6.0	4.5	149	48.06
6.0 - 9.0	7.5	124	40.35
9.0 - 12.0	10.5	17	5.48
12.0 - 15.0	13.5	9	2.9
15.0 - 18.0	16.5	2	0.65
18.0 - 21.0	19.5	2	0.65
21.0 - 24.0	22.5	1	0.32
		310	100

Table 2: Delay time for pedestrian

Figure 4: Delay time for pedestrian



TRAFFIC DATA

Location: Jalan Dato Onn Jaafar – Jalan Sultan Idris Shah

Duration of survey: 1 hour

Time of survey: 0900 – 1000

	Time	Total traffic
	0915	584
	0930	743
	0945	287
	1000	594
	Total	2208

Time	Total traffic
0915	152
0930	139
0945	114
1000	120
Total	525

Time	Total traffic
0915	263
0930	312
0945	241
1000	320
Total	1136

Time	Total traffic
0915	118
0930	187
0945	114
1000	89
Total	508

.

aaSIDRA INPUT DATA

LOCATION 2

Akcelik & Associates - aaSIDRA 2.0.1.206 utp aileen Registered User No. a1061 Licence Type: Educational, Multi Computer

Time and Date of Analysis 3:26 AM, 8 May 2006

Filename: G:\pelajaran\fyp\fyp2\aaSIDRA Projects\all-red pedestrian cross\aileen2.LIS

fixed-time basis jln sultan idris shah

INPUT DATA LISTING

MAIN OPTIONS

						Major						Unit	SIDRA
Line	Int.	Int.	Def.	Summ.	Int.	Road/	Int.	Def	Drive	NZ	User	Time	Versn
111-110-0	m	AL. 1	1732 T -	0+	<u> </u>		0 1	a	D	D 1 -	+ 1	M = 4 1 = -1	N7
rype	Type	CTTL	rıle	out.	Geom.	Łwy	Coord	Grp	ките	Rute	LevL	Method	NO.

PROGRAM CONTROL DATA

Line	Cycl	Cycl	Max	Intg	Stp	Peak	Flow	HV	Total	Satf	PFF	Satf
Туре	Time	Incr	Cycl	Time	Pen	Per	Scal	Opt	Per	Scal	*100	Estim
1	Р	10	150	6	20	15	100	Ρ	60	100	95	Y

INTERSECTION DATA

		No.		Turn	Perct	Lane	Base	Prac		
Line	Int	Appr		On	Heavy	Width	Satn	Deg	Apprch	
Type	No.	Lanes	Peds	Red	Vehs	(Cm)	Flow	Satn	Dist	Speed
A1		3	F	N	3	300	1950	90	500	60

APPROACH DESCRIPTION

	App				No.	No.					Ped.	Cross	Down
Line	Rd	Approach	Road	Name	App	Ext	Med.		Con		Dist	ance	SL
Туре	Loc	(Desc:	riptio	n)	Lns	Lns	Width	Ped	Тур	TOR	Appr	Exit	Lgth
A2	S	mcD			5	0	N	F	FN	N	1500	0	N
A2	E	parade			0	5	N	F		Ň	1500	0	N
A2	Ň	ocean			0	5	N	F		N	1500	0	Ň
A2	W	bcb			5	0	N	F	FN	N	1500	0	N

APPROACH DATA

	Appr	Perct	Appr	Lane	Base	Prac.					
Line	Road	Heavy	Grade	Width	Satn	Deg.	\mathbf{PHF}	Arrvl	Appr	Exit	Appr
Туре	Locn	Vehs	(୫)	(cm)	Flow	Satn	*100	Type	Speed	Speed	Dist
A3	S	3	0	300	1950	90	95	3	⁻ 60	⁻ 60	500
A3	W	3	0	300	1950	90	95	3	60	60	500

MOVEMENT DESCRIPTION

	Appr					VΕ	EHICLES							PEDS	
Line	Road	Exit		Mov	Exit		Mov	Exit		Mov	Exit		Mov	Mov	Mov
Туре	Locn	Road	Trn	No.	Road	Trn	No.	Road	Trn	No.	Road	Trn	No.	No.	No.
A4	S	N	Т	2	E	R	3							51	
A4	E													53	
A4	N													55	
A4	W	N	L	10	E	т	11							57	

VEHICLE VOLUMES

Line		Appr Road					-		APPROACH	
туре	Class	Locn	S	SE	E	NĒ	N	NW	W	SW
A5	TOT	S			508		1 136			
A5	8HV	S			0		0			
A5	TOT	Ë								
A5	8HV	E								
A5	TOT	Ň								
A5	8HV	N								
A5	TOT	W			2208		525			
A5	%HV	W			0		0			

PEDESTRIAN VOLUMES

Line	Vol.	of	Pedes	trians	in	Front	of	Appro	ach	
Туре	S		SE	E	NE	E N		NW	W	SW
A6	312		1	.43		135		3	10	

LANE DATA

	Appr				\mathtt{SL}	Lane	Basic	Lane	SL	No.of	Bus
Line	Road	Lane	Lane	Lane	Length	Width	Satn	Util	Green	Park	Stops
Туре	Locn	No.	Dis.	Type	(m)	(CM)	Flow	(8)	Const	Manvs	/hour
Å8	S	1	Т	1	N*	300	1950	100	N	N	N
A8	S	2	Т	1.	N*	300	1950	100	N	N	N
A8	S	3	Ť	1	N*	300	1950	100	N	N	N
A8	S	4	TR	1	N*	300	1950	100	N	N	N
A8	S	5	R	1	N*	300	1950	100	N	N	Ň
A8	W	1	L	1	N*	300	1950	1.00	N	N	N
A8	W	2	\mathbf{LT}	1	N*	300	1950	100	N	N	N
A 8	W	3	т	1	N*	300	1950	100	N	N	N
A 8	W	4	Т	1	N*	300	1950	100	N	N	N
A8	W	5	Т	1	N*	300	1950	100	N	N	N

SHARED LANE DATA

			F.	IRST MO	OVEMENT		S	ECOND 1	40VEMEN	T
	Appr			Free	Basic	SL		Free	Basic	\mathbf{SL}
Linc	Road	Lanc	Mov	Queue	Satn	Grn	Mov	Queue	Satn	Grn
Type	Locn	No.	No.	(veh)	Flow	Con	No.	(veh)	Flow	Con
A9	S	4	2	0	1950	N	3	0	1950	N
A9	W	2	10	0	1950	N	11	0	1950	N

PHASE DATA

			Opd		Opd		Opd		Opd		Opd		Opd		Opd
Line	Phase	Mov	Ped	Mov	Ped	Mov	Ped	Mov	Ped	Mov	Ped	Mov	Ped	Mov	Ped
Туре	Name	No.	Dum	No.	Dum	No.	Dum	No.	Dum	No.	Dum	No.	Dum	No.	Dum
A14	А	10		11											
A14	В	2		3											
A14	С	51	Ρ	53	P	55	Р	57	Ρ						
A14	D	55	P												
A14	Е	57	Р												
A14	F	51	Р	11											
A14	н	3		57	Р										
A14	J	51	Ρ	55	P	11									
Unde	r Opd/P	ed/Dum:	L,T	, R=Op	posed	i tu	rns,	P=Pec	destr	ian,	D=Du	mmy			

PHASE SEQUENCE DATA

Line Type						Pha Nam		
A15	1	А	в	С				
A15	2	С	D	Ε	F			

A15	3	Н	J		
A15	4	Е	H	D	J
A15	5	E	Н	F	J
A15	6	С	Н	D	Ĵ
A15	7	С	н	F	J

CURRENT PHASE SEQUENCE

	Phase
Line	Seq.
Type	No.
A16	1
ALO	T

NEGOTIATION RADIUS (GEOMETRIC DATA)

Line	Appr Road	Ne	gotiat:	ion ra	dius	for	tra	ffic	exiting	TO APPRO	ACH
Туре	Locn	S	SE	E	NE		N	NW	W	SW	
A21	S			P			P				
A21	W			P			P				

NEGOTIATION SPEED (GEOMETRIC DATA)

Line	Appr Road	Ne	gotiat	ion sp	eed for	traf	fic exi	ting	TO APPROACH	I
Type	Locn	S	SE	Е	NĒ	N	NW	W	SW	
A22	S			Р		Р				
A22	W			Р		P				

NEGOTIATION DISTANCE (GEOMETRIC DATA)

Line	Appr Road		Negotiat:	ion di	istance	for	traffic	exiting	j TO	APPROACH	
Type	Locn	S	SE	E	NĖ	N	NW	W	SW		
A23	S			P		P					
A23	W			P		р					

MOVEMENT DATA: PHASE AND TIMING PARAMETERS (Mov.Type: P=Pedestrian, D=Dummy, U V W=Undetected, C=Continuous) F I R S T G R E E N

Line	Mov.	Mov.	From	То	Inter-	Start	End	Mìn.	Max.
Туре	Туре	No.	Phase	Phase	Green	Loss	Gain	Green	Green
4		2	B	С	6	3	3	6	N
4		3	в	С	6	3	3	6	N
4	Р	51	С	А	6	2	-8	16	N
4	Р	53	С	A	6	2	-8	16	N
4	. P	55	C	A	6	2	-8	16	N
4		10	A	В	6	3	3	6	N
4		11	A	в	6	3	3	6	N
4	P	57	С	A	6	2	-8	16	N

MOVEMENT DATA (2)

		Satn	Flow				Turn Type Radius/Pe	
Line	Mov	1 s t	2nd	Prac.	Grad.			
Туре	No.	Grn	Grn	Deg.Satn	(%)		LR	
5	2			90	0	0	0 0	
5	3			90	0	0	0 0	
5	51	12000		90		0		
5	53	12000		90		0		
5	55	12000		90		0		
5	10			90	0	0	0 0	

5	11		90	0	0	0	0
5	57	12000	90		0		

OPPOSED TURN PARAMETERS

Line	Opsd		Crit	Fol.up	Deps	Exit
Туре	Mov	Opsd	Gap	Hdway	at End	Flow
	No.	Turn	(*10)	(*10)	(*10)	(%)
7	3	R	40	24	. 25	0
7	10	\mathbf{L}	45	26	22	0

MOVEMENT GROUPING DEFINITION

Line	Grp	Mov		GROUP	DESCRIPTION								
Type	No.												
11	1	2	3							mcD			
11	2	10	11							bcb			
11	3	51	53	55	57					Ped	estria	rs	

DATA FOR MOVEMENT GROUPINGS

Line	Group	Flow	Delay	Stop	Queue		
Туре	No.	Scale	Weight	Weight	Weight		
		웅	100w1	100w2	100w3		
12 2	1	100	100	100	100	0	0
12 2	2	100	100	100	100	0	0
12 2	3	100	100	100	100	0	0

DATA FOR FUEL/EMISSIONS/COST

Group	Idling	Steady	Speed	Veh.	Power	Coeffs.	Alphar	numeric
No.	Rate			Mass	(*1)	0E4)	Descri	ption
	(/h)	A	в	(kg)				
			(*10E5)		Beta1	Beta2	Name	Unit
1	All para	meters	program	calcul	ated			
2	All para	meters	program	calcula	ated			
3	All para	meters	program	calcul	ated			
			-					

MOVEMENT DATA (1)

		Appr	oach 		Queue Space (cm/veh)				PHF *100	Arrival & Control
Line	Mov	Speed	Dist.							Туре
Туре	No.	(km/h)	(m)			r_{Λ}	HV			& Coord.
15	2	60	500	0	0	700	1300	0	95	3 <i>e</i> n
15	3	60	500	0	0	700	1300	0	95	3FN
15	51	4	10	0	0	100	0	0	95	3FN
15	53	4	10	0	0	100	0	0	95	3FN
15	55	4	10	0	0	100	0	0	95	3FN
15	10	60	500	0	0	700	1300	0	95	3FN
15	11	60	500	0	0	700	1300	0	95	3FN
15	57	4	10	0	0	100	0	0	95	3 FN

GREEN SPLIT PRIORITY

Line Ap	plic-	Mov.	Pri.								
---------	-------	------	------	------	------	------	------	------	------	------	------

Type 20	able? N	No. Coo	ie No.	Code		Code	No.	Code	No.	Code
20	10	• •	•	•	•	•	•	•	•	•
VARIAB	LE CYCLE	TIME DATA								
				СҮС	СЬЕ	ΤI	MES			
Line	User/									
Туре	Prog	1st 2nd 3	Brd 4th 5	oth 6th	7th 8	th 9th	. 10th	11th 12	2th 13	th 14th
21	N	150	10							
VARIAB	LE FLOW	SCALE DATA								
					FL	οw	SCA	LES		
Line	User/	Groups								
	Prog		1st 2n	d 3rd	4th 5t	h 6th	7th 8t	h 9th 3	10th 1	lth 12th
22	N		100 12							
			200 12							
End of	Input D	ata Listino	from fi	le:						
		p\fyp2\aaS			ll-red	pedes	trian	cross\a	aileen	2.DAT
····	7					£				

RUNTIME INFORMATION

Undertaking aaSIDRA run: fixed-time basis

Calculating Capacities and Timings Main Iteration No. 0 Main Iteration No. 1 Calculating Performance Results and Writing Main Output File: G:\pelajaran\fyp\fyp2\aaSIDRA Projects\all-red pedestrian cross\aileen2.OUT

aaSIDRA OUTPUT DATA

LOCATION 2

Akcelik & Associates Pty Ltd - aaSIDRA 2.0.1.206 _____ _____ utp Registered User No. a1061 aileen Licence Type: Educational, Multi Computer 3:26 AM, 8 May 2006 Time and Date of Analysis Filename: G:\pelajaran\fyp\fyp2\aaSIDRA Projects\all-red pedestrian cross\aileen2.0UT fixed-time basis iln sultan idris shah Intersection ID: RUN INFORMATION * Basic Parameters: Intersection Type: Signalised - Fixed Time Driving on the right-hand side of the road Input data specified in Metric units Default Values File No. 30 Peak flow period (for performance): 15 minutes Unit time (for volumes): 60 minutes (Total Flow Period) Delay definition: Control delay Geometric delay included aaSIDRA Standard Delay and Queue models used Level of Service based on: Delay (HCM method) Queue definition: Back of queue, 95th Percentile * No. of Main (Timing-Capacity) Iterations = 1 Comparison of last two iterations: Difference in intersection degree of sath = 0.0 % Difference in total vehicle capacity = 0.0 % Largest difference in eff. green times = 0 secs (max. value for stopping = 0 secs) fixed-time basis jln sultan idris shah Intersection ID: DEFAULT PARAMETERS _____ Default values for some of the important general parameters: (Default Values File: DEF30.SDF) 1. Basic saturation flow: 1950 tcu/h This value applies mainly to signalised intersections. For roundabouts and sign-controlled intersections, it is used for determining capacity of priority and continuous movements.

•	opposed turn	parameters	(Signalised	a inters	ection)
		Crit.	Fol.up	Deps	% Exit Flow
		Ġap	Hdway	at End	Opposing
	Left turn	s: 4.5	2.6	2.2	0
	Right tur	ns: 4.0	2.4	2.5	0

4. Cruise speed= 60 km/h, Approach Distance= 500 m

5. Queue space per vehicle in metres Light vehicles: 7.0 Heavy vehicles: 13.0

A full list of input data defaults and ranges is given in the Input Guide part of aaSIDRA User Guide.

fixed-time basis jln sultan idris shah Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.0 - TRAFFIC FLOW DATA -----------Left Through Right Flow Peak Motz Scale Flow TA HA TA HA TA HA No. Factor VEHICLES Demand flows in veh/hour as used by the program South: mcD 0 1196 0 л 0 n 1.00 0.95 2 Ő 0 0 0 535 3 0 1.00 0.95 _____ West: bcb 10 11 -----PEDESTRIANS Flow (ped/hour) 1.00 51 328 0.95 53 151 1.00 0.95 55 142 1.00 0.95 57 1.00 326 0.95 ____ _____ Based on unit time = 60 minutes. Flow Scale and Peak Hour Factor effects included in flow values. fixed-time basis jln sultan idris shah Intersection ID: Fixed-Time Signals, Cycle Time = 80 Table S.1 - MOVEMENT PHASE AND TIMING PARAMETERS PHASE MATRIX Mov Lost Tim Req.Mov.Time Eff. Grn Mov First GreenSecond Green------------1st 2nd 1st2ndFr To Op PrFr To Op PrGrn Grn Grn Grn Grn Grn No. Typ First Green Second Green -----_____ ----South: mcD 2 Т *B C 6 22.3 17 6 22.3 6 22.3 3 R вс 17 _____ ____ _____ _____ West: bcb 10 L A B 11 T *A B 6 32.8 6 32.9 29 29 Pedestrians 51 (Ped)*C A 53 (Ped) C A 16 22.0Min 6 22.0Min 16 6 55 (Ped) C A 57 (Ped) C A 16 22.0Min 16 22.0Min 6 6 Current Phase Sequence No.: 1 Input phase sequence: A B C Output phase sequence: A B C

Moveme	nt Types:				U	nder	heading 'Op':
Ped	Pedestrian					L	"Left" turns
Dum	Dummy					R	"Right" turns
Und	Undetected	in bo	th gree	n period	3	LR	"Left and Rig
Unl	Undetected	in 1s	t green	period		С	"Constant" sa
Un2	Undetected	in 2n	d green	period			
			-	-			

Fixed-Time Signals, Cycle Time = 80

: are opposed s are opposed

ght" opposed aturation flow

Table S.2 - MOVEMENT CAPACITY PARAMETERS

Mov No.	Dem Flow		Flow	Flow	Ratio	Total Cap.	Prac. Deg.	Prac. Spare	Lane Util	Deg. Satn
NO.	(veh /h)	1st Grn	2nd Grn	1st Grn	2nd	(veh	Satn xp	Cap.	(%)	x
South: n	cD									
2 Т	1196	6541		0.183		1390	0.90	5	100	0.860*
3 R	535	2926		0.183		622	0.90	5	100	0.860*
West: bo	b									
10 L	553	1831		0.302		664	0.90	8	100	0.833
11 T	2324	7691		0.302		2788	0.90	8	100	0.834
Pedestr	ians									
51	328	12000		0.027		900	0.90		100	0.364
53	151	12000		0.013		900	0.90		100	0.168
55	142	12000		0.012		900	0.90		100	0.158
57	326	12000		0.027		900	0.90		100	0.362

fixed-time basis

fixed-time basis jln sultan idris shah Intersection ID:

jln sultan idris shah

Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.3 - INTERSECTION PARAMETERS

Mov	App.	Green Period			Adjusted Lost	Adjusted Flow	Required Grn Time	Required Movement
NO.	Turn		Fr	То	Time	Ratio	Ratio	Time
11	W_T		 A	в	6	0.302	0.336	32.9
2	ST		В	С	6	0.183	0.203	22.3
51	S_Ped		С	А	22	-	-	22.0Min
					-		-	
				Total:	34	0.485	0.539	77.1

- Flow ratio not used for cycle time calculations and the adjusted lost time equals the required movement time (=Min or Max as shown in Table S.1)

Cycle Time: Minimum 46	Maximum 150	Practical 74	Chosen 80		
Intersectio	on Level of	5 Service		÷	D
Worst movem	ent Level	of Service		=	Ď
Average int	ersection	delay (s)		=	36.5
Largest ave	erage movem	ment delay	(s)	=	50.2
Largest bad	k of queue	e, 95% (m)		=	167
Performance	Index			=	253.02

Degree of saturation (highest)	=	0.860	
Practical Spare Capacity (lowest)	-	5	ያ
Total vehicle capacity, all lanes (veh/h)	=	5463	
Total vehicle flow (veh/h)	=	4608	
Total pedestrian flow (ped/h)	=	947	
Total person flow (pers/h)	=	7859	
Total vehicle delay (veh-h/h)	#	47.13	
Total pedestrian delay (ped-h/h)	=	9.00	
Total person delay (pers-h/h)		79.69	
Total effective vehicle stops (veh/h)	=	4549	
Total effective pedestrian stops (ped/h)	×	876	
Total effective person stops (pers/h)	=	7699	
Total vehicle travel (veh-km/h)	=	2790.6	
Total cost (\$/h)	=	2387.88	
Total fuel (L/h)	=	366.7	
Total CO2 (kg/h)		916.81	

fixed-time basis jln sultan idris shah Intersection ID: Fixed-Time Signals, Cycle Time = 80

Table S.4 - PHASE INFORMATION

Phase No.	Change Time	Green Start	Displayed Green		Intgrn Prop.
Ä	0	<u>-</u>	29	35	0.438
в	35	41	17	23	0.287
С	58	64	16	22	0.275
	······································				

Current Phase Sequence No.: 1 Input phase sequence: A B C Output phase sequence: A B C

fixed-time basis jln sultan idris shah

Intersection ID: Fixed-Time Signals, Cycle Time = 80

Table S.5 - MOVEMENT PERFORMANCE

Mov No.		Total Delay (pers-h/h	Delay	Prop. Queued	Eff. Stop Rate		ick	Perf. Index	Aver. Speed (km/h)
South: n	ncD								
2 Т	13.59	20.38	40.9	1.00	1.01	16.6	116	64.56	28.2
3 R	7.45	11.18	50.2	1.00	1.01	16.2	113	30.28	25.1
West: bo						* == += += += = = = = = = =			
10 L	6.25	9.38	40.7	0.97	0.99	22.9	160	28.61	28.2
11 T	19.83	29.75	30.7	0.98	0.97	23.8	167	113.33	32.5
Pedesti	ians			لفلة علو حيد عله عزم عليه عيد		•			
51	3.12	3.12	34.2	0.92	0.93	1.4	1	5.62	0.8
53	1.44	1.44	34.2	0,92	0.93	0.6	1	2.59	0.8
55	1.35	1.35	34.2	0.92	0.93	0.6	1	2.43	0.8
57	3.10	3.10	34.2	0.92	0.93	1.4	1	5.59	0.8

fixed-time basis jln sultan idris shah Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.6 - INTERSECTION PERFORMANCE

	Satn x	Total Delay (veh-h/h) (Delay pers-h/h	Delay (sec)	Queued	Stop Rate	Queue (m)	Index	Speed (km/h)
South: 1 1731	ncD 0.860	21.04	31.56	43.8	1.000	1.01	116	94.84	27.2
West: b 2877	cb 0.834	26.09	39.13	32.6	0.980	0.97	167	141.94	31.6
Pedest: 947	rians 0.364	9.00	9.00	34.2	0.925	0.93	1	16.24	0.8
ALL VEH	ICLES: 0.860	47.13	70.69	36.8	0.987	0.99	167	236.78	29.8
INTERSE	CTION	(persons):							
Queue va	alues j	In this tab	le are 9	5% back	of que	 ue (me	etres).		

fixed-time basis

jln sultan idris shah

Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.7 - LANE PERFORMANCE

Lane	Mov	Gree	n Ti	mes (s	sec)	(veh	(veĥ	Satn	Aver. Delay	Stop	95% 	e u e Back	
No.	No.	R1	G1	R2	G2	/h)	/h)	х	(sec)	Rate	(vehs) (m)	(m)
South:	mcD												
1 T	2	63	17	0	0	352	409 0	.860	40.9	1.01	16.6	116	
2 Т	2	63	17	0	0	352	409 0	.860	40.9	1.01	16.6	116	
3 Т	2	63	17	Ó	0	352	409 0	.860	40.9	1.01	16.6	116	
4 TR	2,	63	17	0	0	342	397 0	.860	46.3	1.01		113	
•	3			-	-								
5 R	3	63	17	0	0	335	389 0	.860	50.2	1.01	16.0	112	÷
West:	 bcb												
1 L	10	51	29	0	0	553	664 0	.833	40.7	0.99	22.9	160	
2 Т	10,	51	29	0	0	581	697 0	.834	30.7	0.97	23.8	167	
	11	01		· ·	•	001	••••		001			107	
ЗТ	11	51	29	0	0	581	697 0	.834	30.7	0.97	23.8	167	
4 T	11	51	29	Ó	0	581	697 0	.834	30.7	0.97	23.8	167	
5 Т	11	51	29	Ō	Ō	581	697 0	.834		0.97		167	

fixed-time basis jln sultan idris shah Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.8 - LANE FLOW AND CAPACITY INFORMATION

				Satura	tion	Flow	End	Tot		
Lan	Mov	Dem Flow (veh/h)	Lane	Adj.	Aver	Aver	Cap	Cap	Deg.	Lane
No.	No.		Width	Basic	1st	2nd	(veh	(veh	Satn	Util
		Lef Thru Rig Tot	(m)	(tcu)	(veh)	(veh)	/h)	/h)	x	8
	•••••••••									

South: 1 T 2 T	2 2	0	352 352	0	352 352	3.00	1923 1923	1923	0	0	409	0.860	100 100
3 T 4 TR	2 2,	0 0	352 141	0 200	352 342	3.00 3.00	1923 1923		0	0 0		0.860	$\begin{array}{c} 100 \\ 100 \end{array}$
4 110	3	Ŭ	T T T	200	J12	3.00	1920	1000	U	Ŷ	55,	0.000	100
5 R	3	0	0	335	335	3.00	1923	1831	0	0	389	0.860	100
West:													
1 L	10	553	0	0	553	3.00	1923	1831	0	0	664	0.833	100
2 Т	10, 11	0	581	0	581	3.00	1923	1923	0	0	697	0.834	100
3 т	11	0	581	0	581	3.00	1923	1923	0	0	697	0.834	100
4 T	11	0	581	0	581	3.00	1923	1923	0	0	697	0.834	100
5 т	11	0	581	0	581	3.00	1923	1923	0	0	697	0.834	100

Basic Saturation Flow in this table is adjusted for lane width, approach grade, parking manoeuvres and number of buses stopping. Saturation flow scale applies if specified.

Table S.10 - MOVEMENT CAPACITY AND PERFORMANCE SUMMARY

Mov No.	Mov	Dem Flow	Total	Lane Util	Deg. Satn	Eff.			Eff.	95% Back of	Perf.
NO.	Тур	(veh	Cap. (veh			1st	2nd	Delay	Stop Rate	Back of Queue	Index
		/h)	/h)	(5)	x -	Grn		(sec)		(veh)	
South:	mcD										
2 T		1196	1390	100	0.860*	17*		40.9	1.01	16.6	64.56
3 R		535	622	100	0.860*	17		50.2	1.01	16.2	30.28
West: b	cb										
10 L		553	664	100	0.833	29		40.7	0.99	22.9	28.61
11 T		2324	2788	100	0.834	29*		30.7	0.97	23.8	113.33
Pedest	rians										
51	(Ped)	328	900	100	0.364	6*		34.2	0.93	1.4	5.62
53	(Ped)	151	900	100	0.168	6		34.2	0.93	0.6	2.59
55	(Ped)	142	900	100	0.158	6		34.2	0.93	0.6	2.43
57	(Ped)	326	900	100	0.362	6		34.2	0.93	1.4	5.59

* Maximum degree of saturation, or critical green periods

fixed-time basis

jln sultan idris shah

Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.12A -	FUEL CONS	UMPTION,	EMISSIO	NS AND CO	ost - to:	FAL
Mov No.	Fuel Total L/h	Cost Total \$/h	HC Total kg/h	CO Total kg/h	NOX Total kg/h	CO2 Total kg/h
South: mcD						
2 T 3 R	96.7 46.3	599.59 317.11	0.440 0.217	19.33 8.92	0.554 0.253	241.8 115.8
	143.0	916.70	0.658	28.25	0.807	357.6

West: bcb 10 L 11 T	46.1 177.6		•••	9.12 36.49	0.258 1.049	
	223.7	1314.26	1.008	45.62	1.307	559.2
Pedestrians 51 53 55 57		54.35 25.02 23.53 54.02				
		156.91				
ALL VEHICLES:	366.7	2230.97	1.666	73.87	2.113	916.8
INTERSECTION:	366.7	2387.88	1.666	73.87	2.113	916.8

PARAMETERS USED IN COST CALCULATIONS

Pump price of fuel (\$/L) Fuel resource cost factor	=	0.850 0.50
Ratio of running cost to fuel cost	=	3.0
Average income (\$/h)	=	23.00
Time value factor	=	0.60
Average occupancy (persons/veh)	=	1.5
Light vehicle mass (1000 kg)	=	1.4
Heavy vehicle mass (1000 kg)	#	11.0
Light vehicle idle fuel rate (L/h)	=	1.350
Heavy vehicle idle fuel rate (L/h)	=	2.000

The idle fuel and vehicle mass parameters given above are the default values (data given in RIDES may override some of these parameters).

fixed-time basis jln sultan idris shah Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.12B - FUEL CONSUMPTION, EMISSIONS AND COST - RATE

Mov No.	Rate	Cost Rate \$/km	Rate		NOX Rate g/km	Rate
South: mcD						
2 Т	13.3	0.83	0.607	26.65	0.764	333.4
3 R	14.4	0.98	0.674	27.68	0.784	359.3
	13.7	0.88	0.628	26.97	0.770	341.4
West: bcb	نېې بېږ 🖬 دک کان کار کار کار د					
10 L	13.8	0.89	0.641	27.35	0.774	345.6
11 T	12.6	0.72	0.564	25.89	0.744	314.9
	12.8	0.75	0.579	26.17	0.750	320.8
Pedestrians			••••••••••••••••••••••••••••••••••••••			
51		16.57				
53		16.57				
55		16.57				
57		16.57				
		16.57				

ALL VEHICLES:		-				
INTERSECTION:	13.1	0.85	0.597	26.47	0.757	328.5

fixed-time]	basis					
jln sultan :	idris shah					
Intersection	n ID:					
	Fixed-Time	Signals,	Cycle	Time	=	80

Table S.14 - SUMMARY OF INPUT AND OUTPUT DATA

Lane No.	Dema L	and Fl T	ow (v R			Basic	Eff Grn (secs) 1st 2nd	Sat	Delay	Longest Queue (m)	Shrt Lane (m)
South	mcD									*	
1 T		352		352	0	1922	17	0.860	40.9	116	
2 Т		352		352	0	1922	17	0.860	40.9	116	
3 Т		352		352	Ö	1922	17	0.860	40.9	116	
4 TR		141	200	342	0	1923	17	0.860	46.3	113	
5 R			335	335	0	1923	17	0.860	50.2	112	
	 0	1196	535	1731	0			0.860	43.8	116	
West:	bcb						•• •• •• •• •• •• •• ••				
1 L	553			553	0	1922	29	0.833	40.7	160	
2 Т		581		581	0	1923	29	0.834	30.7	167	
3 Т		581		581	0	1923	29	0.834	30.7	167	
4 T		581		581	0	1923	29	0.834		167	
5 T		581		581	0	1923	29	0.834	30.7	167	
	553	2324	0	2877	0			0.834	32.6	167	
Pedest	rians	3									
Acros	38 S 8	pproa	ch	328			6		34.2		
Acros	ss E a	approa	ich	151			6	0.168	34.2	0.6	
Acros	s N a	approa	ch	142			6		34.2	0.6	
Acros	ssW a	approa	ch	326			6	0.362	34.2	1.4	
ALL VE	EHICLE	ES	 	Total	 8		Cycle	Max	Aver.	Max	
				Flow	ΗV		Time	Х	Delay	Queue	
				4608	0		80 ===========	0.860	36.8	167	
Total i	Elow p	period					low peric				

for a set and the set of the set

Queue values in this table are 95% back of queue (metres).

Note: Basic Saturation Flows (in through car units) have been adjusted for grade, lane widths, parking manoeuvres and bus stops.

fixed-time basis

jln sultan idris shah

Intersection ID:

Fixed-Time Signals, Cycle Time = 80

Table S.15 - CAPACITY AND LEVEL OF SERVICE

Mov No.	Моч Тур	Ratio 1st	(g/C)	Total Flow (veh /h)	Total Cap. (veh /h)	Deg. of Satn (v/c)	Aver. Delay (sec)	LOS
South: 2 T		0.213*		1196	1390	0.860*	40.9	D

3 R	0.213	535	622	0.860*	50.2	D				
		1731	2012	0.860	43.8	D				
West: bcb										
10 L 11 T	0.363 0.363*	553 2324	664 2788	0.833 0.834	40.7 30.7	D C				
		2877	3452	0.834	32.6	c				
Pedestrians 51 (Ped) 53 (Ped) 55 (Ped)	0.075	328 151 142	900 900 900	0.364 0.168 0.158 0.362	34.2 34.2 34.2	D D D				
55 (Ped) 57 (Ped)	0.075	326	900	0.362	34.2	D				
				0.364						
ALL VEHICLE	s:	4608	5463	0.860	36.8	D				
INTERSECTIO	ON (persons):	7859	5463	0.860	36.5					
average independ For the aaSIDRA Intersed	f Service calc control delay dent of the cu criteria, ref Output Guide ction capacity v/c ratio, or	r includi arrent de Ser to th or the C r is calc	ng geome lay def: e "Leve utput se ulated o	etric dela inition us l of Servi ection of consideria	sed. ice" top the on-	ic in the line help				
jln sultan io Intersection I	fixed-time basis jln sultan idris shah Intersection ID: Fixed-Time Signals, Cycle Time = 80 Table D.0 - GEOMETRIC DELAY DATA									
From Approach	To F Approach	adius Sp	eed Di	gn Appr. st. Dist. n) (m)	. Dist	tream ance m)				
South mcD										

From Approach	To Approach	Negn Radius (m)	Negn Speed (km/h)	Negn Dist. (m)	Appr. Dist. (m)	Downstream Distance (m)
South: mcD						
	East	10.0	18.5	15.7	500	102
	North	S	60.0	19.5	500	106
West: bcb						
	East	S	60.0	19.5	500	106
	North	5.0	13.1	10.0	500	103

Downstream distance is distance travelled from the stopline until exit cruise speed is reached (includes negotiation distance). Acceleration distance is weighted for light and heavy vehicles. The same distance applies for both stopped and unstopped vehicles.

fixed-time basis jln sultan idris shah Intersection ID: Fixed-Time Signals, Cycle Time = 80

Table D.1 - LANE DELAYS

						Delay	(second	ds/vel	n)		
		Deg.	Stop-	line	Delay	Acc.	Queu:	ing	Stopd		
Lane	Mov	Satn	lst	2nd	Total	Dec.	Total	MvUp	(Idle)	Geom	Control
No.	No.	х	d1	d2	dSL	dn	dq	dqna	di	dig	dic

South:	mcD										
1. T	2	0.860	33.8	7.1	40.9	8.6	32.3	2.2	30.1	0.0	40.9
2 Т	2	0.860	33.8	7.1	40.9	8.6	32.3	2.2	30.1	0.0	40.9
3 Т	2	0.860	33.8	7.1	40.9	8.6	32.3	2.2	30.1	0.0	40.9
4 TR	2,	0.860	33.8	7.3	41.1	5.8	35.3	2.2	33.1	0.0	46.3
	3									9.0	
5 R	3	0.860	33.8	7.4	41.2	3.8	37.4	2.2	35.2	9.0	50.2
West: 1	bcb										
1 L	10	0.833	25.4	5.6	31.0	2.8	28.2	1.2	27.0	9.7	40.7
2 Т	10,	0.834	25.4	5.3	30.7	8.4	22.3	1.2	21.2	0.0	30.7
	11									0.0	
3 Т	11	0.834	25.4	5.3	30.7	8.4	22.3	1.2	21.2	0.0	30.7
4 Т	11	0.834	25.4	5.3	30.7	8.4	22.3	1.2	21.2	0.0	30.7
5 T	11	0.834	25.4	5.3	30.7	8.4	22.3	1.2	21,2	0.0	30.7
dn is	aver	age sto	p-start	dela	y for a	all ve	hicles	queue	d and	unqueu	 ed

fixed-time basis jln sultan idris shah Intersection ID: Fixed-Time Signals, Cycle Time = 80

Table D.2 - LANE STOPS

Lane No.	Deg. Satn x	Ef he1	fectiv he2	e Stop Geom. hig	Rate Overall h	Prop. Queued pq	Queue Move-up Rate hqm
South 1 T 2 T 3 T 4 TR 5 R	: mcD 0.860 0.860 0.860 0.860 0.860 0.860	0.85 0.85 0.85 0.85 0.85	0.16 0.16 0.16 0.16 0.16	0.00 0.00 0.00 0.00 0.00	1.01 1.01 1.01 1.01 1.01	1.000 1.000 1.000 1.000 1.000	0.27 0.27 0.27 0.28 0.28
West: 1 L 2 T 3 T 4 T 5 T	bcb 0.833 0.834 0.834 0.834 0.834 0.834	0.87 0.87 0.87 0.87 0.87 0.87	0.11 0.10 0.10 0.10 0.10 0.10	0.02 0.00 0.00 0.00 0.00	0.99 0.97 0.97 0.97 0.97 0.97	0.979 0.980 0.980 0.980 0.980 0.980	0.15 0.14 0.14 0.14 0.14 0.14

hg is the average value for all movements in a shared lane hqm is average queue move-up rate for all vehicles queued and unqueued

Table D.3 - LANE QUEUES

Tana	Deg. Satn	Ovrfl.	Avera	age (ve	eh)		Perce	ntile	(veh)		Queue
Lane No.	X	Queue - No	Nb1	Nb2	Nb	70%	85%	90%	95%	988	Stor. Ratio
South	: mcD										
1 T	0.860	0.7	8.4	1.1	9.5	11.5	13.7	14.9	16.6	18.2	0.23
2Т	0.860	0.7	8.4	1.1	9.5	11.5	13.7	14.9	16.6	18.2	0.23
ЗТ	0.860	0.7	8.4	1.1	9.5	11.5	13.7	14.9	16.6	18.2	0.23
4 TR	0.860	0.7	8.1	1.1	9.2	11.2	13.3	14.6	16.2	17.9	0.23
5 R	0.860	0.7	8.0	1.1	9.1	11.0	13.1	14.3	16.0	17.6	0.22

West: bcb 0.833 0.9 12.3 1.5 13.8 16.6 19.5 21.1 22.9 24.7 0.32 1 L 1.514.417.320.422.023.825.60.331.514.417.320.422.023.825.60.331.514.417.320.422.023.825.60.331.514.417.320.422.023.825.60.331.514.417.320.422.023.825.60.33 0.834 0.9 12.9 2 T 0.834 0.9 12.9 0.834 0.9 12.9 0.834 0.9 12.9 0.834 0.9 12.9 3Т 4 T 5 T 0.834 0.9 _____ Values printed in this table are back of queue (vehicles). fixed-time basis jln sultan idris shah Intersection ID: Fixed-Time Signals, Cycle Time = 80 Table D.4 - MOVEMENT SPEEDS (km/h) _____ Queue Move-up App. Speeds Exit Speeds Mov -----Av. Section Spd 1st 2nd _____ No. Cruise Negn Negn Cruise Grn Grn Running Overall South: mcD 2 60.0 60.0 60.0 60.0 30.9 3 60.0 18.5 18.5 60.0 30.3 46.3 28.2 46.3 28.2 42.4 25.1 _____ ----West: bcb
 10
 60.0
 13.1
 13.1
 60.0
 39.4

 11
 60.0
 60.0
 60.0
 60.0
 40.4
 28.2 32.5 43.5 47.5 "Running Speed" is the average speed excluding stopped periods. fixed-time basis jln sultan idris shah Intersection ID: Fixed-Time Signals, Cycle Time = 80 Table D.5 - PROGRESSION FACTORS & ACTUATED SIGNAL PARAMETERS Delay Queue Disp. Grn. Settings Mov Arrival Prog. Prog. 1st Grn 2nd Grn No. Control Coord. Type Factor Factor Gmin Gmax Gmin Gmax _____ _____ South: mcD 2 FT NO 3 1.000 1.000 6 NA 3 FT NO 3 1.000 1.000 6 NA _____ West: bcb
 10
 FT
 No
 3
 1.000
 1.000
 6
 NA

 11
 FT
 No
 3
 1.000
 1.000
 6
 NA
 _____ -----_____ Pedestrians
 51
 FT
 No
 3
 1.000
 1.000

 53
 FT
 No
 3
 1.000
 1.000

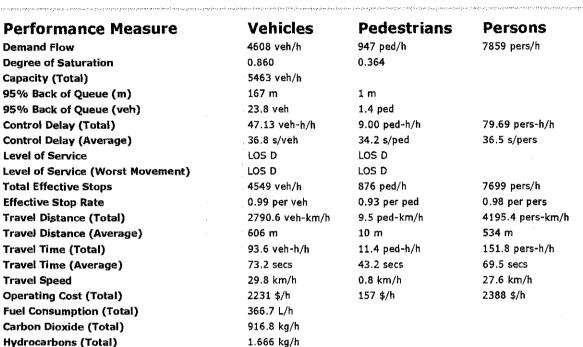
 55
 FT
 No
 3
 1.000
 1.000

 57
 FT
 No
 3
 1.000
 1.000
 57 _____

--- End of aaSIDRA Output ---

Intersection Summary

fixed-time basis



73.87 kg/h

2.113 kg/h

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Carbon Monoxide (Total)

NOX (Total)

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akcelik & associates aa Traffic SIDRA

Movement Summary



fixed-time basis

Signalised - Fixed time Cycle Time = 80 seconds

Vehicle Movements

Mov No	Turn	Dem Flow (veh/h)	Cap (veh/h)	Deg of Satn (v/c)	Aver Delay (sec)	Level of Service	95% Back of Queue (m)	Eff. Stop Rate	Aver Speed (km/h)	Oper Cost (\$/h)
ncD	n dan na garan garan garaka gara	e possi pose provi possi done boso pode dona	n Serder Server Johan group serve Server Server	an panan panén dinan panén dinan dinén di	na tana tanà tanà taon taon taon ta	n 2000 - 2000 2000 2000 2000 2000 200	in fann fa de finne fann fann fan senne	de van de der die kaar die de die die die die die die die die	n pone provenské pone provenské přek pr	de found for the formal sector f
2	Т	1196	1390	0.860	40.9	LOS D	116	1.01	28.2	600
3	R	535	622	0.860	50.2	LOS D	113	1.01	25.1	317
Approach		1731	2012	0.860	43.8	LOS D	116	1.01	27.2	917
ocb	na hayan yan yan yan yan yan ya	ale faile faile faile faile faile faile faile faile	net their fille drakes a finale teach teach	ana dan basi basi dan basi dan basi	Andreiten förde förer sockenen s	ase to ye teestin oo e tinge tin af federi	na franciski hilofoto Degeroa	a naga maga naga maga talap talap t	de true contrato de la contrato de la des	ite a coda treve fode dreve
10	Ł	553	664	0.833	40.7	LOS D	160	0.99	28.2	298
11	т	2324	2788	0.834	30.7	LOS C	167	0.97	32.5	1016
Approach	te to be considered as the co	2877	3452	0.834	32.6	LOS C	167	0.97	31.6	1314
All Vehicles		4608	5463	0.860	36,8	LOS D	167	0.99	29.8	2231

Pedestrian Movements

lov No	Dem Flow (veh/h)	Aver Delay (sec)	Level of Service	95% Back of Queue (m)	Eff. Stop Rate	Oper Cost (\$/h)
51	328	34.2	LOS D		0.93	54
53	151	34.2	LOS D	1	0.93	25
55	142	34.2	LOS D	1	0.93	24
57	326	34.2	LOS D	1	0.93	54
Peds	947	34.2	LOS D	1	0.93	157

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