## CHAPTER 4

## RESULTS AND DISCUSSION

### 4.1 Introduction

This chapter presents results of the experimental work and field measurements, and discusses the findings of this research. The results consist of total station calibration, datum verifications, error propagation in angle, distance, elevation and, sight shot observations for monitoring data and statistical analysis for slope deformation monitoring.

### 4.2 Total Station Calibration

It could not be denied that measurement with electronic measurement tools such as Electronic Distance Measurement (EDM) or Total Station is more accurate relative to other methods of measurement such as Global Positioning System(GPS), close range photogrammetry, precise leveling, Total Station, laser scanning (terrestrial survey), Very Long Baseline Interferometic(VLBI), Image by Interferometic Survey(IBIS) and Satellite Laser Ranging (SLR), because the electronic measurement tool is able to produce a higher precision and has smaller discrepancies. However, this higher precision does not necessarily prove that the electronically measured data set is implicitly more accurate than the values of taped or other measurement methods. In fact, the opposite may be true if the reflector constant had been entered incorrectly, which could cause a large systematic error to be present in all of the electronically measured distances.

The calibration was accomplished on standardized permanent calibration bench marks, in which true distances between the pillars are known as published by Malaysia's leading certification, inspection and testing body (SIRIM) and the Survey and Mapping Malaysia Department (JUPEM) as described in Table 3.1 in chapter 3. In this calibration, each distance between the pillars was measured for five times by the Total Station. An example of the measurement data is shown in Appendix I. The materials of target surface can be categorized into two classes, based on colour and natural material. The average of the measured distances was used in the detection of deformation. The preferred approach is a parametric least square adjustment method that simultaneously determines a zero error, a constant value, and scaling factor of the calibration-target and the Total Station (as systematical errors can be computed).

### 4.2.1 Result of Zero Error Estimation

Once the adjustment computation is completed, the global test is then applied to ensure the compatibility of the aposteori and apriori variances. The result of the global test is presented in Table 4.1. The critical value is obtained from Fisher table with $95 \%$ significance level and 14 degrees of freedom whereby the numbers of observations is 21 less 7(unknown parameters). Table 4.1 shows that F-computed is lower than 1.700 which indicates that there is no outliers in the data. The result of the zero error and its precision is given in Table 4.2.

Table 4.1 F-computed for global test

| Prism | Red | White | Black | Concrete | Wood | Homo. Tile |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.592 | 0.089 | 0.189 | 0.127 | 0.450 | 0.381 | 0.145 |

Table 4.2 Zero error and standard deviation for various targets

| Prism |  | Red |  | White |  | Black |  | Concrete |  | Wood |  | Homo. Tile |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{Z}_{\mathrm{o}}$ | $\sigma \mathrm{z}_{\text {o }}$ | $\mathrm{Z}_{\mathrm{o}}$ | $\sigma \mathrm{Z}_{\text {o }}$ | $\mathrm{Z}_{\mathrm{o}}$ | $\sigma \mathrm{z}_{\text {o }}$ | $\mathrm{Z}_{0}$ | $\sigma \mathrm{Z}_{\text {o }}$ | $\mathrm{Z}_{\mathrm{o}}$ | $\sigma \mathrm{Z}_{\text {o }}$ | $\mathrm{Z}_{\mathrm{o}}$ | $\sigma \mathrm{Z}_{\text {o }}$ | $\mathrm{Z}_{\mathrm{o}}$ | $\sigma \mathrm{Z}_{\mathrm{o}}$ |
| millimetres |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 0.09 | 7.1E-4 | 4.20 | 1.9E-3 | 1.85 | 1.7E-3 | 7.05 | 2.2E-3 | 3.14 | 1.2E-3 | 3.14 | 1.1E-3 | 2.85 | 2E-3 |

The results of these measurements were compared with the published distances, as summarized in Figure 4.1 and Figure 4.2. From the measurement results, the difference between measured distance and published distance for pillars less than 10 meters is below 5 mm for all tested materials. Based on the colour shown, the differences between the measured and published distances are also quite small for distances in the range below than 200 meters; however there is a drastic increase for distances in the range above 200 meters. Black coloured targets mostly show larger differences than other colours, due to low reflectivity. For natural materials, the differences between the measured and publishes distances is not constant in all range of distances due to the texture of the surface. But the differences are still within the acceptable tolerance, according to the specification of the instruments used $10 \mathrm{~mm} \pm 10 \mathrm{ppm}$.

The TS is equipped with dual laser optics, which means it has two option beams, one narrow beam for non-prism function and a broader beam for use with prism. The function is to stabilize the beam when measuring over long distances to provide more accuracy in the measurement. The experiments conducted revealed that reflector-less TS measurements are characterized by the range of distance measured. In order to receive a strong reflected signal, small incident angles should be avoided [45]; and in order to get the measurements of highest quality the zero error and the constant value of the various targets must be identified to correct the distance readings.


Figure 4.1 Distance differences based on colours


Figure 4.2 Distance differences based on natural materials

Referring to the result in the Table 4.2, black material target yields the biggest value of zero error ( $7.054 \pm 0.002$ millimeters), while prism target gives the smallest value ( $0.093 \pm 0.001$ millimeters). To check the significance of the zero error value, $t$-student statistical test was carried out in this study. The critical value of $t$-table is 2.145 with $95 \%$ significance level and 14 degrees of freedom. The results of t-test for zero error are tabulated in Table 4.3. The table shows that t -computed for all targets are larger than
2.145, which indicates that the zero error is significant in this baseline measurement. It implies that the error had occurred in the instrument; therefore the appropriate correction value should be applied to each baseline reading that was observed using this instrument.

Table 4.3 T-computed from significant test for zero error correction

| Prism | Red | White | Black | Concrete | Wood | Homo. Tile |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2.299 | 3.358 | 2.301 | 2.805 | 2.491 | 2.620 | 2.629 |

The adjusted baseline between two various benchmarks is given in Table 4.4. It can be seen that the difference of adjusted baseline between various targets is in millimeters scale. The accuracy of the adjusted baseline is inversely proportional to the difference in the distance measurements, with respect to the adjusted baseline of prism reflector. From the results it seems that textured material requires higher adjustments than coloured material, except for black coloured material, which depends on the distance. If the distance is longer the value of the zero errors is larger.

Table 4.4 Adjusted sub baseline for various material targets

| Baseline | Prism | Red | White | Black | Concrete | Wood | H. Tile |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{array}{c}5.003 \mathrm{~m} \\ \pm 0.000 \mathrm{~mm}\end{array}$ | $\begin{array}{c}5.009 \mathrm{~m} \\ \pm 0.408 \mathrm{~mm}\end{array}$ | $\begin{array}{c}5.007 \mathrm{~m} \\ \pm 1.817 \mathrm{~mm}\end{array}$ | $\begin{array}{c}5.013 \mathrm{~m} \\ \pm 0.837 \mathrm{~mm}\end{array}$ | $\begin{array}{c}5.007 \mathrm{~m} \\ \pm 0.894 \mathrm{~mm}\end{array}$ | $\begin{array}{c}5.007 \mathrm{~m} \\ \pm 0.894 \mathrm{~mm}\end{array}$ | $\begin{array}{c}5.009 \mathrm{~m} \\ \pm 0.894 \mathrm{~mm}\end{array}$ |
| P0-P2(m) | 10.001 m | 10.007 m | 10.002 m | 10.008 m | 10.004 m | 10.005 m | 10.004 m |
| $\pm 0.548 \mathrm{~mm}$ | $\pm 2.588 \mathrm{~mm}$ | $\pm 1.517 \mathrm{~mm}$ | $\pm 2.302 \mathrm{~mm}$ | $\pm 2.702 \mathrm{~mm}$ | $\pm 2.702 \mathrm{~mm}$ | $\pm 1.996 \mathrm{~mm}$ |  |$]$

### 4.2.2 TS Calibration Factors for Different Types of Target

Based on the adjusted sub baseline result for all types of target used in this work, and the parametric least-square adjustment formula as mentioned in Equation 3.9 and Equation 3.10, the constant value and scaling factor (symbolized by $a$ and $b$ respectively) are obtained. The computed calibration factors of the constant value (a) and scaling factor
(b) for the TS for each type of target are presented in Table 4.5.

Table 4.5 TS constant value and scaling factor for various types of target

|  | Constant Value |  | Scaling Factor |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\boldsymbol{a}(\mathbf{m m})$ | $\boldsymbol{\sigma} \boldsymbol{a}(\mathbf{m m})$ | $\boldsymbol{b}(\mathbf{p p m})$ | $\boldsymbol{\sigma} \boldsymbol{b}(\mathbf{p p m})$ |
| Prism | 1.031 | 0.009 | 2.040 | 1.721 |
| Red | 2.316 | 0.027 | 7.196 | 2.699 |
| White | 2.311 | 0.009 | 3.891 | 1.335 |
| Black | 0.552 | 0.015 | 14.987 | 2.369 |
| Concrete | 0.616 | 0.008 | 5.978 | 0.822 |
| Wood | 2.751 | 0.013 | 12.130 | 1.383 |
| Homo. Tile | 0.745 | 0.012 | 4.681 | 1.420 |

Referring to the calibration result in Table 4.5, black coloured and wood targets yield the two largest scaling factor ( 14.987 ppm and 12.130 ppm ) than the value specified for the instrument specification ( 10.000 ppm ); while the prism target gives the smallest value ( 1.031 for $a$, and 2.040 ppm for $b$ ) but the scaling factor is still larger than the specification. To check the significance of the calibration result, t -student statistical test was performed in this research. The critical value of $t$-table is still the same as the previous t-test calculation ( 2.145 with $95 \%$ significance level and 14 degrees of freedom). Table 4.6 shows that the t-computed for all targets (except for prism target) are larger than 2.145 accept the value for prism, which is lower than 2.145 . This indicates that no error is present in the distance measurement tool in the TS and its standard prism. The error mainly exists in the reflector target made of various materials. Therefore the appropriate correction factors should be applied to all distance observations made by this instrument.

Table 4.6 T-computed for significant test of TS calibration

|  | Prism | Red | White | Black | Concrete | Wood | Homo. Tile |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $a(\mathrm{~mm})$ | 0.118 | 0.087 | 0.271 | 0.036 | 0.078 | 0.207 | 0.064 |
| $b(p p m)$ | 1.359 | 2.531 | 2.915 | 6.327 | 7.268 | 8.769 | 3.296 |

### 4.3 Datum Verifications

In order to assess the stability and the system coordinate used by MTD, GPS and TS observations were carried out to check the angles and distances of the three marks according to Malaysian standard survey regulation [60]. According to the regulation, the difference in angles and distances between new observations and old values adopted by MTD must not exceed $30^{\prime \prime}$ in angle and $1 / 8000$ in distance for lines exceeding 40 m or $30^{\prime \prime}$ in bearing and 0.006 m per 20 m with a maximum of 0.03 m .

### 4.3.1 Baselines by GPS Observation

Successively to check the existing coordinate system used by MTD, GPS observation was made as presented in Table 4.7. The observation was done using static method. From the GPS coordinates, the bearing distances was computed and compared with the MTD control point data in order to check that the tolerances are within the limits; the results are shown in Table 4.8. The lines have been used as the baselines for this research and they are located outside the deformable body.

Table 4.7 GPS Coordinates

| SUBNET 'Session' POINTS: ADJUSTED COORDINATES <br> in Malaysia_RSO(Grid, Zone Malysia) |  |  |  |
| :--- | :---: | :---: | :---: |
|  | Station No. 43(Base Station) |  |  |  |
|  | Northing (m) | Easting (m) | Height (m) |
|  | 507987.39300 | 372618.16800 | 1310.84300 |
|  | Northing (m) | Easting (m) | Height (m) |
| Coordinates | 507987.39300 | 372618.16800 | 1310.84300 |
|  | S (N) | S (E) | S (U) |
| Sigmas(mm) | 0.0 | 0.0 | 0.0 |
|  | N-E | N-U | E-U |
| Corr.(\%) | 0.0 | 0.0 | 0.0 |
|  | Station No. 44(Unknown Station) |  |  |
| MTD <br> Coordinates | Northing (m) | Easting (m) | Height (m) |
|  | 372720.072 | 507780.809 | 1299.214 |
|  | Northing (m) | Easting (m) | Height (m) |
| Coordinates | 372719.90979 | 507780.82692 | 1299.15213 |
|  | S (N) | S (E) | S (U) |
| Sigmas(mm) | 0.4 | 0.6 | 1.1 |
|  | N-E | N-U | E-U |
| Corr. (\%) |  |  |  |

Table 4.8 Comparison of Coordinates between GPS and MTD

|  | Easting | Northing | Height |
| :---: | :---: | :---: | :---: |
| MTD | 372720.072 | 507780.809 | 1299.214 |
| GPS | 372720.0558 | 507780.8269 | 1299.1521 |
| Different | 0.0162 m | -0.0179 m | 0.0619 m |

From the table above, the difference between GPS and MTD coordinates is only in centimeters (Easting 1.6 cm , Northing 1.7 cm and height 6 cm ). This indicates that the station is still stable and has been using the same coordinate system. The possibility error occurred because of centering when the instruments were set up, and the precision differences between the instruments.

### 4.3.2 Datum Verifications by TS Observations

All three marks of the control station are located adjacent of each other, and to prove that the points is still in good condition, angular and linear measurements must be done; calculation is a normal practice applied by the Survey and Mapping Department (JUPEM).

Table 4.9 Datum Verification between MTD on 12/02/03 and Epoch 1 on 07/02/08

| Line | Difference |  | Remarks |
| :---: | :---: | :---: | :---: |
|  | Bearing | Distance | $\mathbf{1 2 / 0 2 / 0 3}$ |
| and |  |  |  |
| 07/02/08 |  |  |  |$]$

Referring to the result in Table 4.9, the inner angle difference between data obtained from MTD on $12 / 12 / 03$ and TS data observed on $05 / 01 / 08$ is 20 "; this shows that the angle is below the 30 " stipulated in the survey regulation. The ratio distances are 1:76784 for line 44-43 and 1:57755 for line 44-45. The results show that the ratio is better than 1:8000 as described by the survey regulation. The bearing and distance measurements at epoch 1 obtained by a former survey and epoch 2 captured by the same TS are tabulated in Table 4.10. From the result, the angular and the distance ratios are still in good conditions based on the satisfactory of datum specified by the survey regulation.

Table 4.10 Datum Verification between Epoch 1on 07/02/08 and Epoch 2 on

| 07/07/08 |  |  |  |
| :---: | :---: | :---: | :---: |
| Line | Difference |  | Remarks |
|  | Bearing | Distance | 07/02/08 |
| 44-43 | 0 " | +0.008 | and |
| 44-45 | -15" | -0.013 | 07/07/08 |
| Angle Difference | -15" |  |  |
| Verified Distance <br> Note; <br> $1 / \mathrm{x}=$ Linear Measurements | Line 44-43 $0.006 \times 11=0.066 \mathrm{~m}$ or $1 / \mathrm{x} 0.008 / 230.348=1: 28794$ Line 44-45 $0.006 \times 5=0.06 \mathrm{~m}$ or $1 / \mathrm{x} 0.013 / 115.512=1: 8886$ |  |  |

Table 4.11 Datum Verification between Epoch 2 on 07/07/08 and Epoch 3 on

| 7/12/08 |  |  |  |
| :---: | :---: | :---: | :---: |
| Line | Difference |  | Remarks |
|  | Bearing | Distance | 07/07/08 and 07/12/08 |
| 44-43 | 0 " | +0.005 |  |
| 44-45 | -15" | -0.014 |  |
| Angle Difference | -15" |  |  |
| Verified Distance <br> Note; <br> $1 / \mathrm{x}=$ Linear Measurements | Line $44-43 \quad 0.006 \times 11=0.066 \mathrm{~m}$ or $1 / \mathrm{x} 0.005 / 230.340=1: 46068$ Line $44-45 \quad 0.006 \times 5=0.06 \mathrm{~m}$ or $1 / \mathrm{x} 0.014 / 115.525=1: 8252$ |  |  |

Before carrying out the deformation monitoring observation, it is important to ensure that the control station has remained stable. From the calculation, the result show that the angular measurement is better than $30^{\prime \prime}$ and the linear measurement is better than $1: 8000$ for distance. Thus it can be concluded that all the control stations established by MTD are still in good condition and suitable to be used as reference stations.

### 4.4 Error Propagation

In this study, propagation of errors was analyzed to see the influence on the observed data when integrated with angles, distance and elevations. An amount of adjustments need to be applied to the observation data in order to obtain the best fit. This is the residual that is being minimized. If there are large residuals in the calculations, then it may indicate a blunder in the observation data.

### 4.4.1 Error Sources in Horizontal Angles

The inner angle value is calculated based on the reference object and the monitoring target points, an example of the measurement data is presented on Appendix 11. The error sources in the horizontal angle measurements for the TS in this research is the sum of errors of the target and instrument centering errors, and the standard deviation value
based on DIN 18723 of the instrument specification for reading and pointing errors. From the computation, there is not much difference in the error for every epoch. This is because the angles and the distance do not change so much, the calculation data is presented on Appendix K. Based on the graph in Figure 4.3, below the average angle the error source is very small and the values are almost the same. From the calculations all the monitoring points have 03 " of errors in horizontal angle measurements, the results are shown on Appendix K. It can be concluded that the horizontal angles contain larger errors if sights are shorter (setup error) as shown in Figure 4.4, and also contain a constant error related closely to the least count of the instrument. It is also found that the errors are also influenced by the target size. The finer the sight of the target points, then the lesser potential angular error in the sight.


Figure 4.3 Mean of angle effect on standard deviation of angles sources errors


Figure 4.4 Mean of angle and distance effect of sum of angles sources errors

### 4.4.2 Errors Sources in Electronic Distance Observations

The error propagation in distance was determined during the calibration work. The zero constant value and scaling factor of each type of targets were calculated during the calibration. In this research, the monitoring target was a prism pole which has been permanently planted at the slope by the MTD survey team, for monitoring purpose. Therefore the correction in the observed distance observation depends on the colour of the aimed target, which is the prism pole; the pole is in white and red stripes. Based on the graph shown in Figure 4.4, it is observed that the standard deviation is directly proportional to the measured distance, the longer the distance measured, the larger the standard deviation. This means that the zero and scale error are linearly proportional to the length of the measured line. The calculated data are presented on Appendix L.


Figure 4.5 Standard Deviation against the Measured Distance

### 4.4.3 Error Sources in Trigonometric Leveling

In the determination of leveling by trigonometric method, there are some factors which can influence the results. This includes the accuracy of the instrument mainly the measuring accuracy of slope distance and vertical angles, and external factors such as earth curvature and refraction. The results show small differences in the values of standard deviation of elevation of each epoch because there is minimal difference in slope distances on each monitoring target points. The results are tabulated in Table 4.12 below.

Table 4.12 Standard deviation of elevation

| Target No. | Epoch1 |  | Epoch2 |  | Epoch3 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Elevation(m) | OLFA 02 | Elevation(m) | OLh(n) | Elevation(m) | G4Fin) |
| P1 | 1373.64226 | 0.0097079 | 1373.64051 | 0.0097079 | 1373.64176 | 0.0097078 |
| P2 | 1424.86011 | 0.0111189 | 1424.86061 | 0.0111189 | 1424.86161 | 0.0111190 |
| P3 | 1474.29992 | 0.0139317 | 1474.29617 | 0.0139319 | 1474.29892 | 0.0139317 |
| P4 | 1546.44583 | 0.0194719 | 1546.44433 | 0.0194719 | 1546.44758 | 0.0194719 |
| P5 | 1484.95358 | 0.0155681 | 1484.95183 | 0.0155682 | 1484.95783 | 0.0155684 |
| P6 | 1439.82369 | 0.0123251 | 1439.82294 | 0.0123251 | 1439.82044 | 0.0123251 |
| P7 | 1388.46845 | 0.0086678 | 1388.46470 | 0.0086679 | 1388.46870 | 0.0086680 |
| P8 | 1389.26734 | 0.0098484 | 1389.26834 | 0.0098485 | 1389.27084 | 0.0098487 |
| P9 | 1435.79221 | 0.0130234 | 1435.79496 | 0.0130234 | 1435.80071 | 0.0130235 |
| P10 | 1485.51989 | 0.0159056 | 1485.52214 | 0.0159056 | 1485.53089 | 0.0159060 |
| P11 | 1451.86924 | 0.0158965 | 1451.86999 | 0.0158964 | 1451.87514 | 0.0158967 |
| P12 | 1439.01837 | 0.0203134 | 1439.10627 | 0.0203120 | 1439.12782 | 0.0203118 |
| P13 | 1364.43646 | 0.0081755 | 1364.43621 | 0.0081756 | 1364.43621 | 0.0081759 |
| P14 | 1343.97245 | 0.0070381 | 1343.97095 | 0.0070381 | 1343.97295 | 0.0070382 |
| P15 | 1458.09244 | 0.0286898 | 1458.17598 | 0.0286883 | 1458.16009 | 0.0286887 |
| P16 | 1415.11050 | 0.0288447 | 1415.26130 | 0.0288434 | 1415.15035 | 0.0288444 |
| P17 | 1414.74927 | 0.0274831 | 1414.73156 | 0.0274830 | 1414.75011 | 0.0274829 |
| P18 | 1416.60317 | 0.0251341 | 1416.60083 | 0.0251340 | 1416.67149 | 0.0251333 |
| P19 | 1384.97678 | 0.0200325 | 1385.00245 | 0.0200323 | 1385.02200 | 0.0200320 |
| P20 | 1372.84092 | 0.0264677 | 1372.84568 | 0.0264677 | 1372.85176 | 0.0264675 |

### 4.4.4 Estimated Error in Latitude and Departure

The estimated errors in latitude and departure depend on the value of estimated errors in distance and angle from observation data which have been computed previously. This is due to the correlation between latitude and departure against the distance or azimuth of the observation. This estimated error is very useful in order to estimate the monitoring point coordinates.

### 4.5 Magnitude of Movements

The first stage of data analysis is concerning the coordinates of each epoch. The coordinates are shown in the Table 4.16 below, and Figures 4.5, 4.6 and 4.7 shows the precision of latitude, departure and height, respectively. These figures indicate there are a slight difference in the standard deviation among the first, second and third epochs. Figure 4.6 shows that of the three epochs have more or less the same value of precision in latitude, departure and height. The largest value in latitude is at target point P7 whereby the smallest value is at target point P20. Target point P16 has the largest value in departure and P14 has the smallest value. Whereas, target point P16 has the largest value in height and P13 has the smallest value.

Table 4.16 The N, E and H Coordinate in meters of the 20 Monitoring Targets object

| Target No. | Epoch 1 |  |  | Epoch 2 |  |  | Epoch 3 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | North(m) | East(m) | Height(m) | North(m) | East(m) | Height(m) | North(m) | East(m) | Height(m) |
| P1 | 508015.065 | 372467.503 | 1373.642 | 508015.065 | 372467.502 | 1373.641 | 508015.064 | 372467.504 | 1373.642 |
| P2 | 507950.006 | 372466.300 | 1424.860 | 507950.007 | 372466.300 | 1424.861 | 507950.007 | 372466.300 | 1424.862 |
| P3 | 507893.237 | 372457.161 | 1474.300 | 507893.237 | 372457.154 | 1474.296 | 507893.237 | 372457.160 | 1474.299 |
| P4 | 507805.468 | 372436.332 | 1546.446 | 507805.467 | 372436.332 | 1546.444 | 507805.469 | 372436.333 | 1546.448 |
| P5 | 507836.866 | 372468.587 | 1484.954 | 507836.864 | 372468.587 | 1484.952 | 507836.865 | 372468.584 | 1484.958 |
| P6 | 507870.719 | 372491.613 | 1439.824 | 507870.719 | 372491.612 | 1439.823 | 507870.718 | 372491.613 | 1439.820 |
| P7 | 507905.430 | 372520.980 | 1388.468 | 507905.427 | 372520.978 | 1388.465 | 507905.427 | 372520.978 | 1388.469 |
| P8 | 507849.418 | 372562.532 | 1389.267 | 507849.418 | 372562.531 | 1389.268 | 507849.418 | 372562.531 | 1389.271 |
| P9 | 507832.254 | 372513.834 | 1435.792 | 507832.255 | 372513.835 | 1435.795 | 507832.255 | 372513.835 | 1435.801 |
| P10 | 507814.634 | 372484.809 | 1485.520 | 507814.634 | 372484.811 | 1485.522 | 507814.634 | 372484.806 | 1485.531 |
| P11 | 507769.743 | 372534.317 | 1451.869 | 507769.743 | 372534.317 | 1451.870 | 507769.743 | 372534.312 | 1451.875 |
| P12 | 507670.243 | 372566.671 | 1439.018 | 507670.308 | 372566.680 | 1439.106 | 507670.318 | 372566.698 | 1439.128 |
| P13 | 507858.949 | 372608.785 | 1364.436 | 507858.947 | 372608.785 | 1364.436 | 507858.943 | 372608.785 | 1364.436 |
| P14 | 507870.615 | 372615.636 | 1343.972 | 507870.614 | 372615.636 | 1343.971 | 507870.614 | 372615.636 | 1343.973 |
| P15 | 507523.906 | 372548.249 | 1458.092 | 507523.971 | 372548.249 | 1458.176 | 507523.951 | 372548.293 | 1458.160 |
| P16 | 507496.875 | 372598.204 | 1415.111 | 507496.964 | 372598.273 | 1415.261 | 507496.894 | 372598.287 | 1415.150 |
| P17 | 507522.352 | 372592.793 | 1414.749 | 507522.346 | 372592.797 | 1414.732 | 507522.355 | 372592.818 | 1414.750 |
| P18 | 507567.867 | 372581.144 | 1416.603 | 507567.866 | 372581.147 | 1416.601 | 507567.912 | 372581.156 | 1416.671 |
| P19 | 507647.523 | 372636.456 | 1384.977 | 507647.540 | 372636.475 | 1385.002 | 507647.555 | 372636.465 | 1385.022 |
| P20 | 507522.557 | 372645.445 | 1372.841 | 507522.561 | 372645.467 | 1372.846 | 507522.569 | 372645.486 | 1372.852 |



Figure 4.6 Standard Deviation of Latitude


Figure 4.7 Standard Deviation of Departure


Figure 4.8 Standard Deviation of Height

### 4.6 Displacement Test

As can be seen in Figures 4.8, 4.9 and 4.10, there are coordinate differences in the north, east and height components between each pair of epoch. The magnitude of coordinate difference in general is within a few centimeters. There is a minor variation in the number of $\mathrm{N}, \mathrm{E}$ and U coordinates of each monitoring points as shown in Figures 4.8, 4.9 and 4.10. From those figures, the target points P12, P15, P16, P17, P18, P19 and P20 are identified as slightly active points. Figure 4.11 shows the graphic of the direction of the azimuth within the scale; because the magnitude is too small only target points P12, P15, P16, P17, P18, P19 and P20 can be seen.


Figure 4.9 Coordinate differences in North Components


Figure 4.10 Coordinate differences in East Components


Figure 4.11 Coordinate differences in Height Components


Figure 4.12 The direction is azimuth angle of monitoring target points
However the detection of mass movement cannot be carried out by pushing directly the coordinate values only. Instead, a statistical method is used to determine at which point soil movement or subsidence has occurred. Tables 4.14, 4.15 and 4.16 tabulate the results of t-test of displacement between epochs 1 and 2 , epochs 2 and 3, and between epochs 1 and 3, respectively. From these tables, it can be seen that the T values at P12 and P15 between epochs 1,2, at P16 between epochs 2,3 and at P12 and P16 between epochs 1,3 are larger than 1.960 . This indicates that there have been significant displacements at the particular target monitoring points. Thus, it could be declared statistically with $95 \%$ confidence level that deformation has occurred at CH 23+800, 35 km section of the Simpang Pulai - Lojing Highway project as observed at the three epochs. As shown in Table 4.17 between epoch 1 and epoch 2, there are two target points P12 and P15, which has displacement deformation in the horizontal component.

Table 4.14 Horizontal and elevation displacements, and T-computed Between Epoch 1 and Epoch 2

| Station | Epoch1-Epoch2(T-Test) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Horiz.Deform $(\mathrm{m})$ | $\mathrm{d} / \sigma$ od | Elev.Deform $(\mathrm{m})$ | $\mathrm{h} / \sigma \mathrm{H}$ |
| P1 | 0.004 | 0.347 | 0.014 | 0.127 |
| P2 | 0.003 | 0.150 | 0.016 | 0.032 |
| P3 | 0.009 | 0.745 | 0.020 | 0.190 |
| P4 | 0.004 | 0.248 | 0.028 | 0.054 |
| P5 | 0.005 | 0.327 | 0.022 | 0.079 |
| P6 | 0.003 | 0.121 | 0.017 | 0.043 |
| P7 | 0.009 | 0.148 | 0.012 | 0.306 |
| P8 | 0.004 | 0.255 | 0.014 | 0.072 |
| P9 | 0.005 | 0.147 | 0.018 | 0.149 |
| P10 | 0.004 | 0.360 | 0.022 | 0.100 |
| P11 | 0.003 | 0.186 | 0.022 | 0.033 |
| P12 | 0.029 | 2.257 | 0.029 | 3.060 |
| P13 | 0.006 | 0.297 | 0.012 | 0.022 |
| P14 | 0.003 | 0.206 | 0.010 | 0.151 |
| P15 | 0.028 | 2.316 | 0.041 | 2.059 |
| P16 | 0.058 | 0.950 | 0.041 | 3.697 |
| P17 | 0.011 | 0.451 | 0.039 | 0.456 |
| P18 | 0.007 | 0.296 | 0.036 | 0.066 |


| P19 | 0.030 | 0.323 | 0.028 | 0.906 |
| :--- | :--- | :--- | :--- | :--- |
| P20 | 0.020 | 1.091 | 0.037 | 0.127 |

Table 4.15 Horizontal and elevation displacements, and T-computed Between Epoch 2 and Epoch 3

|  | Epoch2-Epoch3(T-Test) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Station | Horiz.Deform $(\mathrm{m})$ | $\mathrm{d} / \sigma \mathrm{d}$ | Elev.Deform $(\mathrm{m})$ | $\mathrm{h} / \sigma \mathrm{H}$ |
| P1 | 0.005 | 0.392 | 0.014 | 0.091 |
| P2 | 0.002 | 0.192 | 0.016 | 0.064 |
| P3 | 0.008 | 0.677 | 0.020 | 0.140 |
| P4 | 0.009 | 0.074 | 0.028 | 0.118 |
| P5 | 0.006 | 0.495 | 0.022 | 0.273 |
| P6 | 0.005 | 0.217 | 0.017 | 0.143 |
| P7 | 0.000 | 0.000 | 0.012 | 0.326 |
| P8 | 0.000 | 0.000 | 0.014 | 0.180 |
| P9 | 0.000 | 0.000 | 0.018 | 0.312 |
| P10 | 0.008 | 0.607 | 0.022 | 0.389 |
| P11 | 0.008 | 0.651 | 0.022 | 0.229 |
| P12 | 0.020 | 0.769 | 0.029 | 0.750 |
| P13 | 0.008 | 0.524 | 0.012 | 0.000 |
| P14 | 0.001 | 0.127 | 0.010 | 0.201 |
| P15 | 0.031 | 1.236 | 0.041 | 0.392 |
| P16 | 0.030 | 2.268 | 0.041 | 2.720 |
| P17 | 0.021 | 0.913 | 0.039 | 0.477 |
| P18 | 0.024 | 1.830 | 0.036 | 1.988 |
| P19 | 0.019 | 0.607 | 0.028 | 0.690 |
| P20 | 0.020 | 0.893 | 0.037 | 0.162 |

In between epoch 2 and epoch 3, only target point P16 has been identified as having both horizontal and vertical components deformation. Other target points were indentified without any significant movement.

Table 4.16 Horizontal and elevation displacements, and T-computed Between Epoch 1 and Epoch 3

|  | Epoch1-Epoch3(T-Test) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Station | Horiz.Deform(m) | $\mathrm{d} / \sigma \mathrm{d}$ | Elev.Deform $(\mathrm{m})$ | $\mathrm{h} / \sigma \mathrm{H}$ |
| P1 | 0.004 | 0.159 | 0.014 | 0.036 |
| P2 | 0.003 | 0.180 | 0.016 | 0.095 |
| P3 | 0.004 | 0.257 | 0.020 | 0.051 |
| P4 | 0.004 | 0.233 | 0.028 | 0.064 |
| P5 | 0.007 | 0.444 | 0.022 | 0.193 |
| P6 | 0.005 | 0.322 | 0.017 | 0.186 |
| P7 | 0.009 | 0.148 | 0.012 | 0.020 |
| P8 | 0.004 | 0.255 | 0.014 | 0.251 |
| P9 | 0.005 | 0.147 | 0.018 | 0.462 |
| P10 | 0.006 | 0.461 | 0.022 | 0.489 |
| P11 | 0.008 | 0.631 | 0.022 | 0.263 |
| P12 | 0.034 | 2.098 | 0.029 | 3.810 |
| P13 | 0.010 | 0.648 | 0.012 | 0.022 |
| P14 | 0.003 | 0.187 | 0.010 | 0.050 |
| P15 | 0.082 | 0.104 | 0.041 | 1.667 |
| P16 | 0.040 | 2.045 | 0.041 | 0.977 |
| P17 | 0.020 | 1.175 | 0.039 | 0.022 |
| P18 | 0.025 | 1.749 | 0.036 | 1.922 |
| P19 | 0.021 | 1.418 | 0.028 | 1.596 |
| P20 | 0.028 | 1.420 | 0.037 | 0.290 |

Within the 18 months observation period, significant movements have been identified at target points P12 and P16 between epoch 1 and epoch 3. Target point P12 shows that the displacement has occurred in both horizontal and vertical components, whereby at the target point P16 the displacement has occurred in the horizontal component only.

### 4.7 T-Test with Standard Prism

In order to check the significant quality of the deformation monitoring, $t$-student statistical test was carried out. This is done by comparing the difference of the magnitude coordinates deformation monitoring by reflector-less TS and standard prism TS. The standard prism data was provided by MTD and JKR Perak, which was captured by using Sokkia SRX TS with accuracy of $2 \mathrm{~mm} \pm 2 \mathrm{ppm}$.

The critical value of $t$-table is 2.086 with $95 \%$ significance level and 20 degrees of freedom. The results of $t$-test for the comparison between two methods are tabulated in Table 4.17, 4.18 and 4.19. The table shows that the t -computed for all targets points were lower than 2.086, which indicates that the difference between prism modes and reflectorless is not significant or acceptable.

Table 4.17 T-computed and coordinates difference between standard prism TS and reflector-less TS for Epoch 1 and Epoch 2

| Station | Epoch 1 and Epoch 2(T-Test) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\Delta$ Northing(m) | $T_{y}$ | $\Delta$ Easting(m) | $T_{z}$ | $\Delta$ Elevation(m) | $T_{z}$ |
| P1 | 0.001 | 0.007 | 0.005 | 0.014 | 0.002 | 0.019 |
| P2 | 0.000 | 0.003 | 0.006 | 0.018 | 0.002 | 0.012 |
| P3 | 0.003 | 0.020 | 0.002 | 0.007 | 0.001 | 0.005 |
| P4 | 0.000 | 0.000 | 0.003 | 0.008 | 0.002 | 0.009 |
| P5 | 0.002 | 0.020 | 0.005 | 0.015 | 0.002 | 0.015 |
| P6 | 0.002 | 0.014 | 0.007 | 0.020 | 0.001 | 0.006 |
| P7 | 0.000 | 0.002 | 0.001 | 0.004 | 0.002 | 0.016 |
| P8 | 0.005 | 0.039 | 0.007 | 0.021 | 0.004 | 0.034 |
| P9 | 0.001 | 0.008 | 0.001 | 0.004 | 0.010 | 0.076 |
| P10 | 0.005 | 0.042 | 0.002 | 0.007 | 0.004 | 0.392 |
| P11 | 0.000 | 0.004 | 0.002 | 0.006 | 0.037 | 0.248 |
| P12 | 0.004 | 0.032 | 0.004 | 0.011 | 0.001 | 0.007 |
| P13 | 0.003 | 0.025 | 0.003 | 0.010 | 0.000 | 0.002 |
| P14 | 0.003 | 0.027 | 0.010 | 0.031 | 0.007 | 0.065 |
| P15 | 0.002 | 0.019 | 0.006 | 0.018 | 0.008 | 0.037 |
| P16 | 0.025 | 0.590 | 0.009 | 0.025 | 0.005 | 0.026 |


| P17 | 0.002 | 0.018 | 0.002 | 0.006 | 0.001 | 0.007 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| P18 | 0.028 | 0.255 | 0.047 | 0.132 | 0.031 | 0.163 |
| P19 | 0.005 | 0.049 | 0.003 | 0.008 | 0.001 | 0.004 |
| P20 | 0.002 | 0.021 | 0.007 | 0.019 | 0.001 | 0.004 |

Table 4.18 T-computed and coordinates difference between standard prism TS and reflector-less TS for Epoch 2 and Epoch 3

| Station | Epoch 2 and Epoch 3(T-Test) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\Delta$ Northing $(\mathrm{m})$ | $T_{y}$ | $\Delta$ Easting $(\mathrm{m})$ | $T_{y}$ | $\Delta$ Elevation(m) | $T_{z}$ |
| P1 | 0.000 | 0.004 | 0.001 | 0.003 | 0.000 | 0.002 |
| P2 | 0.002 | 0.015 | 0.004 | 0.011 | 0.001 | 0.008 |
| P3 | 0.004 | 0.032 | 0.004 | 0.011 | 0.002 | 0.016 |
| P4 | 0.002 | 0.013 | 0.011 | 0.032 | 0.003 | 0.020 |
| P5 | 0.002 | 0.020 | 0.009 | 0.026 | 0.002 | 0.013 |
| P6 | 0.000 | 0.003 | 0.004 | 0.013 | 0.000 | 0.004 |
| P7 | 0.005 | 0.039 | 0.005 | 0.015 | 0.003 | 0.027 |
| P8 | 0.011 | 0.091 | 0.002 | 0.006 | 0.002 | 0.013 |
| P9 | 0.011 | 0.093 | 0.009 | 0.027 | 0.000 | 0.002 |
| P10 | 0.005 | 0.046 | 0.020 | 0.061 | 0.004 | 0.888 |
| P11 | 0.002 | 0.017 | 0.010 | 0.029 | 0.025 | 0.166 |
| P12 | 0.005 | 0.047 | 0.019 | 0.055 | 0.008 | 0.050 |
| P13 | 0.011 | 0.086 | 0.004 | 0.013 | 0.001 | 0.009 |
| P14 | 0.002 | 0.016 | 0.007 | 0.021 | 0.003 | 0.030 |
| P15 | 0.014 | 0.124 | 0.017 | 0.047 | 0.000 | 0.001 |
| P16 | 0.005 | 0.042 | 0.002 | 0.005 | 0.025 | 0.015 |
| P17 | 0.006 | 0.058 | 0.003 | 0.008 | 0.007 | 0.033 |
| P18 | 0.001 | 0.012 | 0.015 | 0.042 | 0.008 | 0.044 |
| P19 | 0.003 | 0.025 | 0.004 | 0.010 | 0.010 | 0.057 |
| P20 | 0.006 | 0.056 | 0.008 | 0.022 | 0.000 | 0.000 |

Table 4.19 T-computed and coordinates difference between standard prism TS and reflector-less TS for Epoch 1 and Epoch 3

| Station | Epoch 1 and Epoch 3(T-Test) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\Delta$ Northing(m) | $T_{y}$ | $\Delta$ Easting(m) | $T^{\prime}$ | $\Delta$ Elevation(m) | $T_{i}$ |
| P1 | 0.002 | 0.013 | 0.008 | 0.025 | 0.002 | 0.021 |
| P2 | 0.002 | 0.019 | 0.010 | 0.030 | 0.000 | 0.004 |
| P3 | 0.000 | 0.004 | -0.001 | 0.004 | 0.001 | 0.007 |
| P4 | 0.004 | 0.031 | 0.008 | 0.024 | 0.001 | 0.008 |
| P5 | 0.006 | 0.051 | 0.014 | 0.042 | 0.008 | 0.052 |
| P6 | 0.001 | 0.012 | 0.012 | 0.036 | 0.000 | 0.002 |
| P7 | 0.005 | 0.037 | 0.000 | 0.001 | 0.001 | 0.007 |
| P8 | 0.016 | 0.129 | 0.009 | 0.028 | 0.000 | 0.004 |
| P9 | 0.012 | 0.101 | 0.010 | 0.031 | 0.010 | 0.077 |
| P10 | 0.010 | 0.088 | 0.026 | 0.078 | 0.008 | 0.053 |
| P11 | 0.002 | 0.021 | 0.012 | 0.036 | 0.002 | 0.014 |
| P12 | 0.012 | 0.105 | 0.015 | 0.044 | 0.010 | 0.056 |
| P13 | 0.014 | 0.111 | 0.001 | 0.003 | 0.001 | 0.007 |
| P14 | 0.005 | 0.042 | 0.017 | 0.052 | 0.002 | 0.025 |
| P15 | 0.026 | 0.233 | 0.010 | 0.026 | 0.024 | 0.121 |
| P16 | 0.001 | 0.999 | 0.007 | 0.020 | 0.030 | 0.149 |
| P17 | 0.008 | 0.069 | 0.007 | 0.020 | 0.030 | 0.153 |
| P18 | 0.029 | 0.268 | 0.014 | 0.038 | 0.022 | 0.118 |
| P19 | 0.003 | 0.024 | 0.025 | 0.073 | 0.010 | 0.061 |
| P20 | 0.011 | 0.096 | 0.001 | 0.003 | 0.009 | 0.046 |

From the table 4.17, 4.18 and 4.19, the differences of the magnitude in all coordinates components between the two methods are not much different. It implies that the reflectorless TS method can be applied to slope deformation monitoring.

