



UNIVERSITI
TEKNOLOGI
PETRONAS

FINAL EXAMINATION JANUARY 2025 SEMESTER

COURSE : MEB1043/MFB1043 - STATICS
DATE : 12 APRIL 2025 (SATURDAY)
TIME : 9.00 AM - 12.00 NOON (3 HOURS)

INSTRUCTIONS TO CANDIDATES

1. Answer **ALL** questions in the Answer Booklet.
2. Begin **EACH** answer on a new page in the Answer Booklet.
3. Indicate clearly answers that are cancelled, if any.
4. Where applicable, show clearly steps taken in arriving at the solutions and indicate **ALL** assumptions, if any.
5. **DO NOT** open this Question Booklet until instructed.

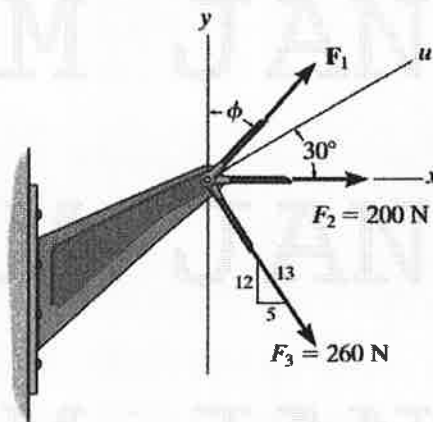
Note :

- i. There are **EIGHT (8)** pages in this Question Booklet including the cover page and appendix.
- ii. **DOUBLE-SIDED** Question Booklet.

1. a. Statics deals with the equilibrium of bodies that are either at rest or move with a constant velocity. Discuss the general procedure in analyzing problems related to statics.

[5 marks]

- b. **FIGURE Q1** shows a free body diagram of bracket to hold the load of F_1 and F_3 , respectively. If the F_1 and ϕ is given 150 N and 30° , respectively.

**FIGURE Q1**

- i. Determine the magnitude of the resultant force acting on the bucket and its direction measured clockwise from the positive x axis.

[13 marks]

- ii. From the finding **Part (i)**, develop the force diagram to shows the forces involved and the magnitude of the resultant force.

[7 marks]

2. a. Discuss the procedure on how to develop the free body diagram of the particle.

[5 marks]

- b. **FIGURE Q2** shows a tow truck model with struts AB , AC and AD mounted on the frame.

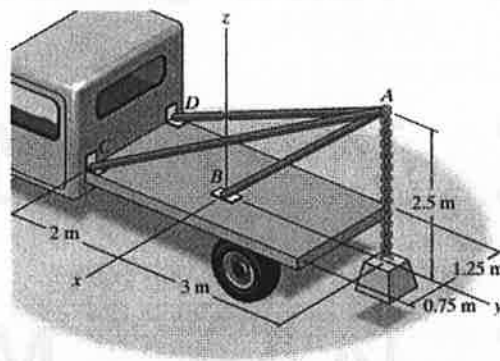


FIGURE Q2

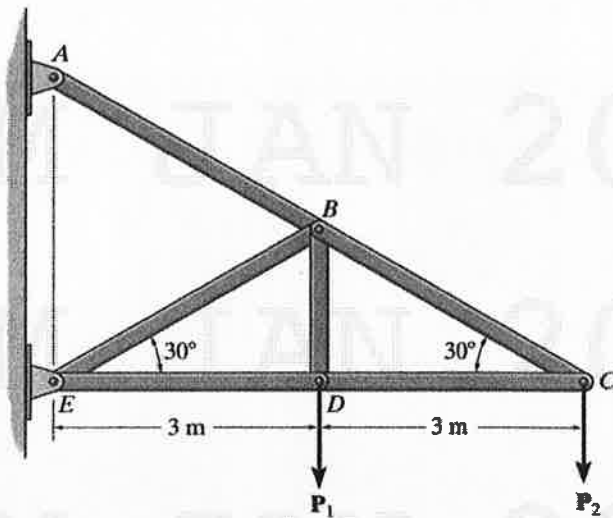
- i. Determine the force acting along the struts for them to support the 500 kg load.

[13 marks]

- ii. Develop a force diagram to show the forces acting along the truss by stating the magnitude and direction.

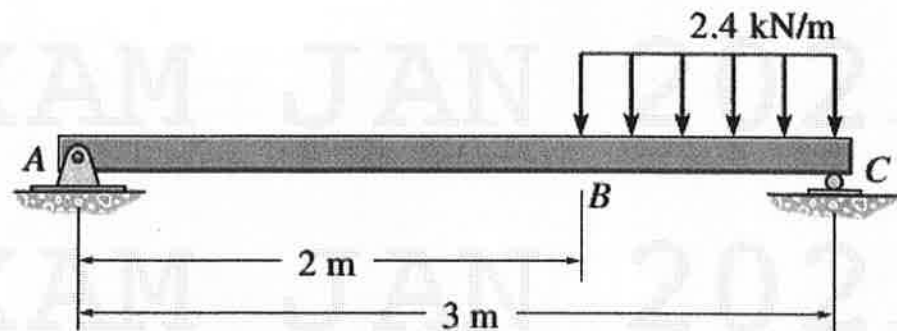
[7 marks]

3. The structural members shown in **FIGURE Q3** is subjected to force $P_1 = 6 \text{ kN}$ and $P_2 = 4.5 \text{ kN}$ at point D and point C , respectively.

**FIGURE Q3**

- a. Determine the forces in each truss member and state if the member is in tension or compression. [18 marks]
- b. Draw all the forces acting at joint E and determine the vertical force at point E . Then draw the free body diagram of the structure. [7 marks]

4. For the beam shown in **FIGURE Q4**, BC is subjected to a uniformly distributed load of 2.4 kN/m :

**FIGURE Q4**

- a. Draw the free body diagram of the structure and calculate the support reactions at point A and point C .

[10 marks]

- b. Develop the shear force diagram & bending moment diagram for the beam.

[15 marks]

- END OF PAPER -

APPENDIX

Cartesian Vector

$$\mathbf{A} = A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}$$

Magnitude

$$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

Directions

$$\begin{aligned} \mathbf{u}_A &= \frac{\mathbf{A}}{A} = \frac{A_x}{A} \mathbf{i} + \frac{A_y}{A} \mathbf{j} + \frac{A_z}{A} \mathbf{k} \\ &= \cos \alpha \mathbf{i} + \cos \beta \mathbf{j} + \cos \gamma \mathbf{k} \\ \cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma &= 1 \end{aligned}$$

Dot Product

$$\begin{aligned} \mathbf{A} \cdot \mathbf{B} &= AB \cos \theta \\ &= A_x B_x + A_y B_y + A_z B_z \end{aligned}$$

Cross Product

$$\mathbf{C} = \mathbf{A} \times \mathbf{B} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Cartesian Position Vector

$$\mathbf{r} = (x_2 - x_1) \mathbf{i} + (y_2 - y_1) \mathbf{j} + (z_2 - z_1) \mathbf{k}$$

Cartesian Force Vector

$$\mathbf{F} = F \mathbf{u} = F \left(\frac{\mathbf{r}}{r} \right)$$

Moment of a Force

$$\begin{aligned} M_o &= Fd \\ \mathbf{M}_o &= \mathbf{r} \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix} \end{aligned}$$

Moment of a Force About a Specified Axis

$$M_u = \mathbf{u} \cdot \mathbf{r} \times \mathbf{F} = \begin{vmatrix} u_x & u_y & u_z \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

Simplification of a Force and Couple System

$$\begin{aligned} \mathbf{F}_R &= \Sigma \mathbf{F} \\ (\mathbf{M}_R)_O &= \Sigma \mathbf{M} + \Sigma \mathbf{M}_O \end{aligned}$$

Equilibrium

Particle

$$\Sigma F_x = 0, \Sigma F_y = 0, \Sigma F_z = 0$$

Rigid Body-Two Dimensions

$$\Sigma F_x = 0, \Sigma F_y = 0, \Sigma M_O = 0$$

Rigid Body-Three Dimensions

$$\begin{aligned} \Sigma F_x &= 0, \Sigma F_y = 0, \Sigma F_z = 0 \\ \Sigma M_x &= 0, \Sigma M_y = 0, \Sigma M_z = 0 \end{aligned}$$

Friction

$$\text{Static (maximum)} \quad F_s = \mu_s N$$

$$\text{Kinetic} \quad F_k = \mu_k N$$

Center of Gravity

Particles or Discrete Parts

$$\bar{\mathbf{r}} = \frac{\Sigma \bar{\mathbf{r}} W}{\Sigma W}$$

Body

$$\bar{\mathbf{r}} = \frac{\int \bar{\mathbf{r}} dW}{\int dW}$$

Area and Mass Moments of Inertia

$$I = \int r^2 dA \quad I = \int r^2 dm$$

Parallel-Axis Theorem

$$I = \bar{I} + Ad^2 \quad I = \bar{I} + md^2$$

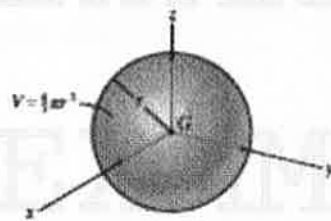
Radius of Gyration

$$k = \sqrt{\frac{I}{A}} \quad k = \sqrt{\frac{I}{m}}$$

Virtual Work

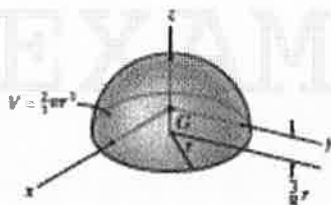
$$\delta U = 0$$

Center of Gravity and Mass Moment Inertia of Homogeneous Solids



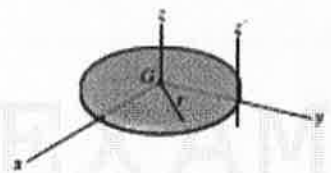
Sphere

$$I_{xx} = I_{yy} = I_{zz} = \frac{2}{5} m r^2$$



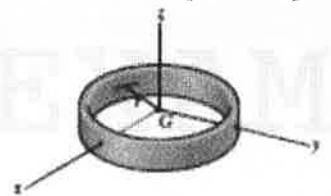
Hemisphere

$$I_{xx} = I_{yy} = 0.259 m r^2 \quad I_{zz} = \frac{1}{5} m r^2$$



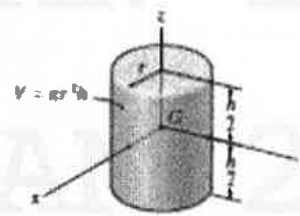
Thin Circular disk

$$I_{xx} = I_{yy} = \frac{1}{4} m r^2 \quad I_{zz} = \frac{1}{2} m r^2 \quad I_{zz'} = \frac{3}{2} m r^2$$



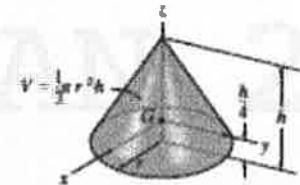
Thin ring

$$I_{xx} = I_{yy} = \frac{1}{2} m r^2 \quad I_{zz} = m r^2$$



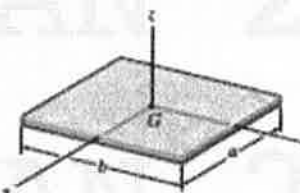
Cylinder

$$I_{xx} = I_{yy} = \frac{1}{12} m (3r^2 + h^2) \quad I_{zz} = \frac{1}{2} m r^2$$



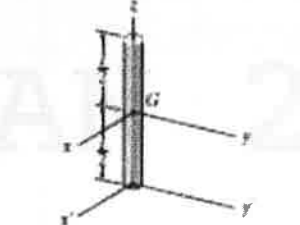
Cone

$$I_{xx} = I_{yy} = \frac{3}{80} m (4r^2 + h^2) \quad I_{zz} = \frac{3}{80} m r^2$$



Thin plate

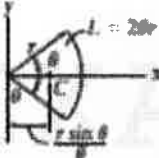
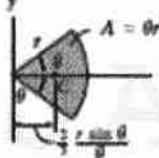
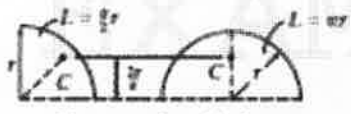
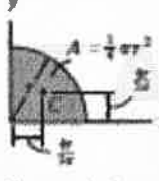
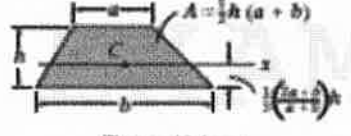
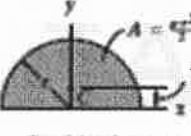
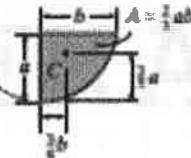
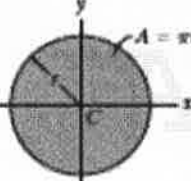
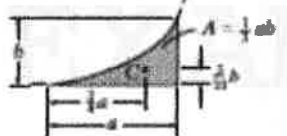
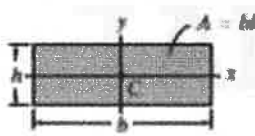
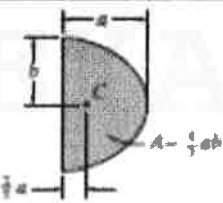
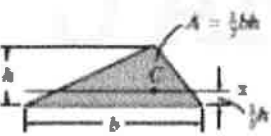
$$I_{xx} = \frac{1}{12} m b^2 \quad I_{yy} = \frac{1}{12} m a^2 \quad I_{zz} = \frac{1}{12} m (a^2 + b^2)$$



Slender Rod

$$I_{xx} = I_{yy} = \frac{1}{12} m L^2 \quad I_{zz} = I_{yy} = \frac{1}{3} m L^2 \quad I_{zz'} = 0$$

Geometric Properties of Line and Area Elements

Centroid Location	Centroid Location	Area Moment of Inertia
 <p>Circular arc segment</p>	 <p>Circular sector area</p>	$I_x = \frac{1}{4} r^4 \left(\theta - \frac{1}{2} \sin 2\theta \right)$ $I_y = \frac{1}{4} r^4 \left(\theta + \frac{1}{2} \sin 2\theta \right)$
 <p>Quarter and semicircle arcs</p>	 <p>Quarter circle area</p>	$I_x = \frac{1}{16} \pi r^4$ $I_y = \frac{1}{16} \pi r^4$
 <p>Trapezoidal area</p>	 <p>Semicircular area</p>	$I_x = \frac{1}{8} \pi r^4$ $I_y = \frac{1}{8} \pi r^4$
 <p>Semiparabolic area</p>	 <p>Circular area</p>	$I_x = \frac{1}{4} \pi r^4$ $I_y = \frac{1}{4} \pi r^4$
 <p>Exparabolic area</p>	 <p>Rectangular area</p>	$I_x = \frac{1}{12} b h^3$ $I_y = \frac{1}{12} h b^3$
 <p>Parabolic area</p>	 <p>Triangular area</p>	$I_x = \frac{1}{36} b h^3$